

NASA CR-66837

CASE FILE COPY

UTILIZATION REPORT ON STATISTICAL TRAJECTORY ESTIMATION PROGRAMS

By William E. Wagner and Arno C. Serold

Distribution of this report is provided in the interest of information exchange. Responsibility for the contents resides in the author or organization that prepared it.

Prepared under Contract No. NAS1-8500 by
MARTIN MARIETTA CORPORATION
Denver, Colorado

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

UTILIZATION REPORT ON
STATISTICAL TRAJECTORY ESTIMATION PROGRAMS

By William E. Wagner and Arno C. Serold

Distribution of this report is provided in the interest of information exchange. Responsibility for the contents resides in the author or organization that prepared it.

Prepared under Contract No. NAS1-8500 by
MARTIN MARIETTA CORPORATION
Denver, Colorado

for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

FOREWORD

This report describing the utilization of the Statistical Trajectory Estimation Programs is provided in accordance with Part IV.A.4 of NASA Contract NAS1-8500. An additional report, provided in accordance with this same contract, is presented in NASA CR-1482 to describe the formulation of the Statistical Trajectory Estimation Program.

This work was conducted under the direction of Robert J. Mayhue, Technical Monitor; Sherwood Hoffman, Alternate Monitor (both of the Applied Materials and Physics Division); and George B. Boyles, Computer Analyst, Analysis and Computation Division, Langley Research Center, National Aeronautics and Space Administration.

CONTENTS

	Page
FOREWORD	iii
SUMMARY	1
I. INTRODUCTION	1
II. PROGRAM INPUT AND OUTPUT	3
A. Card Input	3
B. Tape Input and Output	27
C. Tab Output	27
III. PROGRAM CHECKOUT AND VALIDATION	53
A. Checkout Trajectory	53
B. Checkout of Nonlinear Equations of Motion	59
C. Checkout of Linear Equations of Motion	59
D. Checkout of Measurement Equations	61
E. Checkout of Input/Output Transformations	61
F. Checkout of Complete STEP	61
IV. PROGRAM STRUCTURE AND LOGIC	64
A. Overall Program Logic	64
B. Subroutine Logic	67
V. DEFINITION OF FORTRAN SYMBOLS	79
VI. FLOW DIAGRAMS	97
VII. SOURCE LISTINGS	137
A. STEP1 Listing	137
B. STEP2 Listing	216
APPENDIX - DATA CONDITIONING	273
A. Determination of Anomalies	274
B. Data Replacement	276
C. Smoothing	277
REFERENCES	280
 <u>Figure</u>	
1 Schematic of STEP Inputs and Outputs	4
2 Aerodynamic Coefficients of Checkout Vehicle	55
3 Checkout Trajectory	58
4 Overall Program Logic	65
A1 Measurement Time History	273
A2 Replacement by Interpolation	277
 <u>Table</u>	
1 Variable Identification Numbers and Input/Output Units	21
2 Three Iteration Problems, STEP2	63

UTILIZATION REPORT ON
STATISTICAL TRAJECTORY ESTIMATION PROGRAMS

By William E. Wagner and Arno C. Serold
Martin Marietta Corporation

SUMMARY

This volume documents the computer program logic, subroutine arrangement, input and output formats, and other information concerning the Statistical Trajectory Estimation Programs (STEP) of interest to the user and programmer. These programs were originally developed and used on the U.S. Air Force Precision Recovery Including Maneuvering Entry (PRIME) program to perform the post-flight trajectory reconstruction and analysis of the SV-5D maneuverable lifting reentry vehicle. Subsequently, the programs have been considerably improved under NASA Contract NAS1-8500.

STEP uses the recursive Kalman minimum variance filtering algorithms to fit the equations of motion to trajectory measurement data. The programs are formulated to process position radar tracking and airborne gyro and accelerometer measurements. The equations of motion account for three dimensional trajectories in the vicinity of an oblate rotating planet. Vehicle maneuvers in pitch, roll, and yaw within the atmosphere are acceptable. STEP1 is restricted to nonthrusting vehicles; STEP2 is applicable to any vehicle recording accelerations and inertial angular rates and having at least partial radar coverage.

In addition to postflight reconstruction, the programs are useful for solving preflight trajectory simulation and error analysis problems.

I. INTRODUCTION

The Statistical Trajectory Estimation Programs (STEP1 and STEP2) were originally developed, validated, and successfully used to reconstruct the trajectories of the SV-5D maneuverable lifting reentry vehicles on the U.S. Air Force PRIME program. The original formulation is presented in reference 1.

Subsequently, under NASA Contract NAS1-8500 with Langley Research Center, the original formulation for STEP was modified, and the programs were rebuilt. The modifications consist of changing the translational equations of motion to inertial axes and using quaternions to describe the vehicle attitude. Several additional options to improve utility were also included. The improved formulation is presented in Volume I of this report.

From their first conception, the following six rules have served as guidelines for the development of STEP:

- 1) Keep all user/program interfaces simple and logical;
- 2) Use FORTRAN IV or FORTRAN 2.0 coding throughout to facilitate modifications and conversion to various computers;
- 3) Keep STEP1 and STEP2 as identical as possible;
- 4) Minimize logic that limits program applications to specific vehicles;
- 5) Use an executive program structure wherein the main program controls logic flow to and from numerous subordinate subroutines;
- 6) Be continually concerned with minimizing program execution time and computer core requirements.

As a consequence of these guidelines, the original programs were operated on the IBM 7094/2, GE-635, IBM-360/65, and CDC-6400 computers. The majority of subroutines in the two programs are identical, program input and output are nearly alike, and both programs can interface with the same data tapes.

In the following sections; information pertinent to the user and programmer are presented. This includes descriptions of the input and output, checkout procedures, program logic, FORTRAN symbols, flow diagrams, and listings. Reference will be made frequently to the variables, equations, modes of operation, and computational procedures described in Volume I of this report. It is recommended that the reader be familiar with this material before proceeding into this volume--the Utilization Report.

II. PROGRAM INPUT AND OUTPUT

In Volume I of this report, the mathematical techniques and procedures used in STEP are described. Briefly, the concept consists of fitting the equations of motion to trajectory data in a minimum variance sense. The equations of motion in STEP1 require the inertial angular rate data, P_M , Q_M , and R_M ; and, in STEP2 the inertial angular rate data and accelerometer data, a_{XM} , a_{YM} , and a_{ZM} . These data are satisfied exactly by the equations of motion, so obviously they must be excluded from the data to which the equations of motion are fit. As a result of the two different ways in which data are used, STEP interfaces with two magnetic tapes. The first tape, the PQR tape, contains the inertial angular rate and accelerometer data required by the equations of motion in STEP2. The second tape, the FIT tape, contains the radar tracking and accelerometer data as well as any additional data to which the equations of motion in STEP1 are to be fit. Note that the PQR tape can be used in STEP1, and the FIT tape in STEP2 if the accelerations are neglected.

STEP also requires a priori estimates, covariances, and correlations of the state variables and model parameters; program controls and numerical integration information; geophysical and gravitational constants; vehicle physical and aerodynamic data; atmospheric data; etc. These data are input by cards. Figure 1 is a schematic of the input and output information for STEP1 and STEP2. The figure shows the data required by the equations of motion entering from the left, the data to which the equations of motion are fit in a minimum variance sense entering from the top, and the output exiting toward the right. Also shown are those data obtained from cards and those from tape. In the following subsections, these inputs and outputs are described.

A. Card Input

The program card inputs have been divided into 20 logical categories. The quantities input in each of these categories are discussed below. The categories should be input in numerical order. They contain data consisting of both fixed and floating point numbers. The fixed point numbers, designated by an asterisk in the following description, must be rightmost justified within the column field specified. Floating point numbers must be rightmost justified only if the E-mode is used, e.g., .2574532E+3.

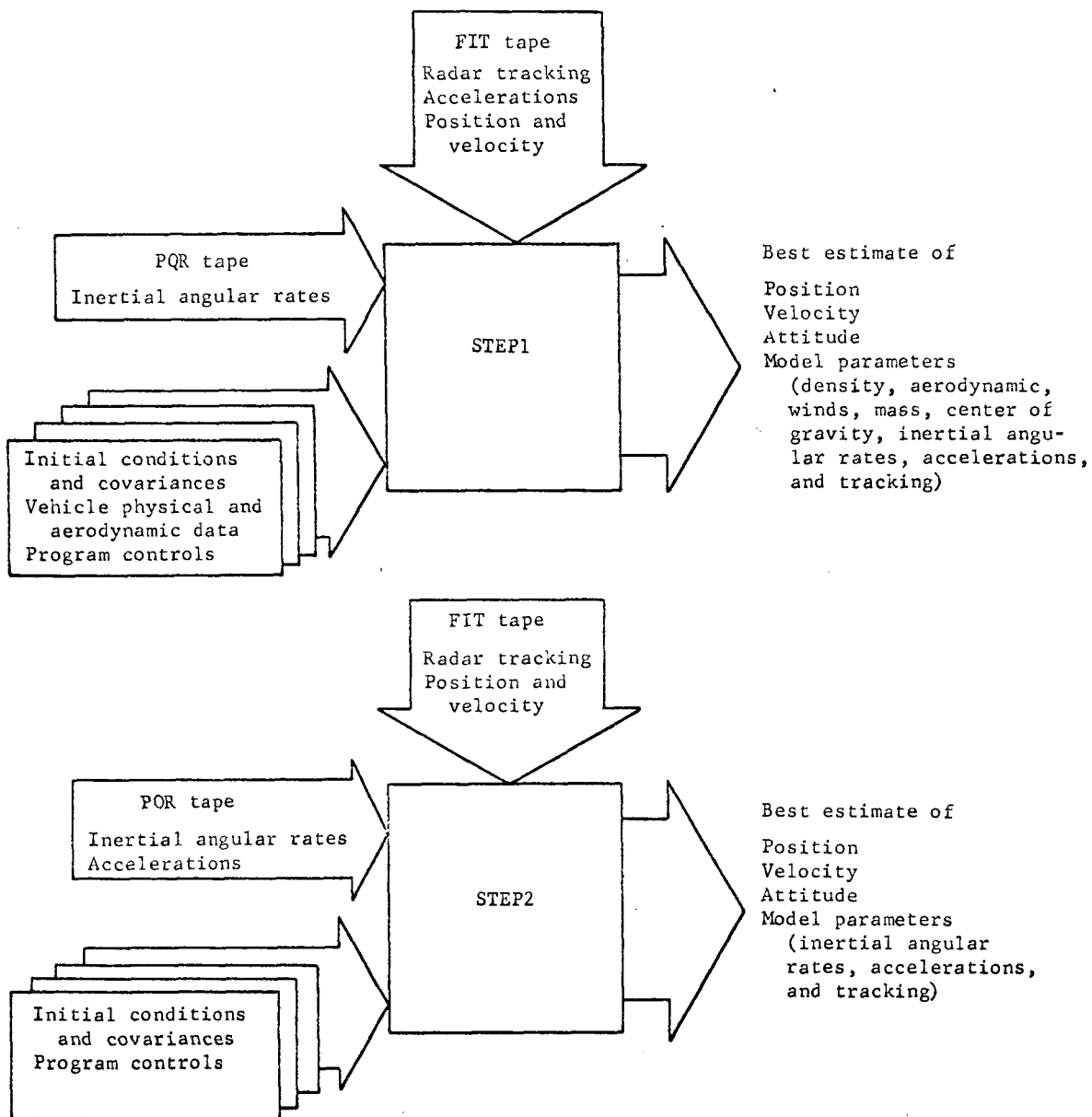


Figure 1.- Schematic of STEP Inputs and Outputs

When floating point numbers are input in the F-mode, e.g., 257.4532, they can lie anywhere within the column field specified. Linear interpolation and extrapolation are used on all tabular input data. Therefore, at least two points must be specified for each table. Curves to be maintained constant at zero need not be input.

1. Input categories.- Those input categories common only to STEP1 will be noted in the description that follows.

Category 1 comment card (STEP1 and STEP2):

<u>Variables</u>	<u>Columns</u>	<u>Description</u>
1* [¶]	2	Identifies category 1 input
"comment"	3-72	Comment containing alphabetic and numerical characters to describe the problem, date, etc.

As many comment cards as desired may be input, each however, requiring a 1 in column 2 (a 0 or blank will also work). The comment cards will be printed on the tab printout.

Category 2 program controls (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
2*	2	Identifies category 2 input
NPC(1)*	6	= 0 filtering, = 1 deterministic, = 2 error analysis
NPC(2)*	10	= 0 metric units, = 1 English units
NPC(3)*	14	= 0, 1, or 2 for input/output in internal variables or types 1 or 2 variables, respectively
NPC(4)*	18	= 0 updated reference, = 1 nonupdated reference
NPC(5)*	22	= 0 print fitting data schedule, = 1 do not print
NPC(6)*	26	= 0 do not print covariance and correlation matrices, = 1 print covariance and correlation matrices during smoothing on last iteration = 2 print covariance and correlation matrices during filtering and smoothing on last iteration
NPC(7)*	30	Number of iterations
NPC(8)*	34	= 0 smooth state only, no residual or loss function calculations = 1 smooth state only, calculate residuals and loss function = 2 smooth state and covariances, no residuals or loss function calculations = 3 smooth state and covariances, calculate residuals and loss function = 4 do not smooth
NPC(9)*	38	= 0 vector process, = 1 scalar process
NPC(10)*	42	= 0 do not write STATE tape during smoothing, = 1 write tape

[¶]A variable followed by an asterisk indicates a fixed point integer which must be rightmost justified.

These program controls pertain to entire program operation. For more complete descriptions, see Subsection A.2. Program controls common to a specific input category are input with that category.

Category 3 state variables and model parameters (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
3*	2	Identifies category 3 input
IPC ₁ *	4	Variable in X=1, W=2, U=3, V=4, Const=5
IDN*	5-8	Variable identification number, see Subsection A.4, page 21
VALUE	9-20	Mean values of state variable or model parameter, see Subsection A.4 for units
SIG	21-32	Standard deviation of state or model parameter if IPC ₁ = 1-4, see Subsection A.4 for units

One category 3 card is required for each state variable and model parameter desired in the problem. Should no card be input for a specific model parameter, it assumes a preset value of 1 or 0 to bypass the error model. For example, in the accelerometer error model, equation (159), $C_{61} = C_{65} = C_{69} = 1$ all other C_s are zero. For uncertain variables, the standard deviations are squared and constitute the variance of the diagonal covariance matrix. Should off-diagonal elements be required, they can be input in category 10. The maximum number of components in X is 10; in W is 20, in U is 5; in V is 5.

Category 4 numerical integration (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
4*	2	Identifies category 4 input
TO	9-20	Initial problem time, sec
DET	21-32	Time interval between block printouts, sec
DCOMP	33-44	Fixed computing interval, sec
TFINAL	45-56	Final problem time, sec

Category 5 geophysical and gravitational (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
5*	2	Identifies category 5 input
1*	4	Identifies remaining variables on card as G0, XMU, and XJ2
G0	9-20	Acceleration of gravity at sea level for use in STEP1 atmosphere equations, m/sec ² , ft/sec ²
XMU	21-32	Coefficient of first gravitational harmonic, m ³ /sec ² , ft ³ /sec ²
XJ2	33-44	Coefficient of second gravitational harmonic
and/or		
5*	2	Identifies category 5 input
2*	4	Identifies remaining variables on card as R _P , R _E , and OMEGA
RPO	9-20	Polar radius of planet, m, ft
REO	21-32	Equatorial radius of planet, m, ft
OMEGA	33-44	Planet rotation rate, rad/sec

Category 5 cards need be input only if a change is desired from the built-in data. The values of the category 5 data that are built-in are from reference 2:

$$G0 = g_0 = 9.80665 \text{ m/sec}^2 = 32.174048 \text{ ft/sec}^2$$

$$XMU = \mu = 3.985992 \times 10^{14} \text{ m}^3/\text{sec}^2 = 1.407639 \times 10^{16} \text{ ft}^3/\text{sec}^2$$

$$XJ2 = J_2 = 1082.645 \times 10^{-6}$$

$$RPO = R_P = 6 \ 356 \ 173 \text{ m} = 20 \ 853 \ 599 \text{ ft}$$

$$REO = R_E = 6 \ 378 \ 163 \text{ m} = 20 \ 925 \ 731 \text{ ft}$$

$$OMEGA = \Omega_P = 7.292116 \times 10^{-5} \text{ rad/sec}$$

Category 6 center-of-gravity/IMU distances (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
6*	2	Identifies category 6 input
IPC ₂ *	4	Identifies table to follow = 1 $x_p(t)$, = 2 $y_p(t)$, = 3 $z_p(t)$
NPTS*	5-8	Number of points on table
[Read in $x_p(t)$, $y_p(t)$, or $z_p(t)$ (m, ft), depending on IPC ₂ , using table input format 1 in Subsection A.3; NPTS must be no larger than 20]		

A separate category 6 card precedes each of the tables. Zero tables are omitted.

Category 7 fitting data controls (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
7*	2	Identifies category 7 input
MTYP*	4	Identifies type of data = 1, 2, 3, 4, 5 tracking stations = 6 airborne radar, = 7 position, = 8 velocity, = 9 accelerometer
TI	5-14	Initial time to process MTYP data, sec
TF	15-24	Final time to process MTYP data, sec
DT	25-34	Minimum time span between MTYP data points, sec
MR(1,MTYP)*	35-36	= 0 do not process component 1, = 1 process component 1
MR(2,MTYP)*	37-38	= 0 do not process component 2, = 1 process component 2
MR(3,MTYP)*	39-40	= 0 do not process component 3, = 1 process component 3
SIG(1,MTYP)	41-50	Incremental standard deviation on component 1, m, ft, rad
SIG(2,MTYP)	51-60	Incremental standard deviation on component 2, m, ft, rad
SIG(3,MTYP)	61-70	Incremental standard deviation on component 3, m, ft, rad

Input one category 7 card for each type (MTYP) of data to be processed. Category 7 cards are used to control the frequency and time span of data on the FIT tape. Specified components of the data triples can be edited out (even though on the FIT tape) by specifying its corresponding MR input equal to 0. The incremental standard deviations are added to the standard deviations on the FIT tape to yield the total standard deviations used in the filtering equations. All angular standard deviations (e.g., A_M and E_M) are in radians.

In error analysis problems, the category 7 cards provide all the fitting data information necessary, i.e., time span, frequency, and standard deviation. Therefore, no FIT tape is used.

Category 8 FIT tape (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
8*	2	Identifies category 8 input
IPC ₃ *	4	= 0 no print of FIT tape, = 1 print FIT tape
IPC ₄ *	8	= 1 input FIT data from cards, = 0 do not enter FIT data from cards
(If IPC ₄ = 1, read in FIT data from cards using table input format 2 in Subsection A.3)		

The category 8 cards permit printing of the FIT tape and/or input of the FIT data from cards. When card input is used, a tape is written from the card inputs and later used in problem execution. If a prepared FIT tape is to be used and no printout of the tape is desired, omit category 8 input.

Category 9 POR tape (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
9*	2	Identifies category 9 input
IPC ₅ *	4	= 0 no print of PQR tape, = 1 print PQR tape
IPC ₆ *	8	= 1 input PQR data from cards, = 0 do not enter PQR data from cards
(If IPC ₆ = 1, read PQR data from cards using table format 3 in Subsection A.3)		

The category 9 cards permit printing of the PQR tape and/or input of the PQR data from cards. When card input is used, a tape is written from the card inputs and later used in problem execution. If a prepared PQR tape is desired, omit category 9 input.

Category 10 covariance and correlation matrices (STEP1 and STEP2):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
10*	1-2	Identifies category 10 input
IPC ₇ *	4	Identifies matrix or matrix elements to follow = 1 P, =2 CUZ, =3 CVZ = 4 P(i,j), = 5 CUZ(i,j) = 6 CVZ(i,j)
NPTS*	8	Number of single point cards to follow if IPC ₇ > 3

[Read in P, CUZ, or CVZ (m, ft, rad) if IPC, = 1, 2, or 3, respectively, by means of table format 4 in Subsection A.3]

or input NPTS cards each containing a single point formatted as follows

i*	5-8	} if IPC ₇ = 4
j*	9-12	
P(i,j)	13-24	

or

i*	5-8	} if IPC ₇ = 5
j*	9-12	
CUZ(i,j)	13-24	

or

i*	5-8	} if IPC ₇ = 6
j*	9-12	
CVZ(i,j)	13-24	

The category 10 data must be input after all category 3 cards have been input. This is necessary to allow the program to determine the number of components in the expanded state vector Z, model parameters U, and measurement parameters V. The size of P, CUZ, and CVZ require that these vector sizes be known. Care should be exercised in assuring that the matrices input in category 10 are compatible both in size and the order of variables input in category 3. The category 10 input can be omitted if the diagonal matrix P input in category 3 and null correlation matrices CUZ and CVZ are acceptable.

Category 11 aerodynamic coefficients (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
11*	1-2	Identifies category 11 input
IPC ₈ *	4	Aerodynamic input option indicator = -1 C_D, C_Y, C_L ; = 0 C_A, C_Y, C_N ; = 1 C_A, C_Y, C_N $\eta \quad \eta$
SREF	9-21	Reference area for aerodynamic coefficients
XLREF	22-33	Reference length in Reynolds number

(Input all three tables of aerodynamic coefficients by means of table input format 5 in Subsection A.3)

Category 12 mass (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
12*	1-2	Identifies category 12 input
NPTS*	8	Number of points on table, the mass table to follow
TONE	9-20	Time t_1 to commence mass error model correction
TTWO	21-32	Time t_2 at which mass error model correction is stopped

[Read in $m(t)$ (kg, slugs) by means of table input format 1 in Subsection A.3]

Category 13 atmospheric winds (STEP1 only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
13*	1-2	Identifies category 13 input
IPC ₁₀ *	4	Identifies wind profile to follow = 0 $u_{WM}(h_o)$, = 1 $v_{WM}(h_o)$
NPTS*	8	Number of points on table

[Read in $u_{WM}(h)$ or $v_{WM}(h)$ (mps or fps), depending on IPC₁₀, by means of table input format 1 of Subsection A.3]

Category 14 atmosphere (STEPl only):

<u>Variable</u>	<u>Column</u>	<u>Description</u>
14	1-2	Identifies category 14 input
IPC ₁₁ *	4	Identifies atmosphere option = 0 1962 U.S. standard, = 1 1959 ARDC, = 2 arbitrary atmosphere to be input as function of geopotential alti- tude, = 3 arbitrary atmosphere to be input as function of geometric altitude
If $IPC_{11} \geq 2$ input the following		
NPTS*	3-4	Number of base points on attitude profile to be input
APO	5-15	Sea level pressure, nt/m ² or lb _f /ft ²
AMO	16-26	Mean molecular weight of atmos- phere constituents
AR	27-37	Gas constant, J/(°K) (kg-mol) or ft/lb _f (°R) (slug-mol)
AGAM	38-48	Specific heat ratio of atmos- phere constituents
ABET	49-59	} Sutherlands constants β and S used to calculate atmosphere viscosity, see units on data below
AS	60-70	
[Input HB(i) (m, ft) and TMB(i) (°K, °R), i=1, NPTS by means of table input format 6 in Subsection A.3]		

The data entered in category 14 input (if $IPC_{11} \geq 2$) must be dimensionally compatible with that specified in other categories. The values of AMO, APO, AR, AGAM, ABET, and AS built-in the program for use in the 1959 ARDC and 1962 U.S. Standard atmospheres are the following:

$$APO = 1.013250 \times 10^5 \text{ nt/m}^2 = 2116.2166 \text{ lb}_f/\text{ft}^2$$

$$AMO = 28.9644$$

$$AR = 8.31432 \times 10^3 \text{ J/}^\circ\text{K} \text{ (kg-mol)} = 49.7192 \times 10^3 \text{ ft-lb}_f/\text{}^\circ\text{R} \text{ (slug-mol)}$$

$$AGAM = 1.40$$

$$ABET = 1.458 \times 10^{-6} \text{ kg/sec m } (^\circ\text{K})^{\frac{1}{2}} = 2.269 \times 10^{-8} \text{ slugs/ft-sec } (^\circ\text{R})^{\frac{1}{2}}$$

$$AS = 110.4 \text{ }^\circ\text{K} = 198.72 \text{ }^\circ\text{R}$$

Category 20 end card:

<u>Variable</u>	<u>Column</u>	<u>Description</u>
20*	1-2	Identifies category 20 card

The category 20 card must always be input last.

2. Program control definitions.- Definitions of the program controls used in the previous section follow:

- NPC(1) = 0 Filtering mode of operation;
1 Deterministic mode of operation;
2 Error analysis mode of operation.
- NPC(2) = 0 Input and output in metric units (kg, m, sec);
1 Input and output in English units (slug, ft, sec).
- NPC(3) Input and output the following state variables, their standard deviations, covariance and correlation matrices;
= 0 $u, v, w, h_o, \varphi_D, \theta, e_o, e_1, e_2, e_3$;
1 $V_A, \gamma_A, \lambda_A, h_o, \varphi_D, \theta, \bar{\psi}, \bar{\theta}, \bar{\varphi}$;
2 $V_A, \gamma_A, \lambda_A, h_o, \varphi_D, \theta, \sigma, \beta, \alpha$.
- NPC(4) = 0 Update reference after each measurement processed;
1 Do not update reference until final time is met.
- NPC(5) = 0 Print schedule of processed fitting data;
1 Do not print schedule of processed fitting data.

- NPC(6) = 0 Do not print covariance and correlation matrices;
- 1 Print covariance and correlation matrices P, CUZ, and CVZ after each block printout during smoothing on last iteration;
 - 2 Print covariance and correlation matrices P, CUZ, and CVZ after each block printout during filtering and smoothing on last iteration.
- NPC(7) = Number of filtering and smoothing iterations.
- NPC(8) = 0 Smooth state only, no residuals nor loss function;
- 1 Smooth state only, calculate residuals and loss function;
 - 2 Smooth state, covariance, and correlation matrices, no residuals nor loss function calculations;
 - 3 Smooth state, covariance, and correlation matrices, calculate residuals, and loss function;
 - 4 Do not smooth.
- [Before the last iteration, only the state is smoothed if NPC(8) = 2 or 3]
- NPC(9) = 0 Process data as vectors where possible;
- 1 Process data as scalars at all times.
- NPC(10) = 0 Do not write STATE tape;
- 1 Write STATE tape on backward smoothing of last iteration.
- IPC₁ = 1 Variable is a component of the state vector, X;
- 2 Variable is a model parameter to be estimated in the expanded state vector, Z;
 - 3 Variable is an uncertain model parameter not to be estimated, U;
 - 4 Variable is an uncertain measurement parameter not to be estimated, V;
 - 5 Variable is a model parameter known with absolute certainty, C.
- IPC₂ = 1 Indicates the $x_p(t)$ table will follow category 6 card;
- 2 Indicates the $y_p(t)$ table will follow category 6 card;

- 3 Indicates the $z_p(t)$ table will follow category 6 card.
- IPC₃(IPC₅) = 0 Do not print out the data on the FIT (PQR) tape;
- 1 Print out the data on the FIT (PQR) tape in tabular form before commencing the problem execution.
- IPC₄(IPC₆) = 0 Write the FIT (PQR) tape from input cards;
- 1 The FIT (PQR) tape has already been prepared and need not be written from cards.
- IPC₇ = 1 The covariance matrix P follows the category 10 card;
- 2 The covariance matrix CUZ follows the category 10 card;
- 3 The covariance matrix CVZ follows the category 10 card;
- 4 Single points P(i,j) follows the category 10 card;
- 5 Single points CUZ(i,j) follows the category 10 card;
- 6 Single points CVZ(i,j) follows the category 10 card.
- IPC₈ = -1 Aerodynamic coefficient inputs are $C_D(\alpha, \beta, M)$, $C_Y(\alpha, \beta, M)$ and $C_L(\alpha, \beta, M)$;
- 0 Aerodynamic coefficient inputs are $C_A(\alpha, \beta, M)$, $C_Y(\alpha, \beta, M)$ and $C_N(\alpha, \beta, M)$;
- 1 Aerodynamic coefficient inputs are $C_A(\xi, \eta, M)$, $C_{Y_\eta}(\xi, \eta, M)$ and $C_{N_\eta}(\xi, \eta, M)$.
- IPC₁₀ = 0 Indicates the $u_W(h_o)$ table follows category 13 card;
- 1 Indicates the $v_W(h_o)$ table follows category 13 card.
- IPC₁₁ = 0 Use a 1962 U.S. Standard atmosphere;
- 1 Use a 1959 ARDC atmosphere;
- 2 Input an arbitrary atmosphere as a function of geopotential altitude;
- 3 Input an arbitrary atmosphere as a function of geometric altitude.

- MTYP = 1 Tracking station 1 with components 1, 2, and 3 being R, A, and E, respectively;
- 2 Tracking station 2 with components 1, 2, and 3 being R, A, and E, respectively;
- 3 Tracking station 3 with components 1, 2, and 3 being R, A, and E, respectively;
- 4 Tracking station 4 with components 1, 2, and 3 being R, A, and E, respectively;
- 5 Tracking station 5 with components 1, 2, and 3 being R, A, and E, respectively;
- 6 Airborne radar with component 1 being R_R (components 2 and 3 are currently unused);
- 7 Velocity of vehicle with components 1, 2, and 3 being u, v, and w, respectively;
- 8 Position of vehicle with components 1, 2, and 3 being h, ϕ , and θ , respectively;
- 9 Accelerometer with components 1, 2, and 3 being a_{XM} , a_{YM} , and a_{ZM} , respectively.

3. Table input formats.- The formats described below are used to input tables in STEP.

a. Format 1: For a table, $X(t_i)$, having NPTS discrete values of the independent variable, t_i , and the dependent variable, $X(t_i)$, the following format is used.

Col Card	1-12	13-24	25-36	37-48	49-60	61-72
1	t_1	$X(t_1)$	t_2	$X(t_2)$	t_3	$X(t_3)$
2	t_4	$X(t_4)$
.
.
.	t_{NPTS-1}	$X(t_{NPTS-1})$	t_{NPTS}	$X(t_{NPTS})$.	.

The number of points on the table NPTS is entered on the category card preceding the table.

b. Format 2: This format corresponds to the data on the FIT tape. The data can be input on cards in category 8 using the following format.

Col Card	1-2	3-4	5-14	15-24	25-34	35-44	45-54	55-64	65-74
1	K*								
2	MTP(1)* TYM(1) DAT(1,1) DAT(2,1) DAT(3,1) SIG(1,1) SIG(2,1) SIG(3,1)								
3	MTP(2)* TYM(2) DAT(1,2) DAT(2,2) DAT(3,2) SIG(1,2) SIG(2,2) SIG(3,2)								
.									
.									
.									
K+1	MTP(K)* TYM(K) DAT(1,K) DAT(2,K) DAT(3,K) SIG(1,K) SIG(2,K) SIG(3,K)								
(The last record of input must contain zeros)									

Each record of the FIT tape corresponds to the K points described above. The number of points per record, K, must never exceed 20. As many records (with $K \leq 20$) as desired may be input. The last record must always consist of a single card having $K = 0$.

c. Format 3: This format corresponds to the data on the PQR tape. The data can be input on cards in category 9 using the following format.

Col Card	1-2	3-12	13-22	23-32	33-42	43-52	53-62	63-72
1	K*							
2		TT(1)	TP(1)	TQ(1)	TR(1)	AX(1)	AY(1)	AZ(1)
.	
.	
.	
K+1		TT(K)	TP(K)	TQ(K)	TR(K)	AX(K)	AY(K)	AZ(K)
(The last record of input must contain zeros)								

Each record on the PQR tape corresponds to the K points described above. The number of points per record, K , must never exceed 20. As many records (with $K \leq 20$) as desired may be input. The last record must always consist of a single card having $K = 0$.

d. Format 4: This format corresponds to the covariance and correlation matrices input in category 10. These matrices are input by rows using the following format.

Card \ Col	1-12	13-24	25-36	37-48	49-60	61-72
1	P(1,1)	P(1,2)	P(1,3)	P(1,4)	P(1,5)	P(1,6)
.	P(1,7)	.	.	P(1,m)	P(2,1)	P(2,2)
.	.	.	.			
.	.	.	.			
.	.	.	P(m,m)			
1	CUZ(1,1)	CUX(1,2)	CUZ(1,3)	...	CUZ(1,q)	CUZ(2,1)
.	.	.	.			
.	.	.	.			
.	.	.	.			
.	.	.	CUZ(m,q)			
1	CVZ(1,1)	CVZ(1,2)	CVZ(1,3)	...	CVZ(1,r)	CVZ(2,1)
.	.	.	.			
.	.	.	.			
.	.	.	.			
.	.	.	.			
.	.	.	CVZ(m,r)			

The number of components of the expanded state vector, m , uncertain model parameters, q , and measurement parameters, r , are determined by counting the category 3 cards as they are input.

e. Format 5: This format is used to input the tables of aerodynamic coefficients in category 11. Each table commences with the following control card

Col Card	1-4	5-8	9-12	13-16	17-20
1	NT*	NV*	N ₁ *	N ₂ *	N ₃ *

where

NT = Table identification number = 1 for C_D or C_A ,
 = 2 for C_Y or C_{Y_η} ,
 = 3 for C_L , C_N or C_{N_η} ;

NV = Number of independent variables for the table,
 $0 \leq NV \leq 3$;

N₁ = Number of points in the first independent variable,
 α or η ;

N₂ = Number of points in the second independent variables,
 β or ξ ;

N₃ = Number of point in the third independent variable,
 M.

The tabular entries follow. The first three cards list the N₁, α , or η values, the N₂, β , or ξ values and the N₃ M values. This is followed by the aerodynamic coefficients, specified by NT, which will be denoted by C below.

Col Card	1-6	7-12	13-18	23-24	25-30	31-36	37-42	43-48	49-54	55-60	61-66	67-72
1	α_1	α_2	α_3	α_4	α_5	.	.	.	α_{N1}			
2	β_1	β_2	.	.	.	β_{N2}						
3	M_1	M_2	M_3	M_4	.	.	.	M_{N3}				
4	$C(\alpha_1 \beta_1 M_1)$	$C(\alpha_2 \beta_1 M_1)$	$C(\alpha_3 \beta_1 M_1)$.	.	.	$C(\alpha_{N1} \beta_1 M_1)$	$C(\alpha_1 \beta_2 M_1)$	$C(\alpha_2 \beta_2 M_1)$.	.	.
.	.	.	$C(\alpha_{N1} \beta_2 M_1)$	$C(\alpha_1 \beta_1 M_2)$
.
.	$C(\alpha_{N1} \beta_{N2} M_{N3})$					

For $NT = 3$, replace α and β by η and ξ in the above table. The trivariate table is size limited to $N_1 \times N_2 \times N_3 \leq 512$, which amounts to eight values of α , eight values of β , and eight values of M . By specifying N_1 and/or N_2 and/or N_3 equal to zero, the trivariate table can be collapsed to a bivariate or monovariate table or a point. For bivariate or monovariate tables, the size limitation is still 512. However $N_i \times N_j \leq 512$ for monovariate tables allowing more points per curve to be specified.

f. Format 6: This format is used to input the base geopotential or geometric altitudes and molecular scale temperatures in category 14.

Col Card	1-12	13-24	25-36	37-48	49-60	61-72
1	HB(1)	HB(2)	HB(3)	HB(4)	HB(5)	HB(6)
2	HB(7)	.	.	.	HB(NPTS)	
.	TMB(1)	TMB(2)	TMB(3)	TMB(4)	TMB(5)	TMB(6)
.	TMB(7)	.	.	.	TMB(NPTS)	

The number of points in each table, NPTS, is input on the category 14 card. In the above table, HB(i) are the base geopotential attitudes and TMB(i) the base molecular scale temperature. The maximum number of points in these tables is $NPTS \leq 23$.

4. Variable identification numbers and input/output units.-
Variable identification numbers and input/output units are given in table 1.

TABLE 1.- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a	
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation
State								
1	u	$\left. \begin{array}{l} \left. \begin{array}{l} V_A \\ \gamma_A \\ \lambda_A \\ h_o \\ \phi_D \\ \theta \\ e_o \\ e_1 \\ e_2 \\ e_3 \end{array} \right\} \begin{array}{l} \text{for NPC(3) = 0} \\ \text{for NPC(3) = 1} \\ \text{for NPC(3) = 2} \end{array} \right\} \begin{array}{l} V_A \\ \gamma_A \\ \lambda_A \\ h_o \\ \phi_D \\ \theta \\ e_o \\ e_1 \\ e_2 \\ e_3 \end{array} \end{array} \right\}$	X	X	mps	mps	mps	mps
2	v		X	X	mps(deg)	mps(rad)	mps(deg)	mps(rad)
3	w		X	X	mps(deg)	mps(rad)	mps(deg)	mps(rad)
4	h_o		X	X	m	m	m	m
5	ϕ_D		X	X	deg (geod) ^b	rad (geoc) ^b	deg (geod) ^b	rad (geoc) ^b
6	θ		X	X	deg	rad	deg	rad
7	e_o		X	X	- (deg)	- (rad)	- (deg)	- (rad)
8	e_1		X	X	- (deg)	- (rad)	- (deg)	- (rad)
9	e_2		X	X	- (deg)	- (rad)	- (deg)	- (rad)
10	e_3		X	X	----	----	----	----
Model parameters								
1	C_1 Aerodynamic	(147)	Z,U,C	<div>↑ Not included ↓</div>	----	----	----	----
2	C_2 Error coefficients		Z,U,C		----	----	----	----
3	C_3		Z,U,C		----	----	----	----
4	C_4		Z,U,C		rad ⁻²	rad ⁻²	rad ⁻²	rad ⁻²
5	C_5		Z,U,C		rad ⁻¹	rad ⁻¹	rad ⁻¹	rad ⁻¹
6	C_6		Z,U,C		rad ⁻¹	rad ⁻¹	rad ⁻¹	rad ⁻¹
7	C_7		Z,U,C		----	----	----	----
8	C_8		Z,U,C		----	----	----	----
9	C_9		Z,U,C		----	----	----	----
10	C_{10}		Z,U,C		----	----	----	----
11	C_{11}		Z,U,C		----	----	----	----
12	C_{12}		Z,U,C		----	----	----	----
13	C_{13} Unused							
14	C_{14}							
15	C_{15}							
16	C_{16} Mass error	(149)	Z,U,C		kg	kg	kg	kg
17	C_{17} Coefficients		Z,U,C		kg/sec	kg/sec	kg/sec	kg/sec
18	C_{18}		Z,U,C		kg/sec ²	kg/sec ²	kg/sec ²	kg/sec ²
19	C_{19} Unused							
20	C_{20} Unused							
21	C_{21} Density error	(151)	Z,U,C		----	----	----	----
22	C_{22} Coefficients		Z,U,C		kg/m ³	kg/m ³	kg/m ³	kg/m ³
23	C_{23}		Z,U,C		1/m	1/m	1/m	1/m
24	C_{24} Unused							
25	C_{25} Unused							
26	C_{26} Atmosphere winds	(152)	Z,U,C		m/sec	m/sec	m/sec	m/sec
27	C_{27} Error coefficient		Z,U,C		m/sec	m/sec	m/sec	m/sec
28	C_{28} Unused							
29	C_{29} Unused							
30	C_{30} Unused							
31	C_{31} Center of gravity	(153)	Z,V,C	Z,U,C	m	m	m	m

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.^bgeod refers to geodetic latitude, geoc refers to geocentric latitude.

TABLE 1- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS - Continued

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a		
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation	
Model parameters									
32	C ₃₂ Error coefficients	↓	Z,V,C	Z,U,C	m	m	m	m	
33	C ₃₃		Z,V,C	Z,U,C	m	m	m	m	
34	C ₃₄ Unused								
35	C ₃₅ Unused								
36	C ₃₆ Inertial	(154)	Z,U,C	Z,U,C	----	----	----	----	
37	C ₃₇ Angular rate	↓	Z,U,C	Z,U,C	----	----	----	----	
38	C ₃₈ Error coefficients		Z,U,C	Z,U,C	----	----	----	----	
39	C ₃₉		Z,U,C	Z,U,C	----	----	----	----	
40	C ₄₀		Z,U,C	Z,U,C	----	----	----	----	
41	C ₄₁		Z,U,C	Z,U,C	----	----	----	----	
42	C ₄₂		Z,U,C	Z,U,C	----	----	----	----	
43	C ₄₃		Z,U,C	Z,U,C	----	----	----	----	
44	C ₄₄		Z,U,C	Z,U,C	----	----	----	----	
45	C ₄₅		Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec	
46	C ₄₆		Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec	
47	C ₄₇		Z,U,C	Z,U,C	rad/sec	rad/sec	rad/sec	rad/sec	
48	C ₄₈		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
49	C ₄₉		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
50	C ₅₀		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
51	C ₅₁		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
52	C ₅₂		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
53	C ₅₃		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
54	C ₅₄		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
55	C ₅₅		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
56	C ₅₆		Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
57	C ₅₇	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m		
58	C ₅₈ Unused	↓	Z,U,C	Z,U,C	rad sec/m	rad sec/m	rad sec/m	rad sec/m	
59	C ₅₉ Unused								
60	C ₆₀ Unused								
61	C ₆₁ Acceleration		(159)	Z,V,C	Z,U,C	----	----	----	----
62	C ₆₂ Error coefficients		Z,V,C	Z,U,C	----	----	----	----	
63	C ₆₃		Z,V,C	Z,U,C	----	----	----	----	
64	C ₆₄		Z,V,C	Z,U,C	----	----	----	----	
65	C ₆₅		Z,V,C	Z,U,C	----	----	----	----	
66	C ₆₆		Z,V,C	Z,U,C	----	----	----	----	
67	C ₆₇		Z,V,C	Z,U,C	----	----	----	----	
68	C ₆₈	Z,V,C	Z,U,C	----	----	----	----		
69	C ₆₉	Z,V,C	Z,U,C	----	----	----	----		
70	C ₇₀	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²		
71	C ₇₁	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²		
72	C ₇₂	Z,V,C	Z,U,C	m/sec ²	m/sec ²	m/sec ²	m/sec ²		

Only metric SI units are presented. For English units replace m by ft and kg by slugs.

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.

TABLE 1.- VARIABLE IDENTIFICATION NUMBERS AND INPUT UNITS - Concluded

IDN	Variable	Reference equation from vol. I	Vector component		Input units ^a		Output units ^a	
			STEP1	STEP2	Variable	Standard deviation	Variable	Standard deviation
Model parameters								
73	C ₇₃ Unused							
74	C ₇₄ Unused							
75	C ₇₅ Unused							
76	C ₇₆ Tracking	(239)	Z,V,C	Z,V,C	----	----	----	----
77	C ₇₇ Station 1	and	Z,V,C	Z,V,C	----	----	----	----
78	C ₇₈ Error coefficients	table 11	Z,V,C	Z,V,C	---	---	---	---
79	C ₇₉		Z,V,C	Z,V,C	m	m	m	m
80	C ₈₀		Z,V,C	Z,V,C	rad	rad	rad	rad
81	C ₈₁		Z,V,C	Z,V,C	rad	rad	rad	rad
82	C ₈₂		Z,V,C	Z,V,C	sec	sec	sec	sec
83	C ₈₃		Z,V,C	Z,V,C	sec	sec	sec	sec
84	C ₈₄		Z,V,C	Z,V,C	sec	sec	sec	sec
85	C ₈₅		Z,V,C	Z,V,C	ft	ft	ft	ft
86	C ₈₆		Z,V,C	Z,V,C	rad	rad	rad	rad
87	C ₈₇ Unused							
88	C ₈₈ Latitude of station 1		Z,V,C	Z,V,C	deg(geod) ^b	rad(geoc) ^b	rad(geoc) ^b	rad(geoc) ^b
89	C ₈₉ Longitude of station 1		Z,V,C	Z,V,C	deg	rad	rad	rad
90	C ₉₀ Altitude of station 1		Z,V,C	Z,V,C	m	m	m	m
91	C ₉₁ Error coefficients	table 11	Z,V,C	Z,V,C				
.	. for tracking sta-		.	.				
.	. tion 2,3,4, & 5		.	.				
.	. See table 11, vol. I to correspond with C ₇₆ - C ₉₀		.	.				
150	C ₁₅₀							
151	δ _P Orientation of airborne radar	(269)	C	C	deg	----	----	----
152	δ _Y	and figure 7	C	C	deg	----	----	----

^aOnly metric SI units are presented. For English units replace m by ft and kg by slugs.

^bgeod refers to geodetic latitude, geoc refers to geocentric latitude.

5. Sample input.- The card inputs for STEP1 and STEP2, which correspond to the sample output in Section II.C.5 follow.

a. STEP1 input:

```

1  STEP1 FILTERING CHECK PROBLEM (FEB. 1969) WAGNER AND SEROLD
2  0 1 2 0 0 2 1 3 0 0 PROGRAM CONTROLS
3 1 1 10001.2000 100. (SIG=100. ,RN=.55)
3 1 2 -6.75080000 .035 (SIG=2 DEG ,RN=-.81)
3 1 3 63.0352000 .018 (SIG=1 DEG ,RN=-.33)
3 1 4 100584.000 1000. (SIG=1000. ,RN=-.96)
3 1 5 16.7583977 .0003 (SIG=.0170DEG,RN=1.69)
3 1 6 28.0418380 .0003 (SIG=.0170DEG,RN=.05)
3 1 7 29.8270000 .0530 (SIG=3 DEG ,RN=1.10)
3 1 8 -4.43200000 .0350 (SIG=2 DEG ,RN=-1.72)
3 1 9 19.3930000 .0530 (SIG=3 DEG ,RN=-1.37)
3 2 46 -.000108 .0002 (SIG=.0002 ,RN=-.54)
3 2 103 16.6055454 .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3 2 104 31.0 .000375 (SIG=.0214 DEG) MOD.PARA. - Z
3 3 45 0. .0001 MOD.PARA. - U
3 3 47 0. .0001 MOD.PARA. - U
3 5 31 -1.0 CONSTANT
3 5 33 0.5 CONSTANT
3 5 88 15.09690377 CONSTANT
3 5 89 27.0 CONSTANT
4 70.0 5.0 0.5 90. NUMERICAL INTEG.
6 1 2 CG/IMU
0.0 1.0 100.0 1.0
6 3 2 CG/IMU
0.0 -0.5 100.0 -0.5
5 1 32.174046 1.407690E16 1092.055E-4 GRAV. DATA
5 2 20855970. 20926430. .7292115E-4 GEOPH.DATA
7 1 70.0 82.0 .99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
7 2 78.0 88.0 1.99 1 1 1 20.0 .00003 .00003 MEAS.CDS.
12 3 -1. 400. MASS(T)
-1. 25.57031 200. 24.8013 400. 24.0262
14 1 ATMOSPHERE
11-1 AERO TABLES
1 3 8 5 8 CD(ALPHA,BETA,M)
0. 4. 8. 12. 16. 20. 24. 28.
-8. -4. 0. 4. 8.
2. 3. 4. 5. 6. 6.5 7. 30.
.2247 .2266 .2404 .2602 .2886 .3261 .3730 .4297 .2220 .2265 .2386 .2589
.2675 .3252 .3724 .4294 .2186 .2252 .2381 .2584 .2871 .3249 .3722 .4293
.2220 .2265 .2386 .2589 .2875 .3252 .3724 .4294 .2247 .2286 .2404 .2602
.2886 .3261 .3730 .4297 .2086 .2121 .2228 .2410 .2672 .3020 .3460 .3997
.2004 .2048 .2170 .2364 .2634 .2989 .3434 .3976 .1915 .2006 .2146 .2347
.2621 .2978 .3425 .3969 .2004 .2048 .2170 .2364 .2634 .2989 .3434 .3976
.2086 .2121 .2228 .2410 .2672 .3020 .3460 .3997 .1660 .1700 .1817 .2006
.2270 .2613 .3043 .3566 .1527 .1585 .1729 .1938 .2214 .2566 .3003 .3531
.1387 .1522 .1692 .1911 .2193 .2549 .2988 .3519 .1527 .1585 .1729 .1938
.2214 .2566 .3003 .3531 .1660 .1700 .1817 .2006 .2270 .2613 .3043 .3566
.1226 .1275 .1410 .1618 .1896 .2250 .2685 .3210 .1058 .1135 .1306 .1537
.1830 .2194 .2637 .3169 .0886 .1061 .1263 .1507 .1807 .2174 .2621 .3154
.1058 .1135 .1306 .1537 .1830 .2194 .2637 .3169 .1226 .1275 .1410 .1618
.1896 .2250 .2685 .3210 .0994 .1051 .1203 .1431 .1728 .2099 .2550 .3090
.0812 .0901 .1095 .1347 .1660 .2041 .2501 .3048 .0625 .0826 .1051 .1317
.1636 .2021 .2484 .3033 .0812 .0901 .1095 .1347 .1660 .2041 .2501 .3048
.0994 .1051 .1203 .1431 .1728 .2099 .2550 .3090 .0969 .1026 .1179 .1408
.1706 .2078 .2532 .3073 .0785 .0876 .1070 .1324 .1638 .2021 .2482 .3030
.0597 .0799 .1027 .1293 .1614 .2001 .2465 .3016 .0785 .0876 .1070 .1324
.1638 .2021 .2482 .3030 .0969 .1026 .1179 .1408 .1706 .2078 .2532 .3073
.0965 .1023 .1176 .1405 .1703 .2075 .2529 .3070 .0782 .0873 .1067 .1321
.1635 .2018 .2480 .3028 .0594 .0796 .1024 .1290 .1611 .1998 .2463 .3013

```


.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028	.0965	.1023	.1176	.1405
.1703	.2075	.2529	.3070	.0965	.1023	.1176	.1405	.1703	.2075	.2529	.3070
.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028	.0594	.0796	.1024	.1290
.1611	.1998	.2463	.3013	.0782	.0873	.1067	.1321	.1635	.2018	.2480	.3028
.0965	.1023	.1176	.1405	.1703	.2075	.2529	.3070				

CY(ALPHA,BETA,M)

2	3	8	5	8							
0.	4.	8.	12.	16.	20.	24.	28.				
-8.	-4.	0.	4.	8.							
2.	3.	4.	5.	6.	6.5	7.	30.				
.1117	.1129	.1163	.1209	.1262	.1319	.1379	.1442	.0538	.0545	.0566	.0593
.0622	.0652	.0684	.07160	0	0	0	0	0	0	0	0
-.0538-	.0545-	.0566-	.0593-	.0622-	.0652-	.0684-	.0716-	.1117-	.1129-	.1163-	.1209
-.1262-	.1319-	.1379-	.1442	.0575	.0623	.0722	.0826	.0924	.1017	.1108	.1197
.0100	.0206	.0312	.0386	.0444	.0496	.0544	.05910	0	0	0	0
0	0	0	0	-.0106-	.0206-	.0312-	.0386-	.0444-	.0496-	.0544-	.0591
-.0575-	.0623-	.0722-	.0826-	.0924-	.1017-	.1108-	.1197	.0345	.0394	.0497	.0607
.0713	.0814	.0913	.1011	.0011	.0089	.0198	.0275	.0337	.0393	.0446	.0497
0	0	0	0	0	0	0	0	.0011-	.0089-	.0198-	.0275
-.0337-	.0393-	.0446-	.0497-	.0345-	.0394-	.0497-	.0607-	.0713-	.0814-	.0913-	.1011
.0354	.0386	.0461	.0548	.0639	.0733	.0827	.0923	.0077	.0128	.0194	.0250
.0303	.0353	.0403	.04530	0	0	0	0	0	0	0	0
-.0077-	.0128-	.0194-	.0250-	.0303-	.0353-	.0403-	.0453-	.0354-	.0386-	.0461-	.0548
-.0639-	.0733-	.0827-	.0923	.0481	.0495	.0538	.0600	.0674	.0755	.0841	.0931
.0228	.0228	.0248	.0283	.0323	.0366	.0411	.04570	0	0	0	0
0	0	0	0	-.0228-	.0228-	.0248-	.0283-	.0323-	.0366-	.0411-	.0457
-.0481-	.0495-	.0538-	.0600-	.0674-	.0755-	.0841-	.0931	.0484	.0499	.0540	.0602
.0675	.0756	.0842	.0932	.0232	.0230	.0250	.0284	.0324	.0367	.0411	.0458
0	0	0	0	0	0	0	0	-.0232-	.0230-	.0250-	.0284
-.0324-	.0367-	.0411-	.0458-	.0484-	.0499-	.0540-	.0602-	.0675-	.0756-	.0842-	.0932
.0484	.0499	.0540	.0602	.0675	.0756	.0842	.0932	.0232	.0230	.0250	.0284
.0324	.0367	.0411	.04580	0	0	0	0	0	0	0	0
-.0232-	.0230-	.0250-	.0284-	.0324-	.0367-	.0411-	.0458-	.0484-	.0499-	.0540-	.0602
-.0675-	.0756-	.0842-	.0932	.0484	.0499	.0540	.0602	.0675	.0756	.0842	.0932
.0232	.0230	.0250	.0284	.0324	.0367	.0411	.04580	0	0	0	0
0	0	0	0	-.0232-	.0230-	.0250-	.0284-	.0324-	.0367-	.0411-	.0458
-.0484-	.0499-	.0540-	.0602-	.0675-	.0756-	.0842-	.0932				

CL(ALPHA,BETA,M)

3	3	8	5	8							
0.	4.	8.	12.	16.	20.	24.	28.				
-8.	-4.	0.	4.	8.							
2.	3.	4.	5.	6.	6.5	7.	30.				
0	.0402	.0825	.1275	.1747	.2230	.2709	.31700		.0387	.0802	.1251
.1726	.2212	.2697	.3163	.0020	.0382	.0793	.1242	.1718	.2206	.2692	.3160
0	.0387	.0802	.1251	.1726	.2212	.2697	.31630		.0402	.0825	.1275
.1747	.2230	.2709	.31700		.0162	.0409	.0737	.1119	.1536	.1969	.2402
0	.0063	.0323	.0670	.1067	.1495	.1937	.2379-	.0288-	.0034	.0279	.0643
.1048	.1480	.1920	.23710		.0063	.0323	.0670	.1067	.1495	.1937	.2379
0	.0162	.0409	.0737	.1119	.1536	.1969	.24020		.0077	.0242	.0492
.0803	.1158	.1538	.19290		-.0022	.0154	.0423	.0748	.1112	.1502	.1901
-.0282-	.0118	.0110	.0395	.0727	.1096	.1489	.18910		-.0022	.0154	.0423
.0748	.1112	.1502	.19010		.0077	.0242	.0492	.0803	.1158	.1538	.1929
0	.0103	.0262	.0485	.0761	.1078	.1424	.17840		.0049	.0206	.0434
.0716	.1040	.1392	.1758-	.0109	.0003	.0180	.0415	.0700	.1026	.1380	.1749
0	.0049	.0206	.0434	.0716	.1040	.1392	.17580		.0103	.0262	.0485
.0761	.1078	.1424	.17840		.0173	.0369	.0603	.0879	.1191	.1528	.1879
0	.0165	.0345	.0573	.0847	.1161	.1502	.1857	.0067	.0171	.0338	.0562
.0830	.1151	.1493	.18500		.0165	.0345	.0573	.0847	.1161	.1502	.1857
0	.0173	.0369	.0603	.0879	.1191	.1528	.18790		.0176	.0375	.0611
.0888	.1202	.1541	.18920		.0169	.0352	.0581	.0857	.1172	.1515	.1871
.0071	.0177	.0345	.0571	.0847	.1162	.1506	.18630		.0169	.0352	.0581
.0857	.1172	.1515	.18710		.0176	.0375	.0611	.0888	.1202	.1541	.1892
0	.0177	.0375	.0611	.0889	.1203	.1542	.18940		.0169	.0352	.0582
.0858	.1173	.1516	.1872	.0071	.0177	.0345	.0571	.0847	.1163	.1507	.1865
0	.0169	.0352	.0582	.0858	.1173	.1516	.18720		.0177	.0375	.0611
.0889	.1203	.1542	.18940		.0177	.0375	.0611	.0889	.1203	.1542	.1894
0	.0169	.0352	.0582	.0858	.1173	.1516	.1872	.0071	.0177	.0345	.0571
.0847	.1163	.1507	.18650		.0169	.0352	.0582	.0858	.1173	.1516	.1872
0	.0177	.0375	.0611	.0889	.1203	.1542	.1894				

END CARD

20
-1 END OF JOB

b. STEP2 input:

1	STEP2 FILTERING CHECK PROBLEM (FEB. 1969) WAGNER AND SEROLD										
2	0	1	2	0	0	2	1	3	0	0	PROGRAM CONTROLS
3	1	1	16001.2000	100.							(SIG=100. ,RN=.55)
3	1	2	-6.75088000	.035							(SIG=2 DEG ,RN=-.81)
3	1	3	63.0352000	.018							(SIG=1 DEG ,RN=-.33)
3	1	4	100584.000	1000.							(SIG=1000. ,RN=-.96)
3	1	5	16.7583977	.0003							(SIG=.017DEG,RN=1.69)
3	1	6	28.0418380	.0003							(SIG=.017DEG,RN=.05)
3	1	7	29.8270000	.0530							(SIG=3 DEG ,RN=1.10)
3	1	8	-4.43200000	.0350							(SIG=2 DEG ,RN=-1.72)
3	1	9	19.3930000	.0530							(SIG=3 DEG ,RN=-1.37)
3	2	72	.092200000	.2000							(SIG=.20 ,RN=-.54)
3	2	103	16.6055454	.000375							(SIG=.0214 DEG) MOD.PARA. - Z
3	2	104	31.0	.000375							(SIG=.0214 DEG) MOD.PARA. - Z
3	3	70	0.	.20							MOD.PARA. - U
3	3	71	0.	.20							MOD.PARA. - U
3	4	76	1.0	.000030							MEAS.PARA.- V
3	4	81	0.	.000030							
3	5	31	-1.0								CONSTANT
3	5	33	0.5								CONSTANT
3	5	88	15.09690377								CONSTANT
3	5	89	27.0								CONSTANT
6	1	2									CG/IMU
	0.0		1.0		100.0		1.0				
6	3	2									CG/IMU
	0.0		-0.5		100.0		-0.5				
4		70.0		5.0		0.5		90.0			
5	1	32.174048		1.407690E16		1092.055E-6					GRAV. DATA
5	2	20855970.		20926430.		.7292115E-4					GEOPH.DATA
7	1	70.0	82.0	.99	1 1 1	20.0	.00003	.00003			MEAS.CDS.
7	2	78.0	88.0	1.99	1 1 1	20.0	.00003	.00003			MEAS.CDS.
20											END CARD
-1	END OF JOB										

B. Tape Input and Output

STEP always requires the PQR tape containing data used by the equations of motion. When operating in the filtering mode, the programs also require a FIT tape containing data to which the equations of motion are fit. Formats for these tapes are presented in the previous section under input format 2 and 3.

On filtering problems, optional capability has been included to write a tape containing the 10-state variables u , v , w , h , ϕ , θ , e_0 , e_1 , e_2 , and e_3 versus time. This tape, called STATE, is written on the backward smoothing of the last iteration so that it contains the best estimate of the variables after processing all data. Because it is written on the backward smoothing, the first points on the tape are at final time, the last points at initial time. The tape can be used to print the state time history in tabular form, or to prepare STEP2 position and velocity estimates for processing on STEP1. All angular data on the tape are in radians, the remainder in the m, kg, sec or slug, ft, sec systems of units.

<u>FORTTRAN</u> <u>name</u>	<u>Logical tape</u> <u>unit</u>	<u>Description</u>
IN	5	Input tape
OUT	6	Output tape
PQR	2	PQR tape
FIT	1	FIT tape
STATE	4	STATE tape
SCRACH	3	Scratch tape used for temporary storage during problem execu- tion

C. Tab Output

The tab printout from STEP is divided into four parts -- Part 1, the printout of input variables and controls; Part 2, the block printout during the forward and backward integration; Part 3, the printout of the measurement schedule; and Part 4, the printout of the residuals and loss function. Each of these printouts will be described. The sample outputs in Subsection C.5 will aid in the discussion.

1. Printout of input data and controls.- As data are input to STEP, they are immediately printed for later verification. This printout, shown on the first page of the sample output, is unlabelled and exactly duplicates the data on the input cards. If the user requests printout of the PQR and/or FIT tapes, it occurs during this part of the output. After all input data have been loaded from cards, subroutine SETUP is called to transform and convert units (e.g., degrees to radians) on the data to prepare for the problem execution. From SETUP, a summary of the problem operating mode, options, and controls is printed in the form of phrases and data. The data consist primarily of geophysical, gravitational, and atmosphere constants, state variables, and tracking station locations. The units on these data are consistent with metric or English system specified. All angular data are in degrees.

The components of the expanded state variables transformed to internal units are next tabulated along with uncertain model parameters and their variances. In this tabulation, all angles are in radians.

2. Block printout.- During execution of a problem, labeled block printouts occur during both the forward filtering and backward smoothing at a frequency specified by input. The variables in the block printout on the forward integration correspond to the reference trajectory. In STEP2, this block printout appears as follows:

```

TIME --
V(A) -- G(A) -- L(A) -- ALT -- LATD -- LON --
U(I) -- V(I) -- W(I) -- PSI -- THE -- PHI --
U(B) -- V(B) -- W(B) -- SIG -- BET -- ALF --
XP -- YP -- ZP -- V(T) -- XZI -- ETA --
P -- Q -- R -- AX -- AY -- AZ --
PM -- QM -- RM -- AXM -- AYM -- AZM --
EO -- E1 -- E2 -- E3 -- LATC -- A(T) --

```

where

$V(A), G(A), L(A)$ = Atmosphere relative velocity vector V_A , γ_A , and λ_A . In STEP2, there is no atmosphere; therefore, the velocity vector is relative to planet surface. Units are m/sec or ft/sec and deg.

$U(I), V(I), W(I)$ = Inertial velocity vector Cartesian components, u , v , and w . Units are m/sec or ft/sec.

$U(B), V(B), W(B)$ = Components of V_A in body axes directions, u_B , v_B , and w_B . Units are m/sec or ft/sec.

ALT = Altitude above oblate planet surface, h_0 . Units are in m or ft.

LATD = Geodetic latitude in degrees.

LON = Longitude in degrees.

PSI, THE, PHI = Euler angles $\bar{\psi}$, $\bar{\theta}$, $\bar{\phi}$ and in degrees.

SIG, BET, ALF = Roll angle σ about the velocity vector V_A , sideslip angle β and angle of attack α . Units are degrees.

XP, YP, ZP = Distances from center of gravity to the IMU as measured along body axes directions, and corrected for systematic error, x_p , y_p , and z_p . Units are in m or ft.

$V(T)$ = Magnitude of the inertial velocity vector in m/sec or ft/sec.

XZI = Steering angle ξ in degrees. See figure 4 of vol. I.

ETA = Steering angle η in degrees. See figure 4 of vol. I.

P, Q, R = Inertial angular rates about the roll, pitch, and yaw axes and corrected for systematic error. Units are in rad/sec.

PM, QM, RM = Inertial angular rates about the roll, pitch, and yaw axes as interpolated from the PQR tape. Units are in rad/sec.

AX, AY, AZ = Accelerations a_{XB} , a_{YB} , and a_{ZB} , along the body axes direction and corrected for systematic error. Units are in m/sec² or ft/sec².

AXM, AYM, AZM = Accelerations, a_{XM} , a_{YM} , and a_{ZM} , along the body axes directions as interpolated from the PQR tape. Units are in m/sec² or ft/sec².

EO, E1, E2, E3 = Euler parameters e_0 , e_1 , e_2 , and e_3 .

LATC = Geocentric latitude in degrees.

A(T) = Total acceleration in m/sec² or ft/sec².

In STEP1, the last two lines of output are replaced by the following:

```
PM -- QM -- RM -- CA -- CY -- CN --
DP -- M -- RHO -- C1 -- C2 -- C3 --
EO -- E1 -- E2 -- E3 -- LATC -- RE --
UW -- VW --
```

where

C_A , C_Y , C_N = Axial, lateral, and normal aerodynamic coefficients.

C1, C2, C3 = Aerodynamic coefficients interpolated from input tables, either C_A , C_Y , C_N , or C_D , C_Y , C_L , or C_A , C_{Y_η} , C_{N_η} , respectively.

DP = Dynamic pressure q in nt/m² or lb_f/ft².

M = Mach number, M.

RHO = Atmospheric density ρ in kg/m³ or slugs/ft³.

RE = Reynolds number, R_e .

UW, VW = Atmospheric winds corrected for systematic error, u_w
and v_w . Units are in m/sec or ft/sec.

On filtering problems during the forward integration the reference values of the model parameters being estimated are printed in the order that they were input. The print format is as follows:

```
C(24) -- C(28) -- C(43) -- C(40) -- C(77) -- C(88) --  
C( . ) -- . . .
```

The argument of C(.) are the variable identification numbers and their units are as described in Subsection II.A.4.

On nonupdated nominal filtering problems during the forward integration, the accumulated minimum variance corrections, $\hat{Z}(t/t)$, to be added to the reference, $Z_{ref}(t)$, are next printed:

```
Z(1) -- Z(2) -- Z(3) -- Z(4) -- Z(5) -- Z(6) --  
Z(7) -- Z(8) -- Z(9) -- Z(24) -- Z(28) -- Z(43) --  
Z(88) -- . . .
```

The first 9 or 10 variables correspond to the transformed state variables specified by NPC(3). The remaining variables correspond to the estimated model parameters whose identification numbers and units are specified in Subsection II.A.4.

The standard deviations of the expanded state vector components are printed next on error analysis and filtering problems according to the following format:

```
S(1) -- S(2) -- S(3) -- S(4) -- S(5) -- S(6) --  
S(7) -- S(8) -- S(9) -- S(23) -- S(19) --.
```

The first 9 or 10 standard deviations correspond to the basic state variables, transformed as specified by NPC(3). These are followed by the standard deviation of model parameters being estimated in the order that they were input. The argument in S() is the identification number of the estimated model parameter which, along with the units for the standard deviations,

are shown in Subsection II.A.4. These standard deviations are printed on the backward smoothing on the last iteration only if NPC(8) equals 2 or 3.

On error analysis or filter problems, the entire covariance and correlation matrices P, CUZ, and CVZ, can be printed during the last iteration if NPC(6) is properly specified. These matrices correspond to the output units designated by NPC(3). Units for the covariance and correlation elements are as described for the standard deviations in Subsection II.A.4. Because the covariance matrix P is symmetrical, only its lower left triangle is printed as follows:

COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

P(1,1)

P(2,1) P(2,2)

P(3,1) P(3,2) P(3,3)

.

The correlation matrices CUZ and CVZ are printed as shown below.

CORRELATION MATRIX (CVZ) TRANSPOSE

CUZ(1,1) CUZ(2,1) CUZ(12,1)

CUZ(13,1) CUZ(14,1) . . .

CUZ(1,2) CUZ(2,2) CUZ(12,2)

CUZ(13,2) CUZ(14,2) . . .

.

.

CUZ(1,q) CUZ(2,q) CUZ(12,q)

CUZ(13,q) CUZ(14,q) . . .

CORRELATION MATRIX (CVZ) TRANSPOSE

CVZ(1,1) CVZ(2,1) CVZ(12,1)

CVZ(13,1) CVZ(14,1) . . .

CVZ(1,2) CVZ(2,2) CVZ(12,2)
 CVZ(13,2) CVZ(14,2) . . .

CVZ(1,r) CVZ(2,r) CVZ(12,r)
 CVZ(13,4) CVZ(14,4) . . .

3. Measurement schedule.- Between block printing on the forward integration, a schedule of the measurements processed can be printed if NPC(5) equals 0. The following format is used for this printout:

```
POINTS  TYPE  TIME  COMP1  COMP2  COMP3  SIG1  SIG2  SIG3
x, x, x   x   xxx   xxx   xxx   xxx   xxx   xxx   xxx
x, x, x   x   xxx   xxx   xxx   xxx   xxx   xxx   xxx
```

The number of scalar data points processed is counted and printed under the heading POINTS. The three numbers correspond to the three scalar components accounted for on each line of data. If a zero is printed under the POINTS heading, then the component corresponding to the zero was not processed. Under TYPE, the type of data (MTYP) is printed. Definitions of MTYP are presented in Subsection II.A.2. The time of the data is next printed under TIME and followed by the values for the three components. Units for these data are shown below.

...	TYP	TIME	COMP1	COMP2	COMP3	SIG1	SIG2	SIG3
Tracking	1-5	(sec)	R(m,ft)	A(rad)	E(rad)	σ_R (m,ft)	σ_A (rad)	σ_E (rad)
Airborne radar	6	(sec)	R_R (m,ft)	unused	unused	σ_{R_R} (m,ft)	unused	unused
Velocity	7	(sec)	u(m/sec ft/sec)	v(m/sec ft/sec)	w(m/sec ft/sec)	σ_u (m/sec ft/sec)	σ_v (m/sec ft/sec)	σ_w (m/sec ft/sec)
Position	8	(sec)	h(m,ft)	φ (rad)	θ (rad)	σ_h (m,ft)	σ_φ (rad)	σ_θ (rad)
Accelerations	9	(sec)	a_x (m/sec ² ft/sec ²)	a_y (m/sec ² ft/sec ²)	a_z (m/sec ² ft/sec ²)	σ_{a_x} (m/sec ² ft/sec ²)	σ_{a_y} (m/sec ² ft/sec ²)	σ_{a_z} (m/sec ² ft/sec ²)

The values for the measurement that are printed under columns COMP1. . COMP3 are the values corresponding to the reference trajectory and not the actual data from the FIT tape. The standard deviations under columns SIG1. . SIG3 are the sum of the standard deviations from the FIT tape and those input in category 7. These are the standard deviations used in the filter equations.

4. Residuals and loss function.- During the backward smoothing on the last iteration, best estimates of the measurements are calculated. The value of the measurement from the FIT tape is then subtracted from that calculated to form a residual. The residual is then divided by the standard deviation to form a weighted residual, and its square accumulated with all previously calculated weighted residuals to form the sum of the weighted residuals squared or loss function. These are tabulated between block prints as follows:

POINT	TYPE	TIME	RES1	RES2	RES3	WGT.	RES1	WGT.	RES2	WGT.	RES3	LOSS FCTN
x, x, x	x	xx	xx	xx	xx	xx		xx		xx		xx
x, x, x	x	xx	xx	xx	xx	xx		xx		xx		xx

The quantities under POINT, TYPE, and TIME are the same as in the measurement schedule in Subsection 3 above. RES1 .. RES3 are the unweighted residuals in m, ft, and rad; WGT. RES1 ... WGT. RES3 are the weighted residuals; and LOSS FCTN is the loss function. Three components of data per line is maintained. Only those components processed on the forward integration are accumulated in the loss function.

5. Sample output.- The sample outputs presented below were obtained on STEP1 and STEP2. They correspond to 20 sec of the check problem between 70 and 90 sec.

INPUT DATA

[illegible]

[illegible]

20

CONTROLS ARE SPECIFIED FOR
 *FILTERING RUN FROM TIME TO= 70.0000 TO TFINAL= 90.0000
 *UPDATED REFERENCE
 *SMOOTH COVARIANCE, CALCULATE RESIDUALS AND LOSS FUNCTION
 *FILTER FOR 1 ITERATIONS
 *VECTOR PROCESS FITTING DATA TRIPLES
 *INPUT AND OUTPUT IN ENGLISH UNITS (FT, FT/SEC, FT/SEC², LB, SLUG)
 *PLANET PARAMETERS
 EQUIT. RAD. = 2.09264300E+07 POLAR RAD. = 2.08559700E+07 ROTATION = 7.29211500E-05
 MU(GRAV.) = 1.40769000E+16 J2(GRAV.) = 1.09205500E-03 G(0) = 3.21740480E+01
 *ATMOSPHERE IS 1959 ARDC
 MO = 2.89644000E+01 R(ISTAR) = 4.97192198E+04 CP/CV = 1.40000000E+00
 P(0) = 2.11621667E+03 BETA = 2.26968110E-08 S = 1.98720000E+02
 3.60892388E+04 A.20209974E+04 1.54199475E+05 1.73884514E+05 2.59186352E+05
 2.95275591E+05 3.44488189E+05 5.24934383E+05 5.51742782E+05 6.56167979E+05 2.29658793E+06
 TMB = 5.18688000E+02 3.89988000E+02 3.89988000E+02 5.08788000E+02 5.08788000E+02 2.98188000E+02
 2.98188000E+02 4.06188000E+02 2.38618800E+03 2.56618800E+03 2.83618800E+03 5.98618800E+03
 PB = 2.11621667E+03 4.72708961E+02 5.19844194E+01 2.51625139E+00 1.21846395E+00 2.10938433E-02
 2.18258255E-03 1.55768677E-04 7.56734675E-06 5.90259850E-06 2.97981080E-06 2.03048103E-09
 *INITIAL STATE ESTIMATE IS
 VELOCITY = 1.60012000E+04 GAMMA = -6.75088000E+00 LAMBDA = 6.30352000E+01
 ALTITUDE = 1.00584000E+05 GEOD. LAT. = 1.67583977E+01 LONGITUDE = 2.80418380E+01
 SIGMA = 2.98270000E+01 BETA = -4.43200000E+00 ALPHA = 1.93930000E+01
 *FITTING DATA IS FROM 2 SOURCES
 1. TRACKING STATION 1, GEOD. LAT. = 15.096904 LONGITUDE = 27.000000 ALTITUDE = 0. ABOVE REF. SURFACE
 2. TRACKING STATION 2, GEOD. LAT. = 16.605545 LONGITUDE = 31.000000 ALTITUDE = 0. ABOVE REF. SURFACE

STATE VECTOR COMPONENTS
 COMP. ID.NO. EST. VALUE VARIANCE
 1 1 7.20532663E+03 6.79079215E+04
 2 2 1.56313582E+04 2.80981835E+04
 3 3 1.88098346E+03 3.09451057E+05
 4 4 9.47712173E+04 1.00000000E+06
 5 5 2.90632098E-01 9.00000000E-08
 6 6 4.89422401E-01 9.00000000E-08
 7 7 7.69645202E-01 2.08169635E-04
 8 8 1.55940474E-01 7.90725687E-04
 9 9 2.08732405E-01 8.18646927E-04
 10 10 5.82889025E-01 2.8045751E-04
 MODEL PARAMETERS IN EXPANDED STATE VECTOR
 11 46 -1.08000000E-04 4.00000000E-08
 12 103 2.87979327E-01 1.40625000E-07
 13 104 5.41052068E-01 1.40625000E-07
 RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR)
 1 45 0.
 2 47 0.
 1.00000000E-08

[illegible]

TIME 9.00000000E+01
 V(R) 1.19554237E+04 G(R) 2.06815112E+00 L(R) 6.83780005E+01 ALT 9.32692875E+04 LAT 1.70498550E+01 LON 2.87620795E+01
 U(I) 4.40248317E+03 V(I) 1.25727819E+04 W(I) -4.31449824E+02 PSI 8.01089506E+01 THE 2.37172370E+01 PHI 2.35771291E+01
 U(R) 1.08836235E+04 YP 0.0 V(R) -5.02356181E+02 W(R) 4.92204576E+03 SIG 2.14226721E+01 BET -2.40822629E+00 ALF 2.43345424E+01
 P -1.40266441E+03 Q 6.71335986E+03 R 9.56333835E+04 AX -1.04926682E+02 XZ1 -5.82757030E+00 ETA 2.24816576E+01
 PM -1.40266441E+03 QM 6.75272832E+03 RM 9.56333835E+04 CX -1.04926682E+02 AY 1.57921351E+01 AZ -1.54454736E+02
 DP 3.18930794E+03 M 1.20763478E+01 RHO 4.46268781E+05 C1 2.51913384E+01 C2 2.49811859E+02 CZ -2.44328108E+01
 E0 7.60313690E+01 E1 2.35892890E+02 E2 2.82641664E+01 E3 5.84363181E+01 LATC 1.69418189E+02 C3 1.54225935E+01
 UW 0.0 VU 2.0
 S(1) 6.5529222E+00 S(2) 3.447435E+04 S(3) 4.563711E+03 S(4) 2.192707E+01 S(5) 1.705938E+06 S(6) 1.491527E+06
 S(7) 2.820497E+02 S(8) 8.709750E+03 S(9) 1.955745E+03 S(46) 0.0
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 4.294E+01
 -8.989E-05 1.188E-07
 -1.159E-03 -1.175E-07 2.083E-07
 6.822E+00 6.515E-03 6.811E+03 4.808E+02
 5.907E-06 2.8024E-10 6.362E-10 1.315E+05 2.910E-12
 7.289E-06 6.861E-11 7.031E-12 3.621E-06 4.863E-13 2.225E-12
 -4.456E-02 0.0 -3.893E-01 -1.189E-08 -5.486E-09 6.867E-04
 -1.329E-02 -2.385E-06 0.0 -1.176E-01 -1.453E-09 -2.048E-09 2.247E-04 7.586E-05
 -1.178E-02 -8.329E-09 3.167E-07 -2.636E-03 -1.217E-09 -1.612E-09 1.890E-05 6.124E-06 3.825E-04
 2.664E-08 1.190E-09 9.588E-04 9.588E-04 4.986E-11 -8.796E-11 -9.120E-07 -3.126E-07 2.735E-07 0.0
 9.632E-12 1.279E-10 9.246E-07 9.246E-07 9.135E-13 2.455E-14 9.819E-10 6.185E-10 -6.777E-11 0.0
 1.191E-11 7.247E-12 1.523E-07 1.523E-07 2.435E-14 6.842E-13 -1.456E-09 -4.826E-10 -8.534E-11 0.0
 CORRELATION MATRIX (CUT) TRANSPOSE
 -4.651E-08 -7.411E-10 5.259E-10 -2.869E-05 -6.680E-13 -4.007E-13 1.376E-07 5.301E-08 4.996E-09 -2.850E-11 6.562E-14 -4.483E-14
 -6.993E-08 -1.867E-09 8.239E-09 -1.603E-05 -1.240E-11 4.332E-12 -1.361E-07 -1.497E-07 -6.644E-09 -2.112E-11 -1.392E-13 -2.952E-13

POTINS TYPE TIME TRES RES3 WGT.RES1 WGT.RES2 WGT.RES3 LOSS FCIN
 54. 53. 52 2 86.000 8.61116E+00 2.29483E-05 -2.66269E-05 4.80858E-01 7.64943E-01 -8.87584E-01 1.56726E+00
 54. 53. 52 2 86.000 2.51242E+00 6.01273E-06 -2.07197E-05 1.25621E-01 2.00424E-01 -6.90657E-01 2.10022E+00

TIME 8.50000000E+01
 V(R) 1.28472466E+04 G(R) 3.58006627E-01 L(R) 6.71738030E+01 ALT 9.18954918E+04 LAT 1.69856578E+01 LON 2.85987195E+01
 U(I) 4.98382560E+03 V(I) 1.33071388E+04 W(I) -8.0274141E+01 PSI 7.88483700E+01 THE 2.17031346E+01 PHI 2.3467792E+01
 U(R) 1.17190580E+04 YP 0.0 V(R) -5.61520723E+02 W(R) 5.23451228E+03 SIG 2.17211533E+01 BET -2.50505191E+00 ALF 2.40687220E+01
 P -1.27096643E-03 Q 7.97577875E-03 R 9.96728523E-04 AX -1.28657875E+02 XZ1 -6.12286345E+00 ETA 2.22828348E+01
 PM -1.27096643E-03 QM 8.01514722E-03 RM 9.96728523E-04 CX -1.64778691E+01 CY 2.57899783E+02 CZ -2.39939670E+01
 DP 3.94309308E+03 M 1.30130011E+01 RHO 4.77400832E+05 C1 2.48307423E+01 C2 2.57899783E+02 C3 1.51876547E+01
 E0 7.67113067E+01 E1 3.72231288E-02 E2 2.69228703E-01 E3 5.81091978E-01 LATC 1.68779800E+01 RE 3.00137644E+07
 UW 0.0 VU 0.0
 S(1) 3.186541E+00 S(2) 1.767405E+04 S(3) 2.4400212E-04 S(4) 1.007031E+01 S(5) 8.053660E-07 S(6) 7.548484E-07
 S(7) 2.591052E-02 S(8) 9.202198E-03 S(9) 1.494262E-03 S(46) 0.0
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 1.015E+01
 6.031E-06 3.124E-08
 -2.296E-04 -2.145E-08 5.761E-08
 2.197E-01 9.328E-04 -4.879E-04 1.014E+02
 8.783E-07 7.948E-12 -1.371E-10 1.615E-07 6.486E-13
 1.300E-06 3.493E-12 2.862E-11 -3.619E-07 -2.735E-14 5.698E-13
 -2.162E-02 0.0 -4.177E-02 2.699E-09 -2.909E-09 6.714E-04
 -6.995E-03 -1.064E-06 0.0 -1.243E-02 1.365E-09 -1.074E-09 2.358E-04 8.468E-05
 -3.266E-03 -8.000E-07 7.837E-08 -7.836E-04 1.466E-11 -1.667E-10 2.617E-05 9.173E-06 2.233E-04
 8.152E-09 2.865E-09 -3.738E-05 3.738E-05 -8.469E-13 2.107E-11 -9.028E-07 -3.326E-07 1.328E-07 0.0
 9.951E-12 -1.062E-10 2.032E-07 2.032E-07 2.585E-13 -2.934E-14 9.618E-10 6.687E-10 -5.106E-11 0.0
 1.513E-12 1.999E-11 -3.536E-07 -3.536E-07 -2.595E-14 4.437E-13 -1.439E-09 -5.157E-10 -1.236E-10 0.0
 CORRELATION MATRIX (CUT) TRANSPOSE
 -8.054E-07 -1.999E-10 -6.729E-12 -3.093E-07 1.893E-13 -8.692E-14 9.055E-08 3.547E-08 3.646E-09 -2.850E-11 6.562E-14 -4.483E-14
 -8.075E-07 3.813E-11 2.001E-09 3.505E-05 1.077E-12 -5.946E-13 -1.525E-07 -1.152E-07 -7.449E-09 -2.112E-11 -1.392E-13 -2.952E-13

```

POINTS      TYPE      TIME      RES1      RES2      RES3      WGT.RES1  WGT.RES2  WGT.RES3  LOSS.FCTN
51. 50. 49 2 86.000 -1.11081E+00 -4.93179E-06 -1.31905E-05 -5.55540E-02 -1.64393E-01 -4.39682E-01 2.32365E+00
48. 47. 46 2 82.000 -3.15169E+00 -1.02173E-05 -4.68689E-06 -2.45758E-01 -3.40577E-01 -1.56230E-01 2.48889E+00
45. 44. 43 1 82.000 -4.92528E+00 -3.05319E-07 -2.45626E-01 -2.46264E-01 -1.01799E-02 -1.53086E-01 2.57307E+00
42. 41. 40 1 81.000 -4.46646E+00 1.42205E-06 -2.28316E-07 -2.23323E-01 4.74017E-02 -7.61052E-03 2.62525E+00
39. 38. 37 2 80.000 -4.56573E+00 -1.06611E-05 3.96538E-06 -2.27287E-01 -3.55368E-01 1.32180E-01 2.82067E+00
36. 35. 34 1 80.000 -3.19663E+00 7.55063E-06 4.18142E-06 -1.59332E-01 8.50211E-02 1.39381E-01 2.87287E+00

TIME R.00000000E+01
V(R) 1.38827931E+04 G(R) -1.58868337E+00 L(R) 6.58464283E+01 ALT 9.25656539E+04 LAT 1.69126709E+01 LON 2.84242584E+01
U(R) 5.67843029E+03 V(R) 1.41293698E+04 W(R) 3.68488937E+02 PSI 7.74884330E+01 THE 1.9443355E+01 PHI 2.33182576E+01
U(B) 1.26889634E+04 YP 0. 5.42612495E-03 R 1.01728525E-03 AX -1.44444595E+02 XZ 2.37001913E+01 AZ -2.07771837E+02
.. 6.42612495E-03 R 1.01728525E-03 AX -1.44444595E+02 XZ 2.37001913E+01 AZ -2.07771837E+02
PM -1.09490564E-03 QM 8.46549342E-03 RM 1.01728525E-03 CX -1.63894121E-01 CY 2.68990503E-02 CZ -2.35740259E-01
DP 4.45333027E+03 M 1.40429897E+01 PHO 4.62126643E-05 C1 2.65084086E-01 C2 2.68905030E-02 C3 1.49561178E-01
EO 7.74243329E-01 EI 5.18706093E-02 E2 2.53627120E-01 E3 5.77550823E-01 LATC 1.68054011E+01 RE 3.12991604E+07
UW 0.
S( 1) 2.0478609E+00 S( 2) 9.251443E-05 S( 3) 1.815181E-04 S( 4) 7.039200E+00 S( 5) 4.096122E-07 S( 6) 4.495324E-07
S( 7) 2.556625E-02 S( 8) 9.891964E-03 S( 9) 1.413456E-03 S( 46) 0. S(103) 0. S(104) 7.252491E-07
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
4.194E+00
-2.191E-05 8.559E-07
-1.278E-04 4.197E-09 3.295E-08
8.681E-01 1.811E-04 9.247E-05 4.955E+01
1.018E-07 3.161E-12 1.863E-11 4.234E-08 1.478E-13
2.994E-07 3.493E-12 1.472E-11 3.852E-07 2.965E-14 2.021E-13
1.762E-02 0. 4.462E-02 5.926E-10 3.708E-10 6.536E-04
7.024E-03 2.278E-07 0. 1.442E-02 3.230E-10 5.081E-11 2.504E-04 9.785E-05
5.357E-04 3.306E-08 1.563E-07 2.058E-03 2.382E-11 4.170E-11 3.329E-05 1.2881E-05 1.998E-06
-4.012E-09 4.032E-09 1.093E-04 1.093E-04 7.236E-12 1.212E-11 8.903E-07 3.596E-07 1.405E-08 0.
6.333E-12 7.593E-11 3.349E-07 3.349E-07 1.964E-13 4.162E-14 9.359E-10 7.319E-10 3.401E-11 0.
-4.401E-12 2.830E-11 1.780E-07 1.780E-07 3.094E-14 2.218E-13 1.418E-09 5.591E-10 1.652E-10 0.
CORRELATION MATRIX (CUT) TRANSPOSE
-2.323E-06 1.236E-10 2.763E-10 7.782E-07 3.630E-13 5.587E-14 4.383E-08 1.727E-08 2.024E-09 2.850E-11 6.562E-14 4.483E-14
-4.960E-06 6.066E-10 6.446E-10 4.135E-06 2.157E-12 5.896E-13 1.692E-08 7.891E-08 8.789E-09 2.112E-11 1.392E-11 2.952E-13

POINTS      TYPE      TIME      RES1      RES2      RES3      WGT.RES1  WGT.RES2  WGT.RES3  LOSS.FCTN
33. 32. 31 1 79.000 -1.16035E+00 3.22293E-06 8.49005E-06 -5.80173E-02 1.07431E-01 2.83002E-01 2.96787E+00
30. 29. 28 2 78.000 -6.19738E+00 -7.37602E-06 1.10344E-05 -3.08669E-01 -2.445867E-01 3.94932E-01 3.27996E+00
27. 26. 25 1 78.000 1.58505E+00 3.60155E-06 1.25344E-05 7.92527E-02 1.20052E-01 4.17819E-01 3.47523E+00
24. 23. 22 1 77.000 4.96830E+00 3.86681E-06 1.61388E-05 2.48415E-01 1.28894E-01 5.37960E-01 3.84295E+00
21. 20. 19 1 76.000 8.90346E+00 4.21347E-06 1.91174E-05 4.45173E-01 1.40449E-01 6.37248E-01 4.46694E+00
18. 17. 16 1 75.000 1.32897E+01 4.84690E-06 2.12810E-05 6.64487E-01 1.61563E-01 7.09367E-01 5.43779E+00

TIME 7.50000000E+01
V(R) 1.49620564E+04 G(R) -3.50931506E+00 L(R) 6.45270147E+01 ALT 9.57506942E+04 LAT 1.68297235E+01 LON 2.82380703E+01
U(R) 6.42289484E+03 V(R) 1.49499584E+04 W(R) 9.15839650E+02 PSI 7.61662630E+01 THE 1.71041290E+01 PHI 2.31785236E+01
U(B) 1.37024886E+04 YP 0. 7.69522527E-03 R 9.82154065E-04 AX -1.42558057E+02 XZ 1.60087338E+03 XZ 1.60087338E+03 XZ 1.60087338E+03
XP 0. 7.69522527E-03 R 9.82154065E-04 AX -1.42558057E+02 XZ 1.60087338E+03 XZ 1.60087338E+03 XZ 1.60087338E+03
PM -9.42614978E-04 QM 7.73459373E-03 RM 9.82154065E-04 CX -1.63094206E-01 CY 2.81164473E-02 CZ -2.02428760E+02
DP 4.1994124E+03 M 1.50399447E+01 PHO 3.94878889E-05 C1 2.41976679E-01 C2 2.81164473E-02 C3 -2.31589595E-01
EO 7.80928947E-01 EI 6.60275258E-02 E2 2.37783293E-01 E3 5.73802625E-01 LATC 1.67229182E+01 RE 2.85227346E+07
UW 0.
S( 1) 3.744827E+00 S( 2) 1.340256E-04 S( 3) 2.373936E-04 S( 4) 7.285943E+00 S( 5) 8.980707E-07 S( 6) 3.943657E-07
S( 7) 2.521082E-02 S( 8) 1.068616E-02 S( 9) 1.842794E-03 S( 46) 0. S(103) 0. S(104) 7.252491E-07
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)

```

1.402E-01
 3.002E-04 1.796E-08
 -6.431E-04 -2.258E-08 5.662E-08
 -9.842E-00 -3.942E-04 4.225E-04 5.308E+01
 -2.543E-06 -7.351E-11 1.553E-10 2.019E-06 6.857E-13
 -6.281E-07 -2.079E-11 4.141E-11 1.667E-07 1.437E-13 1.555E-13
 8.363E-02 0. -6.582E-02 -1.915E-08 4.794E-09 6.356E-04
 3.535E-02 1.018E-06 0. -3.076E-02 -8.213E-09 -1.948E-09 2.663E-04 1.142E-04
 5.377E-03 1.518E-07 -3.221E-07 -5.235E-03 -1.152E-09 -1.378E-10 4.077E-05 1.726E-05 3.396E-04
 -3.677E-09 5.946E-09 2.686E-04 2.686E-04 1.434E-11 -1.375E-11 -8.764E-07 -3.899E-07 -1.726E-07 0.
 -1.057E-12 -3.860E-11 -4.702E-07 -1.537E-14 -3.001E-14 9.067E-10 8.014E-10 -1.641E-11 0.
 -2.829E-12 3.328E-11 2.333E-07 2.333E-07 1.728E-14 6.438E-14 -1.395E-09 -6.073E-10 -2.121E-10 0.
 0. 5.260E-13
 CORRELATION MATRIX (CUT) TRANSPOSE
 4.995E-06 2.028E-10 4.410E-10 -1.147E-05 -1.829E-12 -3.880E-13 -2.295E-09 -2.194E-09 1.389E-10 -2.850E-11 6.562E-14 -4.483E-14
 -2.490E-05 -4.975E-10 1.193E-09 -1.227E-05 3.186E-12 2.518E-12 -1.873E-07 -3.660E-08 -1.066E-08 -2.112E-11 -1.392E-13 -2.952E-13

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT.RES1	WGT.RES2	WGT.RES3	LOSS FCTN
15,	14,	13	1	73.000	1.80118E+01	5.97803E-06	2.24414E-05	9.00589E-01	1.99288E-01
12,	11,	10	1	73.000	2.29408E+01	7.82160E-06	2.24174E-05	1.14704E+00	2.60720E-01
9,	8,	7	1	72.000	2.79360E+01	1.05855E-05	2.10403E-05	1.39680E+00	3.52849E-01
6,	5,	4	1	71.000	3.28470E+01	1.44720E-05	1.81588E-05	1.64235E+00	4.82400E-01
3,	2,	1	1	70.000	3.75168E+01	1.96710E-05	1.36433E-05	1.87584E+00	6.55699E-01

TIME 7.00000000E+01
 (V(R)) 1.593297314E+04 G(R)-5.12193481E+00 L(R) 6.33688559E+01 ALT 1.01564920E+05 LAT 1.67368207E+01 LON 2.80410136E+01
 U(R) 7.11637590E+03 V(R) 1.566060403E+04 W(R) 1.42302923E+03 PSI 7.50264993E+01 THE 1.52554851E+01 PHI 2.30996772E+01
 U(R) 1.46226266E+04 V(R) -8.07034828E+02 W(R) 6.28458815E+03 SIG 2.26472466E+01 BET -2.90214852E+00 ALF 2.32521428E+01
 XP 0. -8.75453184E-04 YP 0. -8.82155972E-04 AX -1.21334273E+02 AY 2.18520195E+01 AZ -1.70094573E+02
 PW -8.75453184E-04 Q 6.00554706E-03 R 8.82155972E-04 CX -1.62260392E+01 CY 2.92227180E-02 CZ -2.27467569E+01
 DP 3.78412315E+03 OM 6.04491552E-03 RH 8.82155972E-04 CX -1.62260392E+01 CY 2.92227180E-02 CZ -2.27467569E+01
 EP 7.86457630E-01 EI 7.82195103E-02 E2 2.24000367E-01 E3 5.70254276E-01 LATC 1.66305368E+01 RE 2.24965894E+07
 UW 0.
 S(1) 8.670433E+00 S(2) 1.920709E-04 S(3) 3.083126E-04 S(4) 1.431983E+01 S(5) 2.099586E-06 S(6) 1.207621E-06
 S(7) 2.490332E-02 S(8) 1.144140E-02 S(9) 2.606191E-03 S(46) 0.
 S(104) 7.252491E-07
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY
 7.618E+01
 -2.820E-04 3.315E-08
 -1.568E-03 -3.792E-08 9.506E-08
 -4.768E+01 -2.095E-03 2.421E-03 2.051E+02
 -1.522E-05 -2.198E-10 5.204E-10 1.826E-05 4.408E-12
 -9.391E-06 -5.010E-11 1.554E-10 6.848E-06 1.993E-12 1.458E-12
 1.752E-01 0. -2.241E-01 -4.997E-08 -2.474E-08 6.202E-04
 7.957E-02 1.000E-06 0. -9.609E-02 -2.205E-08 -1.158E-04 2.805E-04
 2.153E-02 4.123E-08 -4.245E-07 -1.194E-02 -4.138E-09 -2.483E-09 4.870E-05 6.792E-06
 9.504E-09 9.401E-09 -6.632E-05 -6.632E-05 8.421E-11 6.859E-11 -8.640E-07 -4.181E-07 -3.428E-07 0.
 -1.015E-11 5.171E-13 -8.492E-09 -8.492E-09 -8.473E-14 -1.517E-14 8.791E-10 8.666E-10 1.224E-12 0.
 5.360E-12 3.451E-11 1.366E-07 1.366E-07 1.354E-13 1.806E-14 -1.375E-09 -6.521E-10 -2.624E-10 0.
 0. 5.260E-13
 CORRELATION MATRIX (CUT) TRANSPOSE
 7.232E-06 1.219E-10 -5.978E-10 -2.221E-05 -4.136E-12 -9.635E-13 -4.787E-08 -2.289E-08 -2.011E-09 -2.850E-11 6.562E-14 -4.483E-14
 6.720E-05 -2.872E-09 7.083E-09 9.597E-05 2.080E-11 6.148E-12 -2.071E-07 9.780E-09 -1.318E-08 -2.112E-11 -1.352E-13 -2.952E-13

b. STEP2 output:

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	1																																																																																								

CONTROLS ARE SPECIFIED FOR

*FILTERING RUN FROM TIME 10= 70.0000 TO FINAL= 90.0000
 *UPDATED REFERENCE
 *SMOOTH COVARIANCE, CALCULATE RESIDUALS AND LOSS FUNCTION
 *FILTER FOR 1 ITERATIONS
 *VECTOR PROCESS FITTING DATA TRIPLES
 *INPUT AND OUTPUT IN ENGLISH UNITS (FT, FT/SEC, FT/SEC², LR, SLUG)
 *PLANET PARAMETERS

EQUIT, RAD. = 2.09264300E+07 POLAR RAD. = 2.08559700E+07 ROTATION = 7.29211500E-05
 MU(GRAV.) = 1.40769000E+16 J2(GRAV.) = 1.09205500E-03

*INITIAL STATE ESTIMATE IS
 VELOCITY = 1.60012000E+04 GAMMA = -6.75088000E+00 LAMBDA = 6.30352000E+01
 ALTITUDE = 1.00584000E+05 GEOD. LAT. = 1.67583977E+01 LONGITUDE = 2.80418380E+01
 SIGNA = 2.98270000E+01 BETA = -6.43200000E+00 ALPHA = 1.93930000E+01

*FITTING DATA IS FROM 2 SOURCES
 1. TRACKING STATION 1, GEOD. LAT. = 15.096904 LONGITUDE = 27.000000 ALTITUDE = 0. ABOVE REF. SURFACE
 2. TRACKING STATION 2, GEOD. LAT. = 16.605545 LONGITUDE = 31.000000 ALTITUDE = 0. ABOVE REF. SURFACE

STATE VECTOR COMPONENTS

COMP.	ID, NU.	EST. VALUE	VARIANCE
1	1	7.20532863E+03	6.79079215E+04
2	2	1.56313582E+04	2.80981835E+04
3	3	1.88098346E+03	3.09451057E+05
4	4	9.4712173E+04	1.00000000E+06
5	5	2.90632098E-01	9.00000000E+08
6	6	4.89422401E-01	9.00000000E+08
7	7	7.69645202E-01	2.08169635E-04
8	8	1.55940474E-01	7.90725687E-04
9	9	2.9872405E-01	8.18646927E-04
10	10	5.82889025E-01	2.80457751E-04

MODEL PARAMETERS IN EXPANDED STATE VECTOR
 11 72 9.22000000E-02 4.00000000E-02
 12 103 2.87979327E-01 1.40625000E-07
 13 104 5.41052068E-01 1.40625000E-07
 RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U, VECTOR)
 1 70 0.
 2 71 0.
 RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V, VECTOR)
 1 76 1.00000000E+00 9.00000000E-10
 2 81 0.

6.880E-03 8.919E-07

TIME	9.40000000E+01	G(A)	2.09463743E+00	L(A)	6.84176801F+01	ALI	9.33074086E+04	LATD	1.70497522E+01	LON	2.87621416E+01						
V(VA)	1.19157450E+04	W(I)	1.25775287E+04	W(1)	-4.37046954E+02	PSI	8.42001745E+01	THE	2.12640452E+01	PHI	3.17535866E+01						
V(VB)	-1.39546143E+02	V(B)	-7.832488PHE-02	W(H)	4.91016861E+03	SIG	2.93025729E+01	BET	-3.75583042E+00	ALF	2.43003910E+01						
X(P)	0.	Z(P)	0.	A(X)	9.56333303E-04	V(I)	1.333030158E+04	XZI	-9.06344558E+00	ETA	2.257899369E+01						
XP	-1.40626441E-03	Q	6.75272832E-03	R	9.56333303E-04	AXM	-1.04580147E+02	AY	6.53780171E+00	AZ	-1.55212352E+02						
PM	-1.40626441E-03	QM	6.75272832E-03	RM	9.56333303E-04	AXM	-1.04580147E+02	AYM	6.53780171E+00	AZM	-1.55233524E+02						
E0	7.35257112E+01	E1	8.05213741E-02	E2	3.11932281E-01	E3	5.96333154E-01	LATC	1.69417167E+01	A(T)	3.45543794E-05						
C72	1.11171555E+01	C103	2.87979338E-01	C104	5.41051991E-01	C											
S(1)	1.3427940E+00	S(2)	4.405705E-04	S(3)	4.786468E-04	S(4)	2.645112E+01	S(5)	1.8734405E-06	S(6)	1.56797973E-06						
S(5)	7.3382445E-02	S(8)	2.574473E-02	S(9)	2.149743F-03	S(72)	1.864880E-01	S(103)	1.256231E-06	S(104)	1.053415E-02						
COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)																	
1.175E+01																	
7.711E-04	1.941E-07																
-2.8908E-05	-8.050E-08	2.291E-07															
4.116E-01	1.026E-02	2.961E-03	6.997E+02														
1.159E-06	2.047E-10	-6.412E-10	9.267E-06	3.510E-12													
3.654E-06	1.082E-10	2.422E-10	6.748E-06	3.733E-13	2.459E-12												
1.192E-02	0.	0.	2.007E-01	1.147E-09	2.208E-09	1.144E-03											
1.1290E-02	-5.849E-06	0.	-1.846E-01	1.155E-08	2.235E-09	-8.659E-04	6.628E-04										

-4.745E-03-6.142E-07-2.540E-02 4.085E-10-1.378E-09 5.473E-07 3.086E-07 4.621E-06
 -1.58E-05-1.181E-05-7.795E-01 7.795E-01 5.381E-08 3.860E-08 1.832E-05-2.902E-05-5.675E-05 3.478E-02
 1.355E-11-1.512E-10 6.381E-07 8.381E-07 1.814E-12 6.424E-13-1.090E-09 1.734E-10 1.668E-10 7.181E-09 1.578E-12
 1.824E-11 2.130E-11 7.001E-07 7.001E-07 7.260E-13 1.272E-12 6.699E-10-5.276E-10-1.169E-10 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CZV) TRANSPOSE
 1.893E-01-8.256E-06-6.230E-06-4.765E-01 3.629E-08 2.995E-08 1.060E-05-1.587E-05 1.538E-04-3.626E-03 5.135E-09 5.637E-10
 -1.261E-02-1.050E-05 3.212E-06-7.048E-03-5.088E-09-7.642E-10-1.398E-04-9.437E-05-7.736E-06 2.243E-04-2.337E-10-7.590E-11
 CORRELATION MATRIX (CZV) TRANSPOSE
 -3.465E-07 8.337E-10 3.936E-10 3.483E-05-2.998E-11-2.303E-11 7.758E-09-6.153E-09-5.492E-09 1.741E-07-2.849E-11-2.269E-11
 1.140E-05 2.659E-09-6.078E-10 4.663E-05 5.757E-12 4.779E-12 2.500E-08-2.848E-08-9.757E-09-2.340E-07 3.657E-12 3.338E-12

*****BEGIN BACKWARDS SMOOTHING*****

TIME 9.00000000E+01
 V(A) 1.19574508E+04 G(A) 2.09463749E+00 L(A) 6.84176801E+01 ALT 9.33074086E+04 LATD 1.70497522E+01 LON 2.87621416E+01
 U(I) 4.39546193E+03 V(I) 1.25775287E+04 W(I) 4.37046954E+02 PSI 8.42001745E+01 THE 2.12640452E+01 PHI 3.17535862E+01
 U(B) 1.08746202E+04 V(B) 7.89326880E+02 W(B) 4.91016861E+03 SIG 2.93025729E+01 BET -3.75583042E+00 ALF 2.43003910E+01
 XP 0.0 ZP 0.0
 P -1.40826441E-03 Q 6.75272832E-03 R 9.56333835E-04 AX -1.04586147E+02 AY 6.53780171E+00 AZ -1.55212332E+02
 PM -1.40826441E-03 QM 6.75272832E-03 RM 9.56333835E-04 AXM -1.04586147E+02 AYM 6.53780171E+00 AZM -1.55212332E+02
 EO 7.35257134E-01 EI 8.03213741E-02 E2 3.11922621E-01 E3 5.98331343E-01 LATC 1.69417167E+01 A(T) 3.45543794E-05
 S(1) 3.3279480E+00 S(2) 4.405705E-04 S(3) 4.786468E-04 S(4) 2.645112E-01 S(5) 1.873405E-06 S(6) 1.567973E-09
 S(7) 3.382445E-02 S(8) 2.574473E-02 S(9) 2.149743E-03 S(12) 1.864880E-01 S(103) 1.256231E-06 S(104) 1.053415E-06
 COVARIANCE MATRIX P (FLOWER TRIANGLE ONLY)
 1.175E+01
 7.711E-04 1.941E-07
 -2.1908E-03-8.050E-08 2.291E-07
 4.116E+01 1.026E-02-2.961E-03 6.997E+02
 1.359E-06 2.047E-10-6.412E-10 9.267E-06 3.510E-12
 3.654E-06 1.082E-10 2.422E-10 6.749E-06 3.733E-13 2.459E-12
 1.799E-02 0.0
 -1.520E-02-5.848E-06 0.0
 -4.745E-03-6.142E-07-2.540E-02 4.085E-10-1.378E-09 5.473E-07 3.086E-07 4.621E-06
 -1.584E-05-1.181E-05-7.795E-01 7.795E-01 5.381E-08 3.860E-08 1.832E-05-2.902E-05-5.675E-05 3.478E-02
 1.355E-11-1.512E-10 6.381E-07 8.381E-07 1.814E-12 6.424E-13-1.090E-09 1.734E-10 1.668E-10 7.181E-09 1.578E-12
 1.824E-11 2.130E-11 7.001E-07 7.001E-07 7.260E-13 1.272E-12 6.699E-10-5.276E-10-1.169E-10 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CZV) TRANSPOSE
 1.893E-01-8.256E-06-6.230E-06-4.765E-01 3.629E-08 2.995E-08 1.060E-05-1.587E-05 1.538E-04-3.626E-03 5.135E-09 5.637E-10
 -1.261E-02-1.050E-05 3.212E-06-7.048E-03-5.088E-09-7.642E-10-1.398E-04-9.437E-05-7.736E-06 2.243E-04-2.337E-10-7.590E-11
 CORRELATION MATRIX (CZV) TRANSPOSE
 -3.465E-07 8.337E-10 3.936E-10 3.483E-05-2.998E-11-2.303E-11 7.758E-09-6.153E-09-5.492E-09 1.741E-07-2.849E-11-2.269E-11
 1.140E-05 2.659E-09-6.078E-10 4.663E-05 5.757E-12 4.779E-12 2.500E-08-2.848E-08-9.757E-09-2.340E-07 3.657E-12 3.338E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	MGT.RES1	MGT.RES2	MGT.RES3	LOSS FCIN
57,	56,	55	2	88.000	-1.37444E+00	3.15725E-06	8.48743E-06	-6.87221E-02	1.05242E-01
54,	53,	52	2	86.000	-9.38659E-01	-1.61044E+06	7.76388E-07	-4.69329E-02	-5.36814E-02

TIME 8.50000000E+01
 V(A) 1.28475913E+04 G(A) 3.77934747E-01 L(A) 6.71955446E+01 ALT 9.19084577E+04 LATD 1.69856348E+01 LON 2.85987338E+01
 U(I) 4.97945246E+03 V(I) 1.33093224E+04 W(I) 8.4747400E+01 PSI 8.29846784E+01 THE 1.94174709E+01 PHI 3.15896606E+01
 U(B) 1.17046872E+04 V(B) 8.08359670E+02 W(B) 5.23551242E+03 SIG 2.99442913E+01 BET -3.60734503E+00 ALF 2.4077755E+01
 XP 0.0 ZP 0.0
 P -1.27096643E-03 Q 8.01514722E-03 R 9.96728523E-04 AX -1.28517050E+02 AY 8.02340547E+00 AZ -1.88680099E+02
 PM -1.27096643E-03 QM 8.01514722E-03 RM 9.96728523E-04 AXM -1.28517050E+02 AYM 8.02340547E+00 AZM -1.88791271E+02

1.526E-06 5.743E-10 1.846E-12 1.561E-04 3.084E-12 2.495E-12 2.710E-08 2.513E-08 7.683E-09 2.340E-07 3.657E-12 3.338E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT.RES1	WGT.RES2	WGT.RES3	LOSS FCIN	
33.	32.	31	79.000	-1.35924E+00	-2.74801E-06	-2.45315E-06	-6.79622E-02	-9.16004E-02	-8.17716E-02	3.28855E-01
30.	29.	28	78.000	1.35550E-02	1.06557E-06	-1.30329E-06	6.77751E-04	3.55524E-02	-4.34429E-02	3.32007E-01
27.	26.	25	78.000	-1.15783E-01	-2.51061E-06	-1.49191E-06	-5.77751E-04	-8.36871E-02	-4.97303E-02	3.41517E-01
24.	23.	22	77.000	1.17701E+00	-1.59556E-06	-4.49689E-07	5.88505E-02	-5.65187E-02	-1.49896E-02	3.48399E-01
21.	20.	19	76.000	2.41976E+00	-1.55493E-07	5.67658E-07	1.50988E-01	-5.18309E-03	1.89219E-02	3.63422E-01
18.	17.	16	75.000	3.51146E+00	2.25499E-06	1.45315E-06	1.75573E-01	7.51564E-02	4.84383E-02	4.02243E-01

TIME 7.50000000E+01
 V(A) 1.49641593E+04 G(A) -3.50509731E+00 L(A) 6.45148380E+01 ALI 9.5731473E+04 LATD 1.68297096E+01 LON 2.82380534E+01
 U(I) 6.42669410E+03 V(I) 1.49505475E+04 W(I) 9.14868865E+02 PSI 7.94330945E+01 THE 1.52710050E+01 PHI 3.11967081E+01
 U(B) 1.36818354E+04 V(B) -8.64092941E+02 W(B) 5.99889883E+03 SIG 3.03316550E+01 BET -3.31033857E+00 ALF 2.36753928E+01
 X P C -9.42614978E-04 Q 7.73459373E-03 R 9.82154065E-04 AX -1.42491786E-02 AY 8.87341895E+00 AZ -2.04628262E+02
 P M -9.42614978E-04 Q 7.73459373E-03 R 9.82154065E-04 AX -1.42491786E-02 AY 8.87341895E+00 AZ -2.04628262E+02
 E O 7.57120270E-01 E1 1.23214203E-01 E2 2.68743155E-01 E3 5.82549803E-01 LATC 1.67229044E+01 A(T) 5.56835862E+06
 S (1) 1.630148E+00 S (2) 1.360471E+04 S (3) 1.493390E-04 S (4) 1.528436E+01 S (5) 9.632247E-07 S (6) 7.644826E-07
 S (7) 3.640269E-02 S (8) 2.149621E-02 S (9) 2.000494E-03 S (10) 1.864880E-01 S (11) 1.2566231E-06 S (12) 1.053415E-09
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 2.657E+00
 2.585E+05 1.851E-08
 4.225E-05 3.703E-09 2.230E-08
 2.770E-05 6.414E-04 1.998E-04 2.336E+02
 3.008E-07 6.374E-12 2.161E-11 1.349E-06 9.667E-13
 1.675E-07 9.013E-12 5.549E-12 1.443E-07 5.513E-13 5.844E-13
 3.221E-03 0. 1.276E-01 9.515E-09 9.78E-09 1.325E-03
 -2.020E-03 9.360E-07 0. -6.806E-02 5.465E-09 2.875E-09 7.78E-04 4.621E-04
 1.021E-03 6.536E-08 1.226E-07 1.131E-02 3.110E-10 8.321E-11 3.315E-05 -1.911E-05 4.002E-06
 2.732E-06 9.941E-07 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01 2.125E-01
 -5.428E-12 2.958E-11 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07 1.198E-07
 3.572E-12 2.699E-11 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07 2.939E-07
 CORRELATION MATRIX (CZ) TRANSPOSE
 -6.479E-02 1.459E-06 2.200E-07 1.955E-01 -5.997E-09 1.673E-09 8.471E-06 1.260E-05 1.423E-04 3.626E-03 5.135E-09 5.637E-10
 3.214E-03 -2.157E-07 2.667E-08 9.467E-03 6.524E-11 3.389E-10 1.283E-04 1.112E-04 6.920E-06 2.243E-04 2.337E-10 7.590E-11
 CORRELATION MATRIX (CZ) TRANSPOSE
 -1.054E-05 -7.400E-11 -1.270E-11 -3.639E-05 -2.663E-11 -2.005E-11 8.531E-09 -5.223E-09 -4.287E-09 1.741E-07 -2.849E-11 -2.269E-11
 -3.120E-06 -2.045E-10 1.412E-10 1.659E-04 3.419E-12 2.534E-12 2.809E-08 -2.358E-08 -6.789E-09 -2.340E-07 3.657E-12 3.338E-12

POINTS	TYPE	TIME	RES1	RES2	RES3	WGT.RES1	WGT.RES2	WGT.RES3	LOSS FCIN	
15.	14.	13	74.000	4.35127E+00	5.67465E-06	2.10114E-06	2.17563E-01	1.89155E-01	7.00378E-02	4.90262E-01
12.	11.	10	73.000	4.44013E+00	1.02355E-05	2.40975E-06	2.42008E-01	3.41186E-01	8.03250E-02	6.71689E-01
9.	8.	7	72.000	4.88237E+00	1.60575E-05	2.28321E-06	2.44118E-01	5.35251E-01	7.61072E-02	1.02357E+00
6.	5.	4	71.000	4.38496E+00	2.34717E-05	1.63398E-06	2.19348E-01	7.74903E-01	5.44660E-02	1.67512E+00
3.	2.	1	70.000	3.26856E+00	3.18956E-05	3.84540E-07	1.63428E-01	1.06319E+00	1.28180E-02	2.83236E+00

TIME 7.00000000E+01
 V(A) 1.59437078E+04 G(A) -5.12693675E+00 L(A) 6.33489928E+01 ALI 1.01550176E+05 LATD 1.67367329E+01 LON 2.80409860E+01
 U(I) 7.12301019E+03 V(I) 1.56616007E+04 W(I) 1.42477056E+03 PSI 7.80639211E+01 THE 1.34842332E+01 PHI 3.10808113E+01
 U(B) 1.46034724E+04 V(B) -8.49045016E+02 W(B) 6.33620712E+03 SIG 3.06531017E+01 BET -3.20159537E+00 ALF 2.34552310E+01
 X P C -8.75453186E-04 Q 6.04491552E-03 R 8.82155972E-04 AX -1.22842135E-02 AY 7.99954935E+00 AZ 2.18663951E+01
 P M -8.75453186E-04 Q 6.04491552E-03 R 8.82155972E-04 AX -1.22842135E-02 AY 7.99954935E+00 AZ 2.18663951E+01
 E O 7.63029219E-01 E1 1.35447333E-01 E2 2.13544733E-01 E3 5.78102211E-01 LATC 1.6630495E+00 AZ -1.72094754E+02
 S (1) 2.4494760E+00 S (2) 2.200619E-04 S (3) 2.084414E+01 S (4) 2.084414E+01 S (5) 1.1276101E-06 S (6) 9.169253E-05

S(7) 3.705445E-02 S(8) 2.045858E-02 S(9) 2.027214E-03 S(72) 1.864880E-01 S(103) 1.256231E-06 S(104) 1.053415E-06
 COVARIANCE MATRIX P (LOWER TRIANGLE ONLY)
 6.224E+00
 2.052E-04 4.843E-08
 1.246E-04 3.287E-09 4.344E-08
 -1.392E+00 -2.487E-03 1.391E-04 4.345E+02
 3.009E-07 -2.478E-12 1.023E-10 2.265E-06 1.272E-12
 -1.070E-06 -3.376E-11 -6.918E-11 1.880E-08 3.152E-13 8.408E-13
 1.430E-02 0. 0. 1.474E-01 1.537E-08 -1.021E-08 1.373E-03
 -7.694E-03 -5.232E-07 0. -8.602E-02 -8.993E-09 5.845E-09 -7.545E-04 4.186E-04
 2.652E-03 2.683E-07 1.240E-07 -1.635E-04 6.000E-10 -6.374E-10 4.139E-05 -2.244E-05 4.110E-06
 7.224E-06 3.973E-06 -2.161E-01 -2.161E-01 9.337E-09 1.237E-08 2.228E-05 -2.489E-05 -8.364E-05 3.478E-02
 -1.392E-11 4.267E-12 8.624E-07 8.624E-07 7.893E-13 5.187E-13 -1.126E-09 1.696E-10 8.951E-11 7.181E-09 1.578E-12
 -6.656E-12 1.994E-11 3.973E-07 3.973E-07 6.768E-13 3.662E-13 7.405E-10 -4.197E-10 -7.313E-11 9.155E-10 7.171E-13 1.110E-12
 CORRELATION MATRIX (CV2)TRANSPOSE
 -1.552E-01 3.648E-06 1.631E-06 -5.451E-02 8.401E-09 2.337E-08 7.690E-06 -1.192E-05 1.397E-04 -3.626E-03 5.135E-09 5.637E-10
 8.265E-03 -6.898E-08 -6.970E-07 1.013E-02 -1.180E-09 -5.081E-10 -1.247E-04 -1.158E-04 -6.755E-06 2.243E-04 -2.337E-10 -7.590E-11
 CORRELATION MATRIX (CV2)TRANSPOSE
 -1.349E-05 -2.700E-10 -1.583E-10 -2.713E-05 -2.564E-11 -1.714E-11 8.744E-09 -4.992E-09 -3.983E-09 1.741E-07 -2.849E-11 -2.269E-11
 -7.098E-06 -8.871E-10 1.734E-10 -1.217E-04 4.577E-12 3.561E-12 2.888E-08 -2.238E-08 -6.055E-09 -2.340E-07 3.657E-12 3.338E-12

III. PROGRAM CHECKOUT AND VALIDATION

STEP checkout consisted of four separate phases -- checking the nonlinear differential equations of motion; checking the linear equations of motion; checking the measurement equations; and checking the overall system operation. Before preceding with the checkout, a check trajectory was synthesized and PQR and FIT tapes generated using a separate trajectory program. In the following discussion, the check trajectory is described and the results of the various checkout phases discussed.

A. Check Trajectory

The check trajectory corresponded to the flight of a maneuverable lifting reentry vehicle, having a hypersonic L/D of approximately 0.6. The vehicle had the following physical characteristics:

Mass versus time (linear)

m, slugs	25.5763	24.8013	24.0262
t, sec	0.0	200.0	400.0

Reference area, $S = 5.0 \text{ ft}^2$.

The aerodynamic characteristics correspond to an axisymmetric vehicle where

$$C_{N_{\eta}} = N_1(M) \sin [\eta + N_2(M)] + N_3(M)$$

$$C_{Y_{\eta}} = 0$$

$$C_A = A_1(M) \cos [\eta + A_2(M)] + A_3(M)$$

The coefficients $N_1(M)$, $N_2(M)$, $N_3(M)$, $A_1(M)$, $A_2(M)$, and $A_3(M)$ are characterized by the following second-degree polynomials:

$$N_1(M) = \begin{aligned} &1.5900 + 0.0300M - 0.4200M^2 \quad (0 \leq M \leq .8) \\ &2.5879 - 2.4649M + 1.1393M^2 \quad (0.8 < M < 1.2) \\ &0.9058 + 0.3386M - 0.0288M^2 \quad (1.2 \leq M \leq 5.874) \end{aligned}$$

$$N_2(M) = \begin{aligned} &-71.500 - 2.500M + 27.000M^2 \quad (0 \leq M \leq 0.8) \\ &-132.98 + 151.21M - 69.068M^2 \quad (0.8 < M < 1.2) \\ &-31.285 - 18.289M + 1.5561M^2 \quad (1.2 \leq M \leq 5.877) \end{aligned}$$

$$N_3(M) = \begin{aligned} &1.5100 + 0.0100M - 0.5800M^2 \quad (0 \leq M \leq 0.8) \\ &2.8984 - 3.4611M + 1.5894M^2 \quad (0.8 < M < 1.2) \\ &0.5577 + 0.4401M - 0.0361M^2 \quad (1.2 \leq M \leq 6.101) \end{aligned}$$

$$A_1(M) = \begin{aligned} &0.3450 + 0.1250M - 0.4700M^2 \quad (0 \leq M \leq 0.8) \\ &1.2228 - 2.0695M + 0.9016M^2 \quad (0.8 < M < 1.2) \\ &-0.0885 + 0.1161M - 0.0091M^2 \quad (1.2 \leq M \leq 6.368) \end{aligned}$$

$$A_2(M) = \begin{aligned} &-50.000 + 22.000M + 28.000M^2 \quad (0 \leq M \leq 0.8) \\ &-143.64 + 256.11M - 118.32M^2 \quad (0.8 < M < 1.2) \\ &30.823 - 34.668M + 2.8385M^2 \quad (1.2 \leq M \leq 6.107) \end{aligned}$$

$$A_3(M) = \begin{aligned} &-0.1300 + 0.0100M + 0.3200M^2 \quad (0 \leq M \leq 0.8) \\ &-0.8065 + 1.7013M - 0.7371M^2 \quad (0.8 < M < 1.2) \\ &0.2637 - 0.0823M + 0.0061M^2 \quad (1.2 \leq M \leq 6.722) \end{aligned}$$

Above the upper Mach number limit in the above inequalities the coefficients are constant. C_A and C_{N_η} are then transformed to C_A , C_Y , and C_N or C_D , C_Y , and C_L versus α and β . A plot of C_L , C_D , and C_Y is presented in figure 2 for Mach number 0., 1.0, 2.5, and 7.0.

The check trajectory has the following initial conditions at $t = 0$.

$$V_R = 18\,000.0 \text{ fps}, \quad \gamma_R = -6.0^\circ, \quad \lambda_R = 30.0^\circ$$

$$h_0 = 250\,000.0 \text{ ft}, \quad \varphi_D = 15.0^\circ, \quad \theta = 25.0^\circ$$

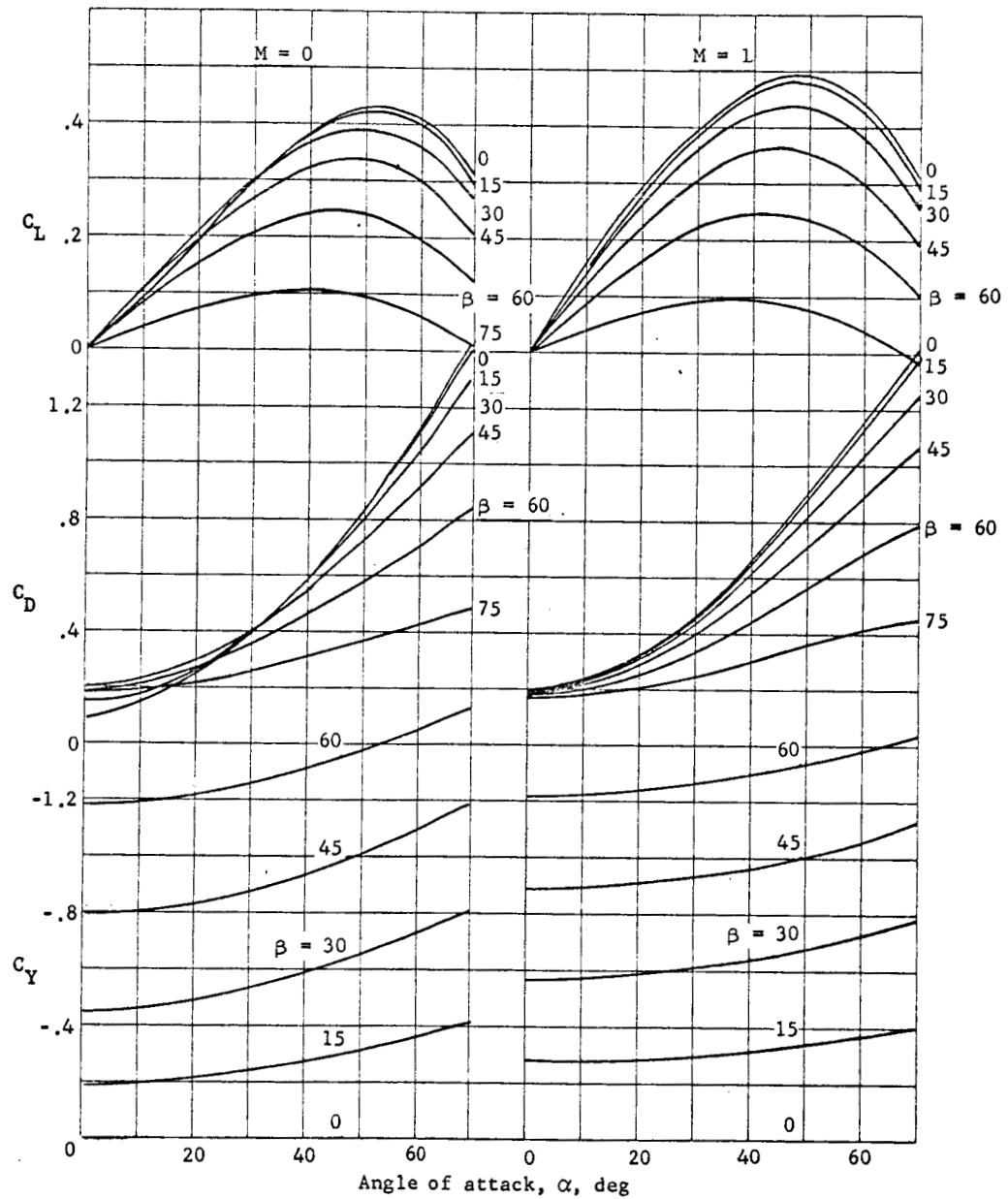


Figure 2.- Aerodynamic Coefficients of Checkout Vehicle

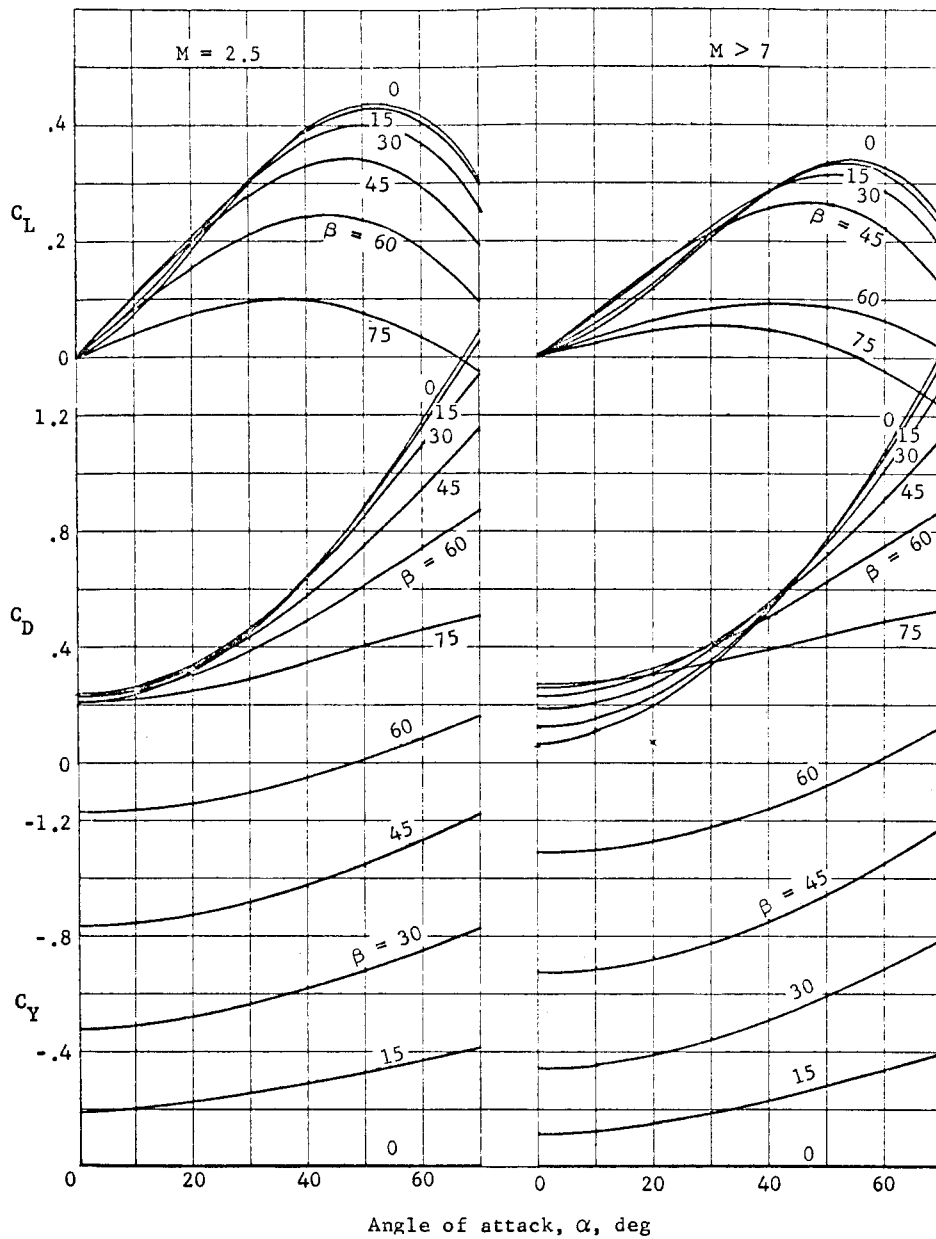
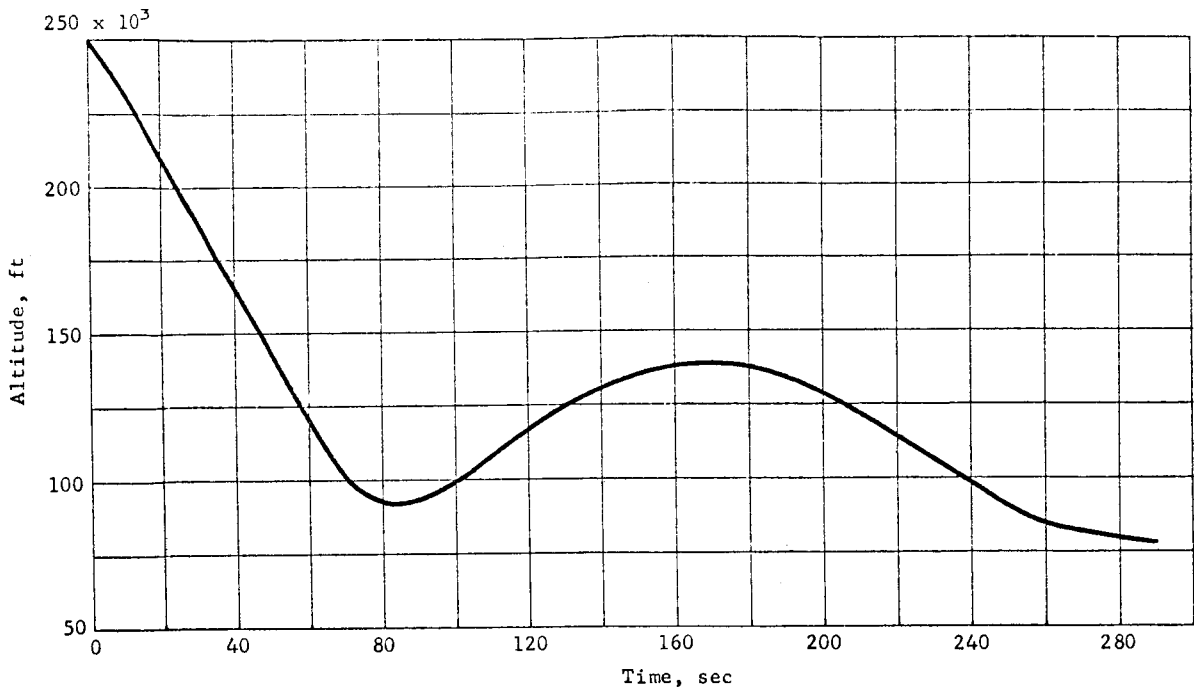


Figure 2.- Concluded

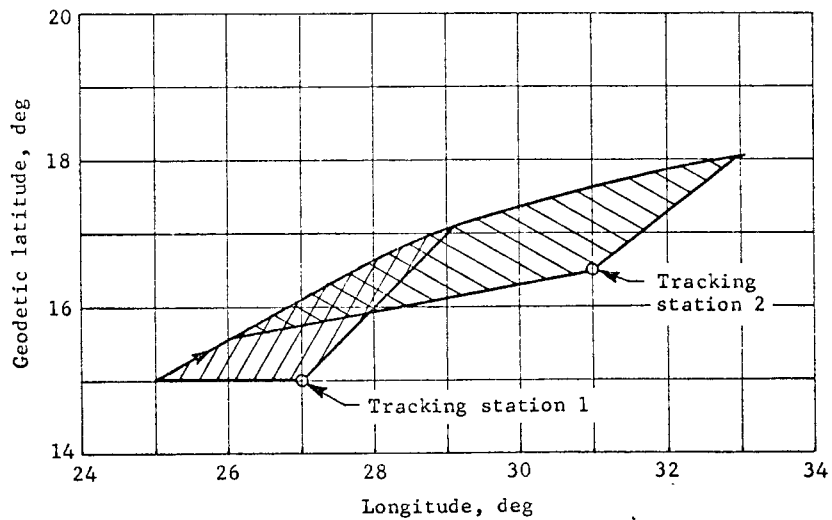
The angle of attack, α , sideslip angle, β , and roll angle, σ , varied linearly with time as follows:

<u>t, sec</u>	<u>0</u>	<u>200.0</u>	<u>400.0</u>
α , deg	20.0	30.0	40.0
β , deg	-1.0	-1.0	-1.0
σ , deg	30.0	20.0	10.0

The altitude versus time and latitude versus longitude are presented in figures 3(a) and 3(b). The PQR tape generated for the check trajectory contained data every 0.25 sec. Tracking stations were located at latitudes and longitudes of 15.0, 27.0 and 16.5, 31.0. The tracking spans, during which time the evaluation angle is larger than 4° is shown in figure 3(b). The tracking data were stored on the FIT tape at a rate of two points per second.



(a) Altitude vs Time



(b) Latitude vs Longitude

Figure 3.- Checkout Trajectory

B. Checkout of Nonlinear Equations of Motion

To check the nonlinear equations of motion, the inertial angular rates (and accelerometers for STEP2) were integrated from $t = 0$ to $t = 250.0$ sec with a computing interval of 0.5 sec. The state time history was then compared with the known check trajectory and agreement to at least six significant digits was obtained. This accuracy is, no doubt, limited by the 0.25-sec interval of the PQR tape data. Several 50-sec problems were solved using different computing intervals for the numerical integration. These results are tabulated below.

	V	h	α	β
Check	17 791.5507	141 872.977	22.5000000	-1.00000000
STEP2 ($\Delta t = 0.25$)	17 791.5337	141 873.085	22.4999995	-1.00000006
STEP2 ($\Delta t = 0.50$)	17 791.5515	141 872.975	22.5000000	-1.00000001
STEP2 ($\Delta t = 5.0$)	17 791.4553	141 873.334	22.5000023	- .99999864

A rather interesting result is exhibited in the above comparison. As the computing interval gets large, errors are introduced as a result of truncation. As the computing interval is reduced, errors are reduced until the computing interval becomes smaller than twice the PQR tape data interval (0.25 sec for this check problem). At this point, the PQR tape requires interpolation. The linear interpolation introduces errors because the data are not linear. Normally, a computing interval twice the PQR tape data interval is most satisfactory because each PQR tape data point is then used in the fourth-order Runge Kutta integration and interpolation is not required. For very nonlinear problems where the threshold for truncation error forces the computing interval to be smaller than the PQR tape data interval, one must either live with the error or increase the frequency at which the PQR tape data are recorded.

C. Checkout of Linear Equations of Motion

The checkout of the linear equations of motion is a very cumbersome task. The solution to the linear equations of motion is the state transition matrix for the expanded state vector. Because any of the model parameters can potentially be components

of the expanded state vector, it is necessary to check a vector solution for each state and model parameter or equivalently, a 9x160 matrix.

The elements of the state transition matrix are partial derivatives of the expanded state vector, Z , at time t_1 with respect to Z components at t_0 . Therefore, the elements can be checked by approximating the partial derivatives by finite differences. This is done by generating a reference nonlinear solution between t_0 and t_1 . A perturbed nonlinear solution is next calculated wherein Z_i , the i^{th} component of Z , is perturbed from the nominal at t_0 . The response of the state variables at t_1 divided by the perturbation in Z_i , which caused them provides a one-sided finite difference approximation to the partial derivative

$$\frac{\Delta Z(t_1)}{\Delta Z_i(t_0)} \approx \frac{\partial Z(t_1)}{\partial Z_i(t_0)}$$

The programs were checked by calculating two-sided finite difference approximations to the state transition matrix. The variable Z_i was perturbed first by $+\Delta Z_i$ then by $-\Delta Z_i$. The difference between the + and - responses in Z at t_1 , divided by $2\Delta Z_i$ yield the desired finite difference approximation.

All state variables and model parameters were perturbed in this manner. A checkout subroutine was mechanized into the STEP decks to do the bookkeeping. It controlled the variable perturbations, recorded the responses, performed the differencing, and printed the finite difference approximation along with its analytically calculated counterpart. The finite difference approximation required only that the nonlinear equations of motion be correct. Agreement with the state transition matrix elements calculated by integrating the linear equations of motion assured that the linear equations of motion were formulated correctly and were being solved correctly. In all cases, the finite difference approximation agreed with its analytical counterpart to at least six significant digits. When disagreement occurred during checkout, it was difficult to determine which coefficient in the linear differential equations was the cause. Therefore, finite difference approximations of the F matrix, equation (6a), were

simultaneously calculated by the check subroutines. Comparison of the finite difference approximation and its analytical counterpart immediately disclosed the erroneous coefficient.

D. Checkout of Measurement Equations

Checking the nonlinear measurement equations was accomplished by comparison with solutions known to be correct. The coefficients in the linear measurement equations, G in equation (4), were checked by comparing the analytically obtained partial derivatives with a finite difference approximation. This comparison study was performed simultaneously with the state transition matrix checkout and was automated by a checkout subroutine discussed previously.

E. Checkout of Input/Output Transformations

The transformations presented in Section VI of Volume I for transforming the input and output were checked by the finite difference approximation comparison technique. Agreement to better than six significant digits were obtained.

F. Checkout Complete STEP

Having assured that the nonlinear and linear state and measurement equations were being solved correctly, the matrix propagation and minimum variance estimation logic was next checked.

1. Matrix propagation.— Two 20-sec problems were solved using the error analysis operating mode. In the first problem, five model parameters were included in the expanded state vector, thus yielding a 15×15 covariance matrix P . In the second problem, three of the model parameters were removed from the expanded state vector Z and placed in the uncertain model parameter vector U . Thus, the second problem has a 12×12 covariance matrix P and a 12×3 correlation matrix CVZ . As indicated in equation (50) of Volume I, CUZ from the second problem should be a submatrix in the 15×15 covariance matrix, P , of the first problem, as indeed it was. Thus, this check confirmed that the covariance and correlation matrices P and CUZ were being propagated correctly.

The next check runs used the filtering mode of operation to test the minimum variance recursive updating equations, equations (53). In the first problem several tracking points from station 1 were processed with infinite variances. As expected, no change in the state variables occurred. In the second problem, tracking data from station 1 were processed with zero variances. The initial covariance matrix of state P was specified to be very large. While attempting to process the ninth tracking point, a variance element in P became negative causing the run to terminate. Because the dynamic model in STEP is a ninth-order system (nine independent first-order differential equations), after processing nine data points of absolute certainty (zero variance), the covariance matrix P should be zero if it is initially specified to be infinity. In the check problem, a finite initial covariance matrix P was specified. Therefore, processing the ninth tracking point produces the expected result of causing a variance of P to become slightly negative in attempting to seek zero.

In the next check runs, the smoothing option was tested. Operating in the error analysis mode with no tracking data, the covariance matrix was input using input/output option 1 and 2. The covariance matrix P was transformed to internal units, propagated forward in time for 20 sec, propagated back to initial time, and transformed back to the output variable of option 1 and 2. The state and covariance matrix at the completion of the run matched those inputted to better than eight significant digits.

The final series of tests checked the filtering mode of operation. Twenty-second problems were run, during which tracking data from stations 1 and 2 were discretely selected from the FIT tape and processed. The problems ran for as many as three iterations using both the updated and nonupdated references, and both vector and scalar data processing options. Typical of the convergence of these runs is the two iteration problems presented in table 2 for STEP2. The expanded state vector was randomly noised at initial time by an amount consistent with the initial covariance. The random noise was normally distributed with zero mean. Table 2 shows the correct state at initial time, the noised state at initial time and the converged state at initial time after two iterations. Also shown are the estimated standard deviations at initial time after the second iteration. Comparing these residuals with their calculated variances, 83% lie within one-sigma and 100% within two-sigma. Theoretically, 68.3% should be within one-sigma, 95.5% within two sigma, and 99.7% within three sigma.

TABLE 2.- THREE ITERATION PROBLEMS, STEP 2

Iter	V	γ	λ	h	ϕ	θ	σ	β	α
Nom	15 946.18	-5.13088	63.3697	101 549.4	16.736757	28.040927	26.50	-1.0000	23.5000
0	16 001.20	-6.75088	63.0352	100 584.0	16.758397	28.041838	29.8270	-4.4320	19.3930
1	15 943.70	-5.12694	63.3490	101 550.2	16.736733	28.040986	30.6531	-3.2016	23.4552
2	15 945.99	-5.12227	63.3601	101 547.5	16.736749	28.040935	30.2796	-3.0292	23.5244
Iter	δV	$\delta \gamma$	$\delta \lambda$	δh	$\delta \phi$	$\delta \theta$	$\delta \sigma$	$\delta \beta$	$\delta \alpha$
0	55.02	-1.6200	-.3345	-965.4	.02164	.00091	3.327	-3.432	-4.107
1	-2.48	.0039	-.0207	- .8	.00002	.00005	4.153	-2.202	- .045
2	-.19	.0086	-.0096	- 1.9	.00001	.00000	3.779	-2.029	.024
Est. σ	(2.52)	(.0135)	(.0128)	(20.59)	(.00006)	(.00005)	(2.254)	(1.210)	(.112)

IV. PROGRAM STRUCTURE AND LOGIC

STEP is completely coded in FORTRAN 2.0 using an executive structure wherein the MAIN program controls logic to and from the various subordinate subroutines. Each of the subroutines performs a specific logical task. Because of the versatility of the programs, the logic is somewhat complex. This is necessary to accommodate the numerous options described in the input section. STEP contains the following contractor-developed subroutines

<u>STEP1</u>	<u>STEP2</u>
MAIN (called ST1)	MAIN (called ST2)
AERO	DATAB
AEROIN	FXXU
ATMDAT	INDAT
CRV	INTAG
DATAB	MINVAR
DERIVE	MOTION
FUNCT	OBSERV
FXXU	OUTPUT
INDAT	PRESET
INTAG	PROP
MINVAR	RKUTTA
MOTION	SETUP
OBSERV	SMOOTH
OUTPUT	STAT
PRESET	TAB
PROP	
RKUTTA	
SETUP	
SMOOTH	
STAT	
TAB	

The subroutines common to STEP1 and STEP2 are nearly identical.

A. Overall Program Logic

The overall program logic for filtering, error analysis, and deterministic problems is described below with the aid of figure 4.

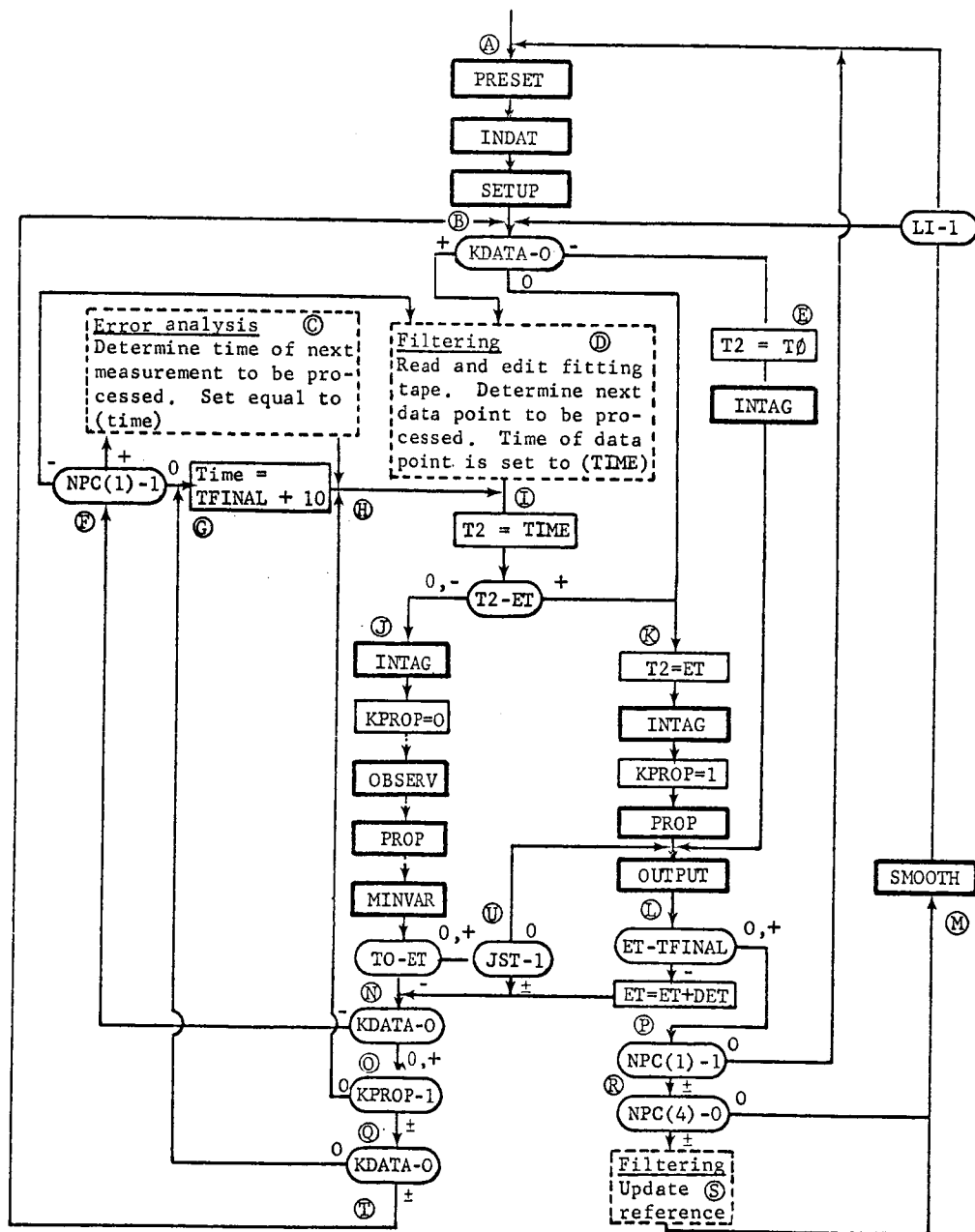


Figure 4.- Overall Program Logic

1. Filtering problems [$NPC(1) = 0$].- Referring to figure 4, the program commences at (A) by calling PRESET, INDAT, and SETUP. PRESET specifies values for variables and triggers. INDAT reads all input data from cards. SETUP performs all necessary calculations on the input data and controls in preparation for the processing that follows. In SETUP, the fixed point triggers KDATA and KPROP are set equal to -1, and T_0 is set equal to the initial problem time. From (B) the logic transfers to (E) where INTAG is called. INTAG always integrates the nonlinear and linear differential equations of motion from T_0 to T_2 to yield the nonlinear state at T_2 and the state transition matrix that relates variables between T_0 and T_2 . Obviously, when INTAG is called at (E), $T_0 = T_2$ so that the computation involves only an evaluation of the differential equations and auxiliary variables. The logic then proceeds to OUTPUT where the state variables and auxiliary parameters are block printed at the initial time. The time at which the block print occurs is called ET. Thus, after OUTPUT, ET is compared with final problem time TFINAL, at (L), and, because it is smaller, it is updated by the print interval DET. Logic then proceeds to (N) where KDATA is tested. Because it is negative, the logic transfers to (F) where $NPC(1)$ is tested. For filtering problems, $NPC(1)$ equals zero so the logic branches to (D) where the FIT tape is read and edited to determine the next data point to be processed. The time corresponding to the data point is called TIME. If more than one data point is to be processed at TIME, the trigger JST is set to 2, otherwise JST equals 1. At (I) T_2 is set equal to TIME and is then compared with the next block print time. If TIME is less than or equal to ET, the logic proceeds to (J) where, in INTAG, the nonlinear state and state transition matrix are calculated between T_0 and T_2 . After INTAG, T_0 is equated to T_2 (although not shown in fig. 4). OBSERV then calculates the nonlinear measurement variables and their partial derivatives with respect to the expanded state vector components. PROP next propagates the covariance and correlation matrices, P, CUZ, and CVZ to T_2 , and MINVAR performs the minimum variance update of the expanded state, its covariance, and correlation matrices. T_0 is then compared with ET, and, if smaller, the logic goes to the KDATA test at (N). Because KDATA corresponds to the number of points per record on the FIT tape, it is now a positive integer. Therefore, the logic drops to (O) where KPROP is tested. However, KPROP was set to 1 in the processing path (J) - (N), so the logic drops to (Q), then to (T) and back to (D) to determine the next point to be processed. As long as data are available on the FIT tape, the program loops through the circuit (D) - (I) - (J) - (N) - (T) - (B) - (D). If a block print time intervenes the logic forks after

(I) to (K). From (K) to (L) the state, covariance and correlation matrices are propagated to time ET, the print occurs in output, and the logic transfers back to (N). Because KPROP is set zero in the propagation path (K) - (L), the test below (O) now transfers back to (H) then to (I). Because during propagation (K) - (L) no data are processed, it is not necessary to determine another data point at (D). If a data time, TIME, equals the print time, ET, the processing path (J) - (N) is traversed until the last point at time TIME is processed (JST = 1). Then the logic branches through (U) to output to perform the block printing. When final time, TFINAL, is ultimately equaled or exceeded, the test below (L) transfers the logic to (P) and then to (R) because NPC(1) = 0. Below (R) the reference is updated and logic returns to (M) where SMOOTH is called. SMOOTH performs the backward smoothing from final time to initial time as well as calculation of residuals and loss function. After SMOOTH, the logic transfers to (B) where the next iteration is commenced. On the last iteration, logic is transferred back to (A) to begin the next problem. If the FIT tape runs out of data at any time during the processing, the program will read a zero record (having KDATA = 0) last from the tape. Subsequently the transfer from (Q) goes to (G) where TIME is set to exceed the final problem time. This forces the program to traverse the circuit (H) - (I) - (K) - (L) - (N) - (O) - (H) thereafter.

2. Error analysis problems [NPC(1) = 2]. - The error analysis logic proceeds the same as the filtering logic with the following exceptions. The data processing time TIME is determined at (C) from card inputs rather than at (D) from the FIT tape. In MINVAR, the expanded state vector is not updated. At (S) the reference need not be updated.

3. Deterministic problems [NPC(1) = 1]. - On deterministic problems the logic flows through (A) - (B) - (E) - (L) - (N) - (F) - (G). At (G), TIME is set larger than final time and the logic continues through (I) - (K) - (L) - (N) - (F) - (I) until final time is equaled or exceeded at (L). From (L) the logic branches to (P) and then to (A) to commence the next problem.

B. Subroutine Logic

The logic and equations solved in each of the subroutines will next be described with the aid of the flow diagrams and source listings in Sections VI and VII. The subroutines are grouped into five classifications -- initialization and problem setup; integration of differential equations; measurement calculations and minimum variance updating; smoothing; and output.

1. Initialization and problem setup.- The initialization and problem setup is performed by subroutines PRESET, INDAT, and SETUP. These subroutines are only called once per problem. Therefore, they have been arranged to form an overlay. After SETUP has completed its execution, the remainder of the program is read into core overlaying the cells previously occupied by PRESET, INDAT, and SETUP.

a. PRESET: The first operations performed by STEP during an execution are to preset variables. These operations are performed in subroutine PRESET, and consist of prespecifying values for variables, counters, and triggers. Should values for these variables not be input, the prespecified values will be used in the problem execution.

b. INDAT: All card inputs are read from subroutine INDAT. The unique inputting logic divides the card input data into 20 categories described in Subsection II.A.1. As each category is input, the category number on the lead card is read as a fixed point number. The remaining data on the lead card is read in the A-mode to preclude the computer from transforming the data to binary numbers immediately. By means of the category number, logic is transferred, through a computed GO TO to the category specified. Here, the A-mode numbers are decoded into binary numbers and equated to specific variables in this category. Note that the decoding of the A-mode numbers is the one feature in STEP that limits the use to CDC computers. If more data are required for the particular category, they are input by standard READ instructions. In STEP1, subroutine AEROIN is called to input the trivariate tables containing the aerodynamic coefficients. Logic is then transferred back to the beginning of INDAT where the next category input is read.

Insofar as INDAT is concerned, the order in which the categories are input makes no difference. However, some data are required before others, and it is a good rule to input the categories in numerical order, especially categories 2, 3, 5, 10, and 14. When all data have been input, the category 20 card is read to end the input loop and return to PRESET.

Note how the expanded state vector components, uncertain model and measurement vector components, and other model parameters are stored. The nonlinear state variables are input into an array called ZO(i). These are later transformed into internal variables and stored into the array X(i), $i = 1, 10$ in SETUP. All model parameters, whether to be estimated or not, are stored

in the array $C(i)$, the argument (i) being their identification number. The model parameters to be estimated are counted as they are input, the counter being NSTC, and their identification numbers loaded into the array NC(i). If at any later time these model parameters are required, their identification numbers are stored in NC(i), $i = 1, \dots, \text{NSTC}$, and their values are stored in the $C(i)$ array. The uncertain model parameters not to be estimated, U, are counted by NPU, their identification numbers stored in MC(i), and their values stored in the $C(i)$ array. Uncertain measurement parameters not to be estimated, V, are counted by NPV, their identification numbers stored in MCC(i), and their values in $C(i)$. All constants known with absolute certainty are stored in the $C(i)$ array. The number of fitting data sources or types is counted by NSTA.

c. SETUP: After all data have been input, subroutine SETUP is called to set up the problem to be executed. SETUP commences by interrogating the program controls and printing comments to inform the user of the options he has selected. In the process of doing this, the gravitational, geophysical, and atmospheric (STEP1 only) data are printed in units either specified by the user via NPC(2) or in units in which the data were input.

In STEP1, all atmospheric data are calculated in subroutine ATMDAT during problem execution. This subroutine requires base pressure and temperature/altitude slope data. These are calculated in SETUP using the built-in altitude and temperature base points and sea-level pressure corresponding to the 1962 U.S. Standard or 1959 ARDC atmospheres or data provided by the user in INDAT.

The fitting data sources are next listed. For tracking stations, the geodetic latitude is transformed to geocentric and subroutine STAT called to calculate tracking station related information to be used during the execution. Tests are also performed to determine if rate terms on tracking station k are to be estimated [$M\emptyset(k) = 1$] or not estimated [$M\emptyset(k) = 0$]. Also, the number of tracking stations whose station locations are to be estimated (KSS) are determined and their station numbers (MTYP = 1, 2, ... 5) are stored in the array NSS(i), $i = 1, \dots, \text{KSS}$.

The inputted state variables are next transformed into internal variables $u, v, w, h, \phi, \theta, e_0, e_1, e_2$, and e_3 as are their covariance and correlation matrices. The transformations are presented in Section VI of Volume 1. The transformation matrix $N_I(i,j)$ is stored in the array DUB(i,j).

All angles at this point are in radians. SETUP next prints tables of the internal state variables and model parameters and their standard deviations. Finally, near the end of SETUP, the number of differential equations to be integrated is determined (NALL), and counters, triggers, arrays, and variables are set to their required values to commence the forward integration.

2. Integration of differential equations.- All linear and nonlinear differential equations are integrated in subroutine INTAG. Supporting subroutines required by INTAG to perform the integration are RKUTTA, DATAB, MOTION, FXXU, and in STEP1 AERO and DERIVE are also required.

a. INTAG: When subroutine INTAG is called, it will integrate the nonlinear differential equation in filtering and error analysis problems, from time T_0 to time T_2 . Initial conditions must have been specified for the linear and nonlinear equation dependent variables before calling INTAG. The equations are integrated by a fourth-order Runge Kutta integration scheme as one large system. The dependent variables in this system are stored in the array $X(i)$. Consider a problem where only the basic state variables are to be estimated. INTAG would then integrate the 10 nonlinear differential equations plus 10 independent vector solutions for the 10 linear differential equation, or 110 differential equations in all. In the array $X(i)$; $X(1-10)$ contains the solution to the nonlinear equations; $X(11-20)$ contains the first solution to the linear equations (the first column of the state transition matrix Φ); $X(21-30)$ contains the second solution to the linear equations; ... $X(101-110)$ contains the tenth solution to the linear equations. Note that there is but one system of linear differential equations, having time varying coefficients. Ten separate solutions to this system must be obtained. At the beginning of a problem, the initial conditions for the state variables, $X(1-10)$, are provided from SETUP. The initial conditions for the linear equations are specified in SETUP to be the identity matrix, i.e., $X(11-110) = 0$ except $X(11) = X(22) = X(33) = \dots = X(99) = X(110) = 1$. Inspection of the flow diagrams and listing of INTAG reveals that the array $PH(i,j)$ is frequently used instead of $X(10-110)$ discussed previously. This is possible because, in common INTGRL, $X(i)$ is dimensioned 10 and is followed by $PH(i,j)$ dimensioned 10 x 30. Thus, $X(11)$ is equivalent to $PH(1,1)$, $X(12)$ equivalent to $PH(2,1)$ and so on. $PH(i,j)$ is therefore the state transition matrix Φ .

The numerical integration logic is contained in subroutine RKUTTA. RKUTTA relies on the fixed point indicator LRK. The integration is commenced by setting $LRK = 4$ and calling RKUTTA. Upon returning from RKUTTA, LRK will equal 1, 2 or 3. When $LRK = 1$, the differential equations must be evaluated and logic returned to RKUTTA. $LRK = 2$ each time RKUTTA has completed an integration cycle. Thus, upon returning from RKUTTA with $LRK = 2$, the state can be printed if a printout is desired at a frequency dictated by the fixed computing interval DCOMP. The STATE tape is written during the backward integration whenever $LRK = 2$. RKUTTA returns with $LRK = 3$ when it has integrated to exactly the time T2. Because INTAG only integrates to T2, logic is returned to the main program whenever $LRK = 3$ on the return from RKUTTA.

b. RKUTTA: RKUTTA is a general numerical integration subroutine developed specifically for use in STEP. Its internal variables differ from those in the rest of STEP, thus through common block INTGRL, the RKUTTA variables are made equivalent to the STEP variables. As discussed above, LRK (or L in RKUTTA) is the indicator that RKUTTA uses to communicate with INTAG.

c. DATAB: Subroutine DATAB contains the logic for reading the PQR tape, writing a scratch tape containing the PQR data and interpolating tables to obtain P_M, Q_M, R_M and $a_{X_M}, a_{Y_M}, a_{Z_M}$

(STEP2 only). At the beginning of a problem, DATAB reads the PQR tape until the last time on a PQR tape record exceeds the initial problem time. It then stores between 20 and 40 of the PQR data points in core. As the integration proceeds the core stored tables are interpolated until time exceeds that of the second to the last point in core. All points in core are then transferred to the SCRACH tape, the last two points in core are transferred to the beginning of the table, and more PQR tape data is read into core until between 20 and 40 points are in core. The integration again proceeds until time exceeds that of the second to last point in core. Again, the core-stored points are transferred to the SCRACH tape, the last two core-stored points moved to the beginning of the table and more PQR tape data read. This continues until final time is exceeded and the backward integration (smoothing) commenced. Before commencing the backward integration, a false record is written on the SCRACH tape so that later, in DATAB, two backspaces will position the tape to read the last valid record. At final time, sufficient data are already in core to commence the backward integration. When time becomes smaller than that of the second point in core, the

SCRACH tape is backspaced twice and a record is read into core. This record already contains tie-in points, i.e., the first two points previously in core. Whenever time becomes smaller than the second point in core, the SCRACH tape is backspaced twice and read. In this manner the integration proceeds to initial time. During all remaining iterations, the PQR tape is used on the forward integration and the SCRACH tape used on the backward integration.

On filter problems, capability is included to calculate residuals of the measurements and a loss function on the backward integration. To do this requires that the data from the FIT tape, which were processed on the forward integration, be stored. This storage is accomplished without requiring an additional tape unit, by having logic included in DATAB to store the processed FIT data on the SCRACH tape also. Therefore, when the SCRACH tape is written on the forward integration, all but the last two good (not edited, eligible to be processed) FIT data points in core are written on the SCRACH tape simultaneously with the PQR data. The two FIT data points, which are held back, will be written on the next SCRACH record. Therefore, during the backward smoothing, the core always contains a FIT data point at a time smaller than the PQR data in core. Subsequently it will be seen that this is necessary in subroutine SMOOTH.

d. MOTION: In subroutine MOTION, the nonlinear differential equations of motion are calculated. The state variables $X(1-10)$ are used to calculate the state variable time derivatives $DX(1-10)$ presented in equations (127) thru (129) of Volume I. The major portion of MOTION is used in calculating the auxiliary equations, equations (130) thru (160). In STEP1, MOTION calls subroutine ATMDAT to determine the atmosphere data, and subroutine AERO to determine the aerodynamic coefficients.

An entry point AUXIL is provided to calculate quantities needed by subroutine OUTPUT. These quantities are altered whenever the nominal is changed (i.e., when a data point is processed during an updated nominal filter problem); thus, OUTPUT must evaluate these equations immediately before printing. Entry point AUXIL is used only by subroutine OUTPUT.

e. FXXU: Subroutine FXXU calculates the coefficients in the linear differential equations of motion, equation (165). These coefficients are presented in Section V of Volume I.

Subroutine FXXU always evaluates the equations in table 4 of vol. 1. The STEP1 program calculates the equation in table 5 also. Logic is included, which determines if the state vector has been augmented to include model parameters or if any model parameters have been included in the U array (uncertain, but not to be estimated). If so, the partial derivatives associated with these model parameters are evaluated.

For STEP1, entry point PAXPC is included in subroutine FXXU. This allows equations that are common to the linearized equations of motion and the linearized model for the accelerometers to be coded only once. Entry point PAXPC is used only by subroutine OBSERV.

f. ATMOS (STEP1 only): In subroutine ATMOS, all atmospheric parameters are calculated. These quantities are presented in equations (121) thru (126) in Volume I.

g. AERO (STEP1 only): Subroutine AERO determines all aerodynamic coefficients for the vehicle. The trivariate tables are linearly interpolated by subroutine FCTN. The interpolated coefficients are either C_A, C_Y, C_N ; C_D, C_Y, C_L ; or C_A, C_Y, C_N .

In AERO, these coefficients are then transformed to $-C_A, C_Y, -C_N$ by equations (134) and the error model, equation (147), solved before returning to MOTION.

Subroutine AERO has a seven-variable argument list. The first two arguments are determined by IPC_8 in category II (α, β if $IPC_8 = 0$ or -1 ; η, ξ if $IPC_8 = 1$). Arguments 3 and 4 are Mach and Reynolds numbers, respectively. Arguments 5, 6, and 7 are C_X, C_Y , and C_Z , which are returned to the calling program by AERO. Note that $C_X = -C_A$ and $C_Z = -C_N$.

Subroutine AERO has been written to facilitate its removal and replacement by a subroutine specialized to the particular vehicle being analyzed. The tables interpolated by subroutine AERO are the only quantities in common block AERTAB; after reading the category 11 card, subroutine INDAT transfers control to subroutine AEROIN, which reads in the tables, and then returns control to INDAT, which then continues to read in the remaining input data.

If subroutine AERO is replaced with a subroutine written for a specific vehicle, several facts should be considered. The input control IPC_8 in category 11 should be specified so the correct angles are passed to AERO; these angles are in radians, not degrees. The coefficients calculated must be transformed to C_X , C_Y , and C_Z . The error model, equation (147), must be included in subroutine AERO. Subroutine AEROIN may be modified to simplify any inputs to the new subroutine AERO.

h. TAB and FCTN: Subroutine FCTN is used solely for interpolating the trivariate aerodynamic coefficients tables. All other interpolations are performed by TAB. TAB was specifically developed for STEP and is limited to linear interpolation of monovariate tables. Each table contains an array of three fixed point numbers, $N(i)$, $i = 1, 3$, which TAB requires. $N(1)$ is the number of points in the table, $N(2)$ is the argument of the tabular array which bounds the last interpolated value on the lower side. TAB commences searching the table from this point the next time interpolation is required. $N(3)$ is zero for an increasing independent variable, and one for decreasing independent variable.

3. Measurement calculations and minimum variance updating.- On filtering and error analysis problems, the calculation of the nonlinear measurements, $Y(t_i)$, and their partial derivatives with respect to state variables and model parameters, G and H , are performed in OBSERV. In subroutine PROP, the covariance and correlation matrices, P , C_{uz} , and C_{vz} , are propagated to the measurement time by equation (54). In subroutine MINVAR, the minimum variance updating by means of equation (53) is accomplished.

The logic controlling the execution of OBSERV, PROP, and MINVAR is located in MAIN and is complicated by the optional ways that the data can be processed, i.e., scalar or vector processing with an updated or nonupdated reference of a one-, two-, or three-component measurement. The options are tested in MAIN and the flag KK is set to 1 if only one circuit through the OBSERV, PROP, and MINVAR loop is required. The only time more than one circuit is required is when processing a multicomponent vector, scalar point at a time in the updated reference mode for which case KK equals the number of vector components to be processed.

KN is set to 0 if only one component of the measurement vector and its partial derivatives need be specified in OBSERV. If more than one component must be calculated $KN = 1$. A loop is then commenced through OBSERV, PROP, and MINVAR with index KAR going from 1 to KK.

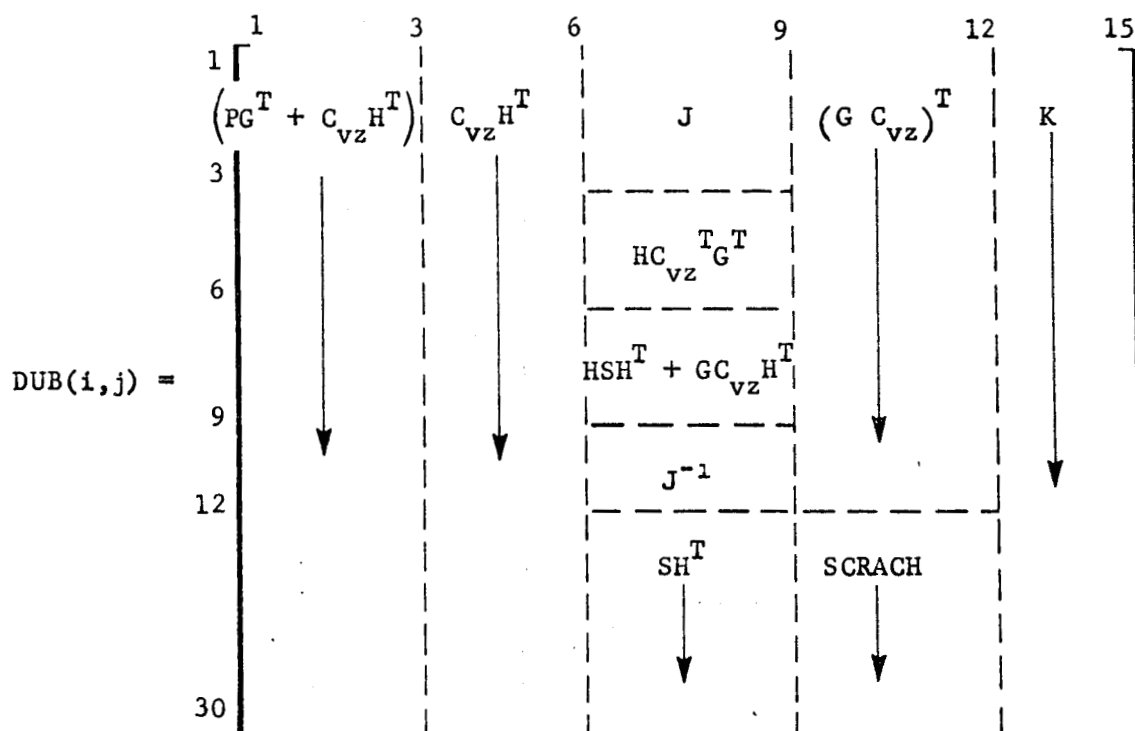
a. OBSERV: Subroutine OBSERV commences by testing the measurement type indicator, MTYP, and then branches the logic to calculate the nonlinear measurement specified. These measurement equations are presented in Volume I, Section VII. Measurements from all five tracking stations as solved from the same equations with the model parameters symbolically specified as a function of MTYP.

The three components of the measurement vector are stored in the array DFM(1-3). If only one component is to be processed ($KN = 0$), it is stored in DATC(KAR). If more than one component is to be processed, they are stored sequentially in DATC(i). Thus, if the second component of the measurement vector has been edited out by input controls, DATC(1) equals component one and DATC(2) equals component three. The integer KOB is set to KAR if only one component is to be processed or to JNBR if multiple components are to be processed. Thus, looping on i from KAR to KOB sequentially specifies the components of DATC(i) to be processed.

OBSERV next calculate the G and H matrices in equations (51a) and (51b). The matrices contain the partial derivative of the measurement components to be processed with respect to state variables and model parameters. The equations for these partial derivatives are presented in Section VII of Volume I. The partial derivatives are located in an array G(i,j) where i denotes the measurement vector components or rows. The rows of G are arranged similar to the elements of DATC(i), not necessarily sequentially with component number.

b. PROP: Subroutine PROP propagates the covariance and correlation matrices to the current measurement time by means of equations (54). Because the covariance matrix P is symmetric, only its upper right triangle is propagated. Before returning from PROP, the state transition matrix ϕ is reinitialized to the identity matrix.

c. MINVAR: Subroutine MINVAR next solves the minimum variance equations, equations (53). Rather than introduce additional FORTRAN variables, the dummy array DUB(i,j) is used throughout MINVAR. The order in which equations are solved and the location in DUB where the matrices are solved are as follows. Equation (53f) is first synthesized. The matrix product PG^T and GPG^T are calculated (using only the upper right triangle of P) and stored in DUB(1-3, 1-3) and DUB(1-3, 7-9), respectively. For convenience, a mapping of DUB is shown below. If uncertain measurement parameters are included ($NPV > 0$) then $GC_{vz}H^T$ and SH^T are calculated and stored in DUB(1-3, 7-9) and DUB(13-15, 7-9). $C_{vz}H^T$ is also added to PG^T in DUB(1-3, 1-3). Inspection of equations (53e) and (53f) reveals the J is being accumulated in DUB(1-3, 7-9) and the matrix $PG^T + C_{vz}H^T$ in DUB(1-3, 1-3). MINVAR continues to calculate matrix products and accumulating matrix sums using DUB as shown below.



The matrix J is inverted by means of the Gauss-Jordan reduction method coded in MINVAR. The 3×3 matrices shown in DUB are only calculated when a three-component vector is being processed. When the measurement vector contains fewer components, the matrices are smaller (2×2 or 1×1).

Because of the dependency of e_3 on e_0 , e_1 , and e_2 the tenth column of G , and the tenth row and column of P and the tenth rows of C_{uz} and C_{vz} are set to zero before their calculations in MINVAR. This produces the same results as not having the rows and columns to begin with. Before returning from MINVAR, these rows and columns of P , C_{vz} , and C_{uz} are calculated by equations (163) and (164). The correction for e_3 , is calculated from equation (162).

4. Smoothing. - When the forward integration is completed, subroutine SMOOTH is called to integrate the best estimate of the state, and possibly covariance, back to initial time. SMOOTH commences by testing program controls to determine if the residuals and loss function are to be calculated, if the linear equations of motion are to be integrated to propagate the covariance and correlation matrices, or if smoothing is even to be performed. The flag KSM is set to zero if the residuals and loss function are not to be calculated, and to one if they are to be calculated. NPC(1) is temporarily reset to 1 if the linear equation are not to be integrated. SMOOTH then proceeds to integrate backwards in INTAG to either a block print time, ET, or a measurement data time TIME. The measurement data are obtained from the SCRACH tape. OBSERV is called to calculate the best estimate of the measurement. During the backward integration, OBSERV returns after calculating only the nonlinear measurements. After SMOOTH has integrated back to the initial time, it resets counters, triggers, and tapes for the next iteration or problem before returning.

5. Output. - Subroutine OUTPUT performs all the block printing on both the forward and backward integration. The variables printed are described in Subsection II.C.2. If a state update has occurred before OUTPUT, MOTION is called, via entry point AUXIL, to recalculate auxiliary variables needed for outputting. After the state and auxiliary variables have been printed, the covariance and correlation matrices are transformed to output variables specified by NPC(3). This transformation is described in Section VI of Volume I. The transformation matrix N_0 is

stored in the DUB(i,j) array as follows:

$$N_0^T(1-3, 1-10) = \text{DUB}(1-10, 1-3)$$

$$N_0^T(7-9, 1-10) = \text{DUB}(1-10, 4-6)$$

The middle three rows of N_0 contain only the identity matrix for h , φ , and θ so they are not stored.

V. DEFINITION OF FORTRAN SYMBOLS

A(i,j)	Transformation matrix G between the G-frame and B-frame, see equation (133).
AB(i), AC(i)	Accelerations a_{XB} , a_{YB} , a_{ZB} acting through the center of gravity in body axes directions, see equations (134) and (146).
AG(i)	Accelerations a_{XG} , a_{YG} , a_{ZG} in the G-frame axes directions, see equation (132).
ALPH	Angle of attack, α , see equation (135).
AM(i)	Accelerations a_{XM} , a_{YM} , a_{ZM} modeled or measured at the inertial measuring unit in body axes directions with systematic error included, see equations (159) and (258).
AMDOT(i)	Time derivative of a_{XM} , a_{YM} , a_{ZM} , see equation (160).
AP(i)	AP(1-3) are accelerations a_{XP} , a_{YP} , a_{ZP} acting at the inertial measuring unit in body axes directions without systematic error; AP(4) is \bar{a}_p , see equations (158) and (159).
APDOT(i)	Time derivatives of a_{XP} , a_{YP} , a_{ZP} , and \bar{a}_p , see equations (160) and (157).
AS	Speed of sound c_s , see equation (125).
ASU	Sutherland constant, S, see equation (126).
AX(i), AY(i), AZ(i)	Tabular array of the accelerations a_{XM} , a_{YM} , a_{ZM} from the PQR tape.
B(i)	Array used in INDAT to input A-format information.
BETA	Sideslip angle, β , see equation (136).

C(i)	Model parameters C_1, C_2, \dots, C_{152} .
CALP	Cosine of the angle of attack, α , in equation (135).
CBET	Cosine of the sideslip angle, β , in equation (136).
CCAPHI(i)	Cos Φ corresponding to tracking station i, see equation (236).
CDP	Cosine pitch angle δ_P in equation (269).
CDY	Cosine yaw angle δ_Y in equation (269).
CETA	Cosine of total angle of attack, η in equations (137) and (187).
CF(i)	Array containing the aerodynamic coefficients $-C_A, C_Y, -C_N$.
CGR	Cosine γ_R in equation (271b).
CGM(i)	Modeled distances, x_{PM}, y_{PM} , and z_{PM} , from the center of gravity to the IMU along the body axes directions.
CI(i,j)	Matrix inverse, C^{-1} calculated in OBSERV, see equation (266).
CJ(i,j)	Product of matrix inverse in equation (259) times the transformation matrix involving P, Q, and R in equation (260); calculated in OBSERV.
CLR	Cos λ_R in equation (271a).
CONRD	Conversion from degrees to radians; equal to 0.017453292.
CPH	Cosine of geocentric latitude φ .
CPHIDT(i)	Cos Φ_{DT} corresponding to tracking station i, see equation (237).

CT(i) Dummy array of cosines used in SETUP and OUTPUT for $\cos \gamma_A$, $\cos \lambda_A$, $\cos \frac{\psi}{2}$, or $\cos \frac{\sigma}{2}$, $\cos \frac{\theta}{2}$, $\cos \frac{\beta}{2}$, and $\cos \frac{\phi}{2}$ or $\cos \frac{\alpha}{2}$.

CTM(i) Used in OBSERV for calculating R_c , A_c , E_c , \dot{R}_c , \dot{A}_c , and \dot{E}_c , respectively from equations (238) and (240).

CUZ(i,j), CVZ(i,j) Correlation matrices C_{uz} and C_{vz} , see equations (53) and (54).

CXZI Cosine of the steering angle, ξ , in equations (138) and (187).

D(i) Variances of uncertain model parameters not being estimated, see equations (41) and (54).

DADX(i,j) Partial derivatives of α and β with respect to state variables, see equation (186).

DAT(i,j) Array of data from FIT tape that is stored in core; subscript i indicates component.

DATA(i) Components of the current measurement vector or being processed; see MAIN and MINVAR.

DATAS(i) Components of the next measurement vector to be processed; see MAIN.

DATC(i) Measurement vector calculated in OBSERV; note that DATC(1), DATC(2), and DATC(3) do not correspond to the components of the data vector but to only those components to be processed, e.g., $DATC(1) = E_M$, $DATC(2) = A_M$ if R_M is edited out.

DCDY(i,j) Partial of $-C_A$, C_Y , $-C_N$ with respect to V_A , h_O , α , and β , see equation (186).

DCOMP	Fixed computing interval for the numerical integration.
DERIV(i,j)	Partial of a_{XB} , a_{YM} , a_{ZB} with respect to state variables, see equations (182) and (184).
DET	Print interval for block output.
DFIT(i)	Minimum time span between data points processed from the FIT tape of measurement type i.
DFM(i)	Components 1, 2, and 3 of the calculated measurement vector in OBSERV.
DPH(i,j)	Time derivative of the dependent variable in the linear differential equations of motion; equivalently the time derivative of the state transition matrix.
DRDH	Partial derivative of ρ with respect to h_o in equation (185).
DRDP	Partial derivative of r with respect to ϕ .
DTI(i)	Time to commence processing data of type i.
DTF(i)	Time to stop processing data of type i.
DTRAN(i,j)	Transformation matrix in equation (189).
DUB(i,j)	Dummy array used throughout program; especially in SETUP and OUTPUT for input/output transformations N_I and N_o , and in MINVAR.
DUD(i)	Dummy array.
DUE(i)	Dummy array.
DUF(i)	Dummy array.
DWDH(i)	Array containing du_{WM}/dh_o and dv_{WM}/dh_o calculated in DERIV.

DX(i)	Time derivatives of the internal state variables and state transition matrix.
DZ(i)	Expanded state variable perturbations $\hat{z}(t_1 t_1)$ calculated in MINVAR, see equation (54a).
ET	Time to print block output.
F1(i,j)	Coefficients of first three linear differential equations of motion calculated in MOTION and FXXU; also used in OBSERV for calculating adjoint matrix in equation (264).
F2(i,j)	Coefficients of middle three linear differential equations of motion.
F3(i,j)	Coefficients of last four linear differential equations of motion.
FIT	Logical tape number of the FIT tape, Fit = 1.
FLOS	Loss function calculated in SMOOTH.
G(i,j)	Partial derivative of the measurement vector with respect to expanded state vector components, G, see equation (6b).
GG(i)	Temporary storage for each column of G(i,j) as they are calculated in OBSERV.
H(i,j)	Partial derivative of the measurement vector with respect to uncertain measurement vector components, see equations (51a) and (51b).
HI(i)	Dummy array.
HO	Altitude above an oblate planet surface.
ICOUNT	Iteration counter.
IDN	Dummy integer variable used in INDAT.
II	Dummy integer variable.
IN	Logical input tape number, IN = 5.

IP	Dummy integer variable.
IPC	Temporary storage for input controls.
JJ	Dummy integer variable.
JN	Dummy integer variable.
JNBR	Number of components to be processed in the current measurement vector.
JNBRS	Number of components to be processed in the next measurement vector.
JST	Specified in MAIN to be 1 if only one measurement is to be processed at time TIME; JST > 1 if more than one vector measurement is to be processed at TIME.
KA	Dummy variable.
KAR	Index on loop through OBSERV, PROP, and MINVAR, see MAIN program.
KC(i)	Point numbering array used when printing the measurement schedule in OBSERV.
KD(i)	Point numbering array used in SMOOTH for printing the residuals.
KDAP	Number of points on PQR tape record, see DATAB.
KDATA	Number of points on previous FIT tape record, see MAIN.
KDATAS	Number of points on present FIT tape record, see MAIN.
KDUM	Dummy variable in INDAT.
KG	Counter for acceptable data points read from the FIT tape, which are stored in core and either have been or are to be processed.

:	KG2	Number of measurement points from FIT tape that are written on the SCRACH tape in DATAB.
:	KK	Number of times loop is traversed between OBSERV and MINVAR in MAIN.
	KN	Flag set in MAIN to 0 if the reference is updated between processing of the measurement components; KN = 1 if state is not updated between component processing.
	KOB	Largest measurement vector component to be processed in MINVAR; loop goes from KAR to KOB; KOB is set in OBSERV.
	KPROP	Indicator that is initialized -1 in SETUP, is set to 0 after each minimum variance update, and set to 1 after each propagation; see figure 4.
	KS	Number of FIT tape measurement vectors stored in core; updated in MAIN.
:	KSS	Number of tracking stations whose location is being estimated.
:	KSM	Indicator in SMOOTH; if KSM = 0, do not calculate residuals; if KSM = 1, calculate residuals and loss function.
	K1	Dummy variable.
	LC(i)	Array containing the component numbers of the current measurement vector DATA(j) to be processed, e.g., LC(1) = 2, LC(2) = 3 if component 1 is edited out.
	LCS(i)	Same as LC(i), but corresponding to the next data vector DATAS(j).
:	LS	Number of PQR tape points that are stored in the arrays TT(i), TP(i) . . . AZ(i); counter is updated in DATAB.
:	LT	Dummy variable.

L1	Flag used to determine if fitting schedule title should be printed from OBSERV; print titles if $L1 = 2$, do not print if $L1 \neq 2$; also used to print residual schedule titles in SMOOTH if $L1 \neq 0$, and used as a transfer flag at return from SMOOTH; If $L1 = 0$, start next problem, if $L1 = 1$, start next iteration.
MC(i)	Array containing the identification numbers for variables in U, the uncertain model parameters not to be estimated.
MCC(i)	Array containing the identification numbers for variables in V, the uncertain measurement parameters not to be estimated.
MØ(i)	Flag set to 1 if rate terms are included in the radar tracking error model, equation (239), from station i; otherwise zero.
MR(i,j)	Flag equal to 1 if component i of measurement type j of the FIT tape data is to be processed; flag equals 0 if not to be processed.
MTP(i)	Array containing the data type identification number corresponding the FIT tape data that has been read into core.
MTP	Measurement data type identification number for current measurement to be processed $MTP = 1, 2, 3, 4, 5$ for radar tracking from stations 1, 2, 3, 4, 5; $= 6$ for airborne radar; $= 9$ for accelerations; $= 8$ for position vector; and $= 7$ for velocity vector.
MTYPS	Same as MTP, but corresponds to next data vector to be processed.
NC(i)	Array containing the identification numbers for model parameters to be estimated.
NCOUNT	Processing measurement point counter.
NNN	Dummy variable.

NPC(i)	Program controls specified in INDAT, see Section II.A.2.
NPTS	Dummy variable used in INDAT to denote the number of points on a table; one point consists of two scalar numbers, the independent variable and dependent variable.
NPU	Number of components in U, the uncertain model parameter vector not to be estimated.
NPV	Number of component in V, the uncertain measurement parameters not to be estimated.
NS(i)	Array containing the measurement type indicators (MTYP) for measurement to be processed from FIT tape; NS(i) is set in INDAT.
NSS(i)	Array containing the station numbers of radar stations whose location is to be estimated.
NST	Counter for state variable components input in INDAT.
NSTA	Measurement data type counter input in INDAT.
NSTC	Counter for model parameters which are to be estimated.
NSTX	Number of components in expanded state vector to be estimated; NSTX = 10 + NSTC.
NT	Dummy variable.
NTR(i)	Flag used in editing measurement type i in MAIN; NTR(i) is initialized to zero at beginning of problem; thereafter, NTR(i) = 2 indicates the last fitting point was accepted, = 3 indicates the last fitting point was rejected.
N4(i)	Array used by TAB for interpolating $m_M(t)$ table.

N5(i)	Array used by TAB for interpolating $u_{WM}(h)$ table.
N6(i)	Array used by TAB for interpolating $v_{WM}(h)$ table.
NS(i)	Array used by TAB for interpolating $x_{PM}(t)$ table.
N9(i)	Array used by TAB for interpolating $y_{PM}(t)$ table.
N10(i)	Array used by TAB for interpolating $z_{PM}(t)$ table.
N11(i)	Array used by TAB for interpolating $P_M(t)$, $Q_M(t)$, $R_M(t)$ tables.
OMEGA	Planet rotation rate Ω_P .
OUT	Logical output tape number, $\cdot OUT = 6$.
P(i,j)	Covariance matrix P .
PA(i)	Inertial angular rates, P , Q , R calculated in MOTION.
PAR(i)	Parameters calculated in MOTION and subsequently used in other subroutines.
PAXP(i,j)	Partial of a_{XP} , a_{YP} , a_{ZP} with respect to state variables, see equation (189).
PDOT(i)	Time derivative of P , Q , and R calculated in MOTION.
PE	Atmospheric pressure calculated in ATMDAT from equation (123).
PH(i,j)	State transition matrix ϕ .
PHIDT(i)	Geodetic latitude of tracking station i .
PM(i)	Measured inertial angular rates P_M , Q_M , and R_M .

PMDOT(i)	Time derivatives of P_M , Q_M , and R_M .
PQR	Logical tape number of the PQR tape, PQR = 2.
R	Radial distance from planet center to vehicle, r .
RCC(i)	Partial derivatives of R_c , A_c , E_c with respect to C_i calculated in OBSERV from equation (250).
RCDC(i)	Partial derivatives of \dot{R}_c , \dot{A}_c , \dot{E}_c with respect to C_i , calculated in OBSERV from equation (251).
RCDX(i,j)	Partial derivatives of \dot{R}_c , \dot{A}_c , \dot{E}_c with respect to u , v , w , h , ϕ , θ calculated in OBSERV from equation (245).
RCX(i,j)	Partial derivative of R_c , A_c , E_c with respect to h , ϕ , θ calculated in OBSERV from equation (244).
REØ	Equitorial radius of planet, R_E .
RERP2	Parameter $(R_E/R_P)^2$.
RES(i)	Residuals and weighted residuals in SMOOTH.
RØ	Radius of oblate planet, R_O .
RØE	Atmospheric density corrected for systematic error in MOTION from equation (151).
RØEC	The exponential portion of the atmospheric density correction; calculated in MOTION from equation (151).
RØEM	Modeled atmospheric density ρ_M , transferred to MOTION from ATMDAT where it is calculated via equation (124).

RPØ	Polar radius of planet.
RT(i)	Radial distance from planet center to tracking station i.
ROT(i)	Radius of oblate planet at latitude of tracking station i.
S(i)	Variances of uncertain measurement parameters not being estimated, see equations (44) and (53).
SALP	Sine of angle of attack α , see equation (135).
SBET	Sine of sideslip angle β , see equation (136).
SCAPHI(i)	Cos ϕ corresponding to tracking station i.
SCRACH	Logical tape number of the SCRACH tape, SCRACH = 3.
SDP	Sine of pitch angle δ_p in equation (269).
SDY	Sine of yaw angle δ_y in equation (269).
SETA	Sine of total angle of attack η , see equation (137).
SGR	Sin γ_R in equation (271b).
SI(i)	Standard deviations of the fitting measurements processed in MINVAR.
SIG(i,j)	Array of standard deviations from FIT tape, which are stored in core.
SIGM(i)	Standard deviations of measurement vector currently being processed.
SIGMS(i)	Standard deviations of next measurement vector to be processed.

SLR	Sin λ_R in equation (271a).
SP(i)	Scratch pad or dummy variable used throughout program.
SPD(i)	Scratch pad or dummy variable used throughout program.
SPH	Sine of the geocentric latitude φ .
SPHIDT(i)	Sin φ_{DT} corresponding to tracking station i, see equation (237).
SREF	Reference area for aerodynamic coefficients.
ST(i)	Dummy array of sines used in SETUP and OUTPUT for $\sin \gamma_A$, $\sin \lambda_A$, $\sin \frac{\bar{\psi}}{2}$, or $\sin \frac{\sigma}{2}$. $\sin \frac{\bar{\theta}}{2}$, or $\sin \frac{\beta}{2}$, and $\sin \frac{\bar{\phi}}{2}$, or $\sin \frac{\alpha}{2}$.
STATE	Logical tape number for STATE tape, STATE = 4.
SUM	Dummy variable use primarily for accumulating matrix products.
SUM2	Dummy variable used similarly to SUM.
SXZI	Sine of steering angle ξ , see equation (138).
SYG(i,j)	Incremental standard deviations on component i of measurement type j input in category 7 input.
T	Running variable for time used in RKUTTA.
TABLES(i,j)	Array containing all three aerodynamic coefficient tables in AERO.
TAU	Time increment $t-t_1$ calculated in MOTION from equation (150).
TCX(i)	First aero table C_A or C_D in AERO; note TCX(i) is equivalent to TABLE(i,1).

TCY(i)	Second aero table C_Y in AERO; note TCY(i) is equivalent to TABLE (i,2).
TCZ(i)	Third aero table C_N or C_L in AERO; note TCZ(i) is equivalent to TABLE(i,3).
TFIT(i)	Minimum time for processing the next type i measurement in MAIN; all type i data before TFIT(i) will be rejected.
TFINAL	Final problem time; stop the forward integration after the first block printout that equals or exceeds TFINAL.
TIME	Time corresponding to the current measurement vector being processed.
TIMES	Time corresponding to the next measurement vector to be processed.
TMAS(i)	Independent variable on the vehicle mass table $m_M(t)$.
TØ	Time to initiate integration in INTAG
TONE	Time t_1 at which mass correction commences, see equations (149) and (150).
TP(i)	Table containing the inertial angular rate data, P_M , read from the PQR tape.
TPH	Tangent of geocentric latitude ϕ .
TQ(i)	Table containing the inertial angular rate data, Q_M , read from the PQR tape.
TR(i)	Table containing the inertial angular rate data, R_M , read from the PQR tape.
TRAN(i,j)	Transformation matrix containing P, Q, and R in equation (146).
TT(i)	Table containing the independent variable (time) for TP(i), TQ(i), TR(i) and AX(i), AY(i), AZ(i) (STEP2 only).

TIWØ	Time t_2 at which mass correction stops, see equation (149) and (150).
TUW(i)	Independent variable on atmospheric wind table $u_{WM}(h_o)$.
TVW(i)	Independent variable on atmospheric wind table $v_{WM}(h_o)$.
TXCG(i)	Table containing the independent variable (time) for $x_{PM}(t)$.
TYCG(i)	Table containing the independent variable (time) for $y_{PM}(t)$.
TYM(i)	Table containing the measurement data times from the FIT tape.
TZCG(i)	Table containing the independent variable (time) for $z_{PM}(t)$.
TZERØ	Initial problem time.
T2	Time to stop the integration in INTAG and return to the point where INTAG was called.
UW	Atmospheric wind component u_w calculated in MOTION from equation (152).
VA(i)	Array containing u_A , v_A , w_A , V_A , and V_A^2 , calculated in MOTION from equations (140) and (141).
VB(i)	Components of V_A in body axes directions, u_B , v_B , w_B ; calculated in MOTION from equation (139).
VØ(i)	Dummy array used for temporary storage.
VW	Atmospheric wind component v_w calculated in MOTION from equation (152).

X(i)	Dependent variables in the nonlinear differential equations of motion.
XA(i)	Array containing a_1, a_2, \dots, a_5 in equation (277).
XAX(i,j)	Partial derivatives of a_1, a_2, \dots, a_5 with respect to $h, \varphi, \theta, e_0, e_1, e_2, e_3$; calculated in OBSERV from equation (283).
XC(i)	Array containing C_1, C_2, C_3 ; calculated in OBSERV from equation (276).
XCX(i,j)	Partial derivatives of C_1, C_2, C_3 with respect to $h, \varphi, \theta, e_0, e_1, e_2, e_3$; calculated in OBSERV from equation (282).
XIND1 } XIND2 }	Independent variable α, β or η, ξ used in AERO to calculate aerodynamic coefficients.
XJ2	Coefficient of the second gravitational harmonic, J_2 , see equation (106).
XLB(i)	Direction cosines l_B, m_B, n_B ; calculated in OBSERV from equation (269).
XLG(i)	Direction cosines l_G, m_G, n_G ; calculated in OBSERV from equation (270).
XLGE(i,j)	Partial derivatives of l_G, m_G, n_G with respect to e_0, e_1, e_2, e_3 ; calculated in OBSERV from equation (286).
XLGX(i,j)	Partial derivatives of λ_R and γ_R with respect to e_0, e_1, e_2, e_3 ; calculated in OBSERV from equations (284) and (285).
XLREF	Vehicle reference length, l , used in calculating Reynolds number, see equation (148).

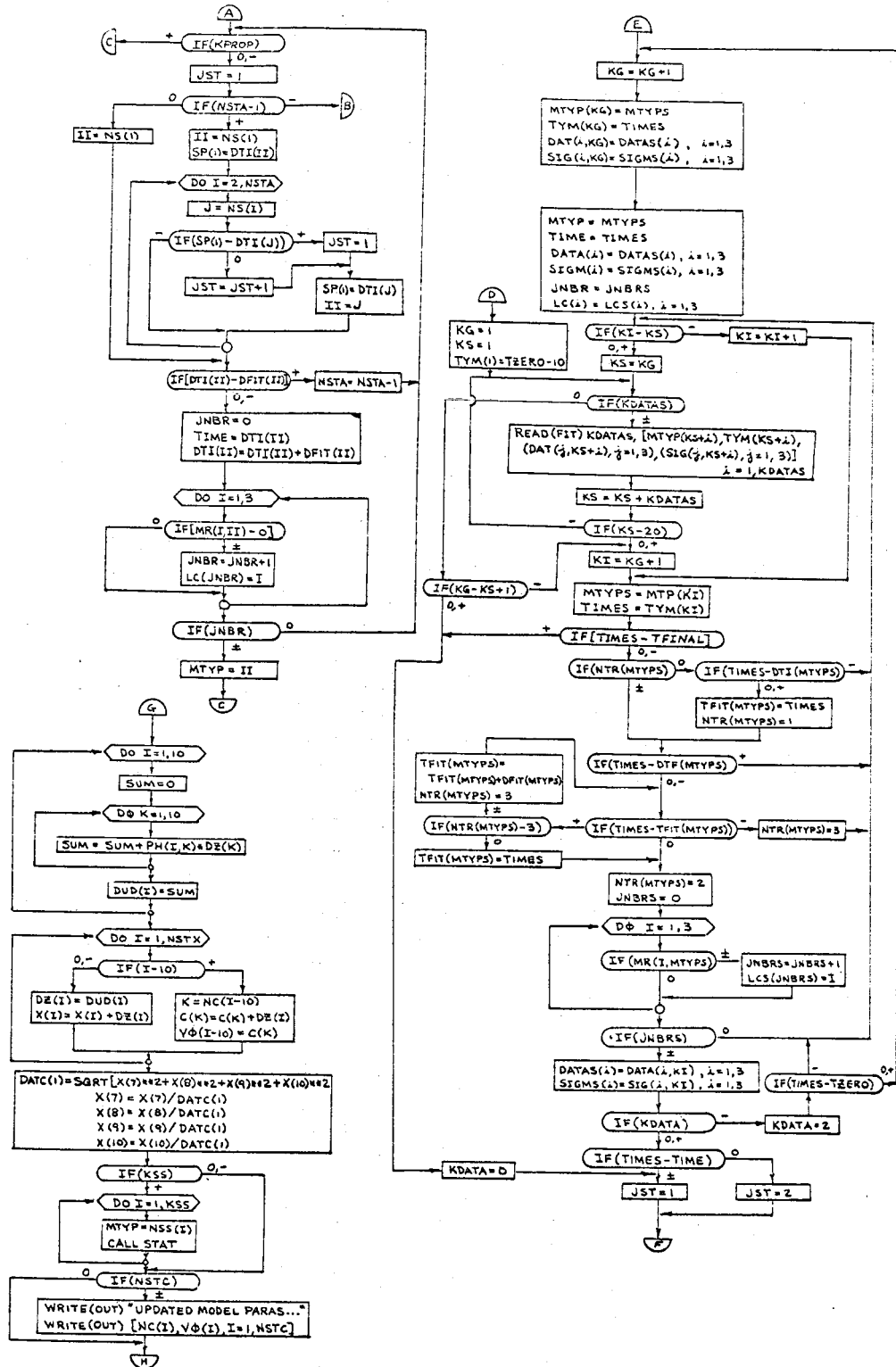
XM	Mach number, M ; calculated in MOTION from equation (143).
XMAS(i)	Dependent variable on the $m_M(t)$ table.
XMU	Coefficient of the first gravitational harmonic μ ; see equation (106).
XMUJ	The product $2 \mu J$; see equation (106).
XNU	Atmospheric viscosity μ_A ; transferred to MOTION from ATMDAT where it is calculated via equation (126).
XP(i)	The center-of-gravity/IMU distances x_p , y_p , z_p in equation (153).
XQ	Dynamic pressure, q ; calculated in MOTION from equation (142).
XQSM	Parameter equal to $XQ \cdot SREF / YMAS$ calculated in MOTION.
XRE	Reynolds number, R_E ; calculated in MOTION from equation (148).
XS(i)	Cartesian components of the radar tracking vector, x_s , y_s , z_s ; calculated in OBSERV from equation (235).
XSC(i)	Partial derivatives of x_s , y_s , z_s with respect to C_{88} , C_{89} or C_{90} ; calculated in OBSERV from equation (252).
XSD(i)	Time derivatives \dot{x}_s , \dot{y}_s , \dot{z}_s calculated in OBSERV from equation (241).
XSDC(i)	Partial derivatives of \dot{x}_s , \dot{y}_s , \dot{z}_s with respect to C_{88} , C_{89} , or C_{90} ; calculated in OBSERV from equation (253).

XDSX(i,j)	Partial derivatives of \dot{x}_s , \dot{y}_s , \dot{z}_s with respect to u , v , w , h , ϕ , θ ; calculated in OBSERV from equation (247).
XSX(i,j)	Partial derivatives of x_s , y_s , z_s with respect to h , ϕ , θ calculated in OBSERV from equation (246).
XTEMP	Atmospheric temperature transferred to MOTION from ATMDAT.
XUW(i)	Dependent variable on atmospheric wind table $u_{WM}(h_o)$.
XVW(i)	Dependent variable on atmospheric wind table $v_{WM}(h_o)$.
XXCG(i)	Dependent variable on $x_{PM}(t)$ table, see equation (153).
XYCG(i)	Dependent variable on $y_{PM}(t)$ table, see equation (153).
XZCG(i)	Dependent variable on $z_{PM}(t)$ table, see equation (153).
XZI	Steering angle ξ , see equations (138) and (187).
YMAS	Vehicle mass, m , corrected for systematic error; calculated in MOTION from equation (149).
YMASM	Vehicle mass as interpolated from the model mass table.
ZØ(i)	Dummy array used for temporary storage.

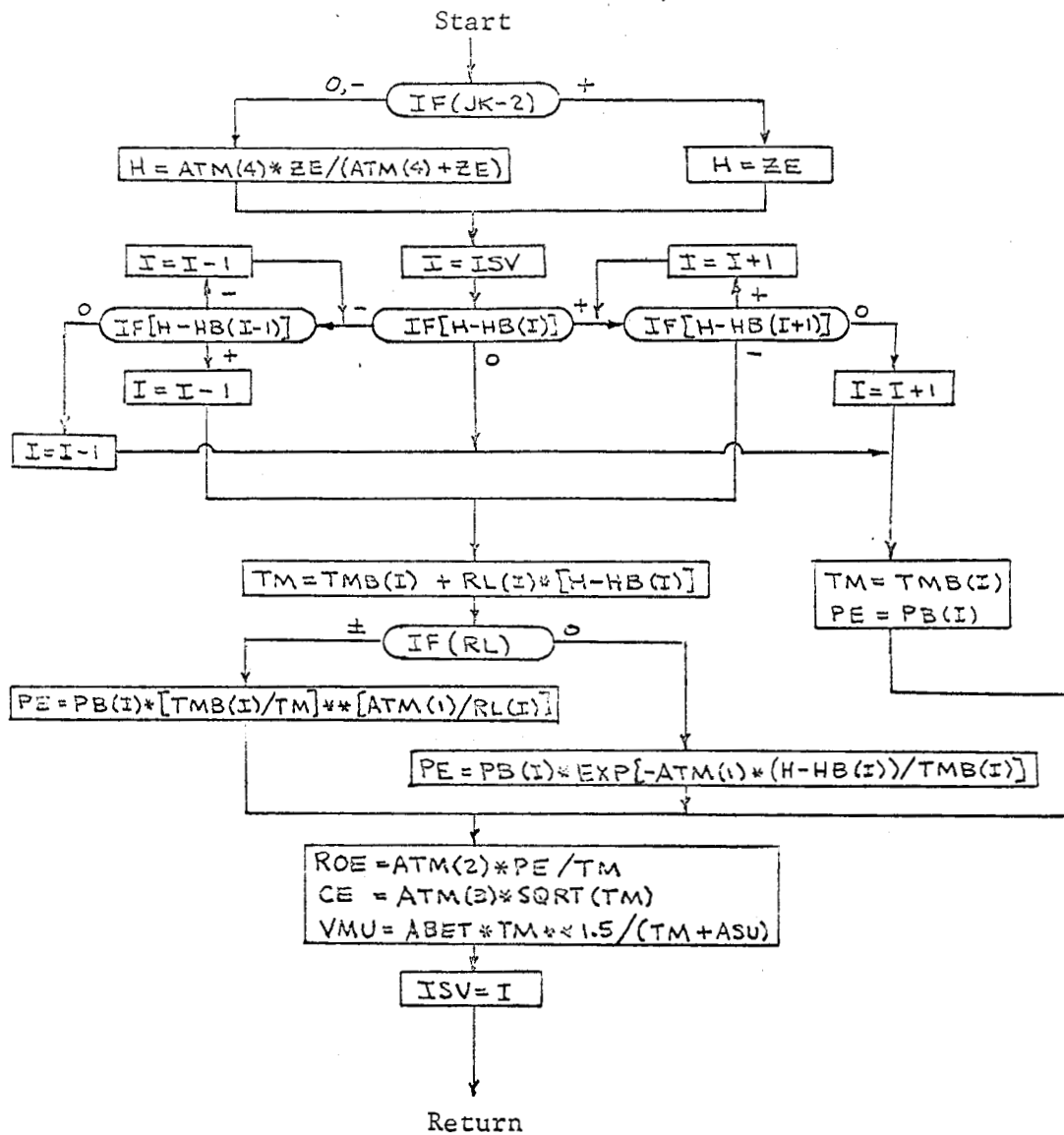
VI. FLOW DIAGRAMS

Subroutine flow diagrams are presented in this section. The following listing indicates the page on which the various flow diagrams appear.

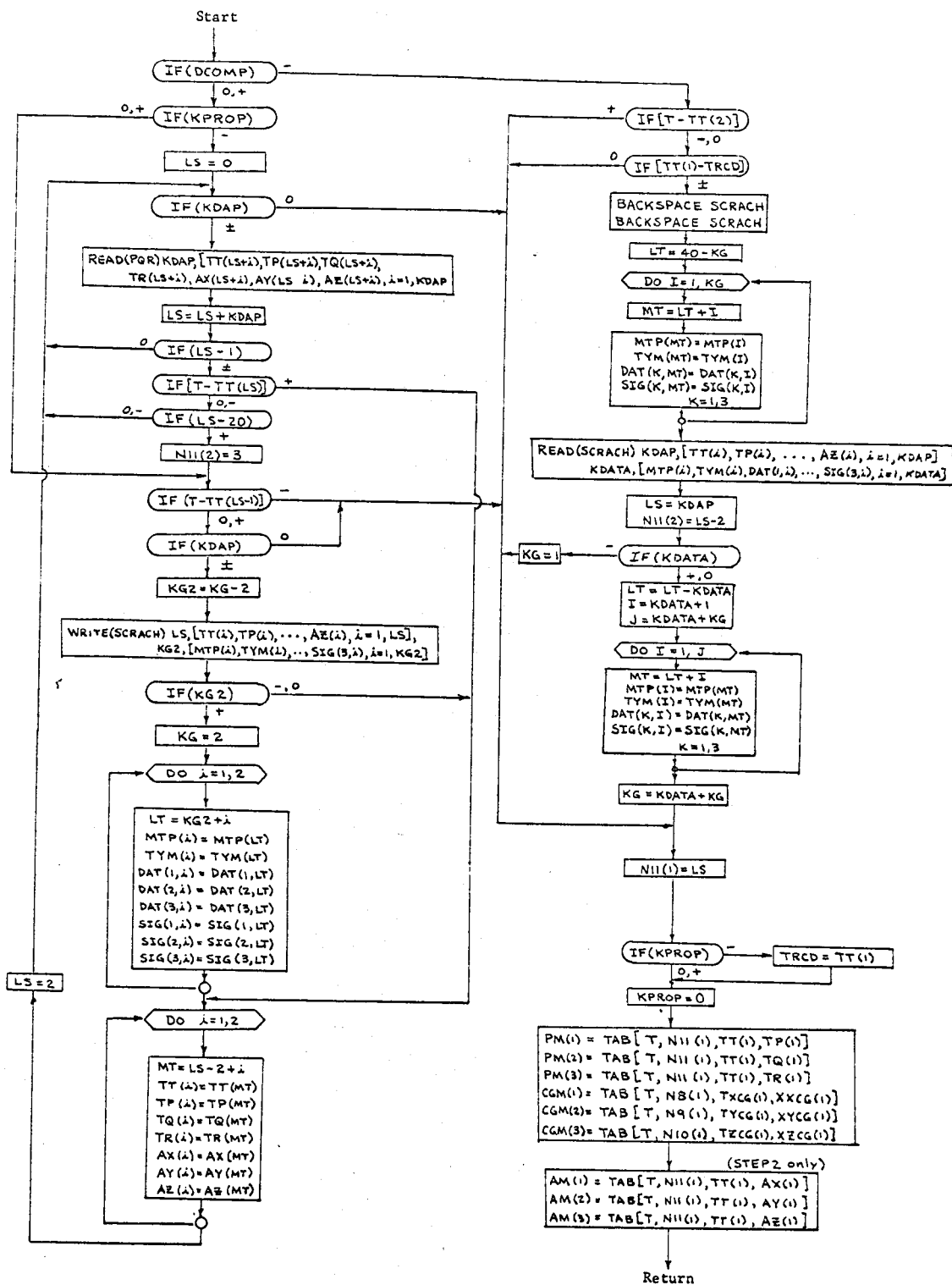
<u>Subroutine</u>	<u>Page</u>
MAIN	98
AERO	100
AEROIN	101
ATMDAT	102
DATAB	103
DERIVE	104
FXXU	105
INDAT	111
INTAG	114
MINVAR	115
MOTION	118
OBSERV	120
OUT PUT	124
PRESET	127
PROP	128
RKUTTA	129
SETUP	130
SMOOTH	134
STAT	135
CRV	136
FUNCT	136
TAB	136



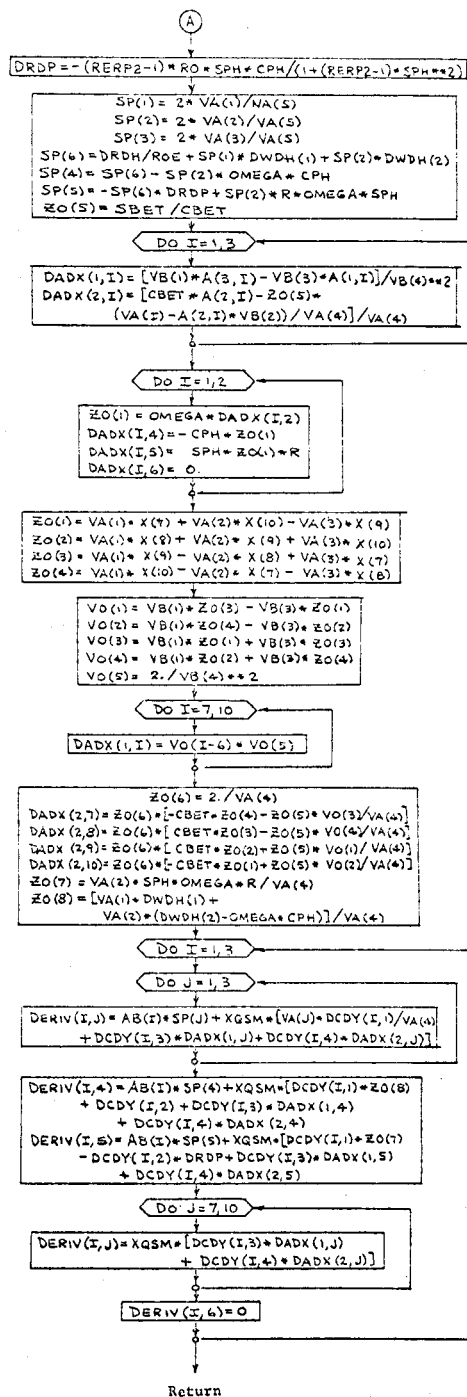
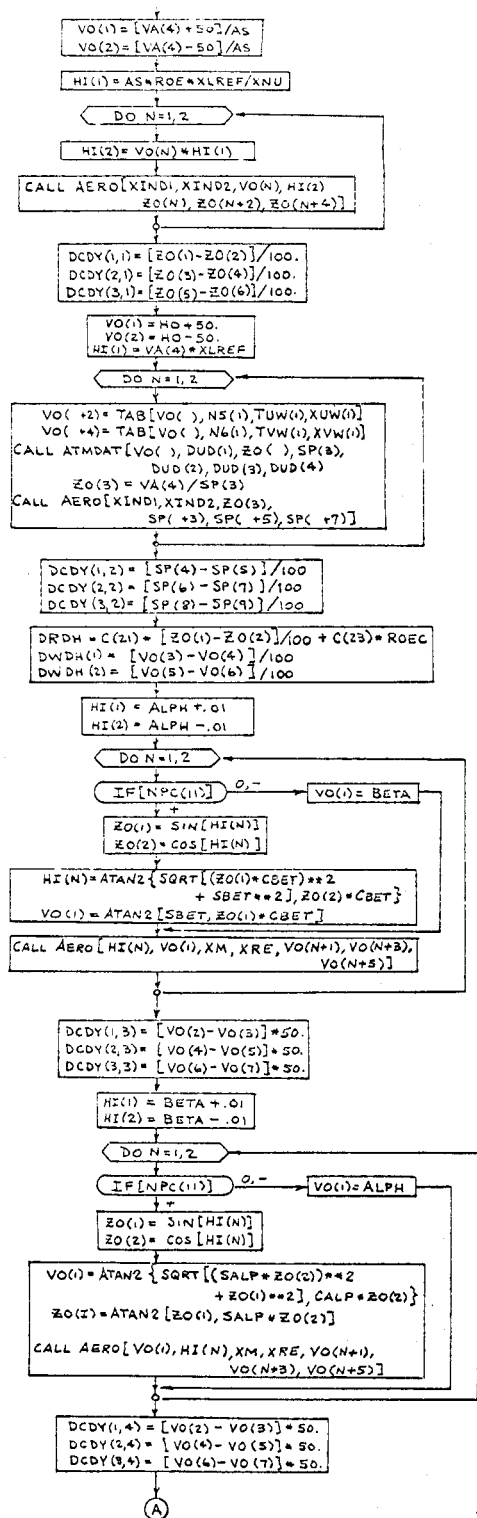
MAIN Program - Concluded



Subroutine ATMDAT (ZE, PE, ROE, CE, TM, VMU, ISV)



Subroutine DATAB



Subroutine DERIVE

Start

```

SP(1) = PAR(4)*X(2)/CPH**2
F2(2,1) = 1./R
F1(1,3) = F2(2,1)*X(1)
F1(3,1) = -F1(1,3) - F1(1,3)
F1(3,2) = -F1(2,3) - F1(2,3)
F1(1,1) = F2(2,1)*X(3)
F1(1,2) = -F1(2,1) - F1(2,1)
F1(1,4) = [-PAR(5)*F2(2,1)
+ 4*PAR(3)*SPH*CPH]*F2(2,1)
F1(1,5) = SP(1)*F1(3,2)*R
- PAR(3)*(CPH+SPH)*(CPH-SPH)
F1(2,4) = -F1(2,2)*F1(2,3)
F1(2,5) = -SP(1)*F1(3,1)*R
F1(3,4) = [PAR(1)*F2(2,1)-PAR(2)
- PAR(2)+4*PAR(3)*PAR(6)]*F2(2,1)
F1(3,5) = -3*PAR(3)*SPH*CPH
F2(2,4) = -F1(1,3)+F2(2,1)
F2(3,2) = F2(2,1)/CPH
F2(3,4) = -F1(2,3)*F2(3,2)
F2(3,5) = F1(2,1)/CPH
F3(1,1) = -X(9)*PAR(4)
F3(2,1) = X(10)*PAR(4)
F3(3,1) = X(7)*PAR(4)
F3(4,1) = -X(8)*PAR(4)
F3(1,2) = [X(8)-X(10)*TPH]*PAR(4)
F3(2,2) = -[X(7)+X(9)*TPH]*PAR(4)
F3(3,2) = [X(10)+X(8)*TPH]*PAR(4)
F3(4,2) = -[X(9)-X(7)*TPH]*PAR(4)
F3(1,4) = -F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)
F3(2,4) = -F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)
F3(3,4) = -F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)
F3(4,4) = -F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)
F3(1,5) = -X(10)*SP(1)
F3(2,5) = -X(9)*SP(1)
F3(3,5) = X(8)*SP(1)
F3(4,5) = X(7)*SP(1)
F1(1,7) = 2.*[X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3)]
F1(1,8) = 2.*[X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3)]
F1(1,9) = 2.*[-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3)]
F1(1,10) = 2.*[X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3)]
F1(2,7) = -F1(1,10)
F1(2,8) = -F1(1,9)
F1(2,9) = F1(1,8)
F1(2,10) = F1(1,7)
F1(3,7) = F1(1,9)
F1(3,8) = -F1(1,10)
F1(3,9) = -F1(1,7)
F1(3,10) = F1(1,8)
F3(2,7) = -F3(1,8)
F3(3,7) = -F3(1,9)
F3(3,8) = -F3(2,9)
F3(4,7) = -F3(1,10)
F3(4,8) = -F3(2,10)
F3(4,9) = -F3(3,10)
F2(1,5) = -1.

```

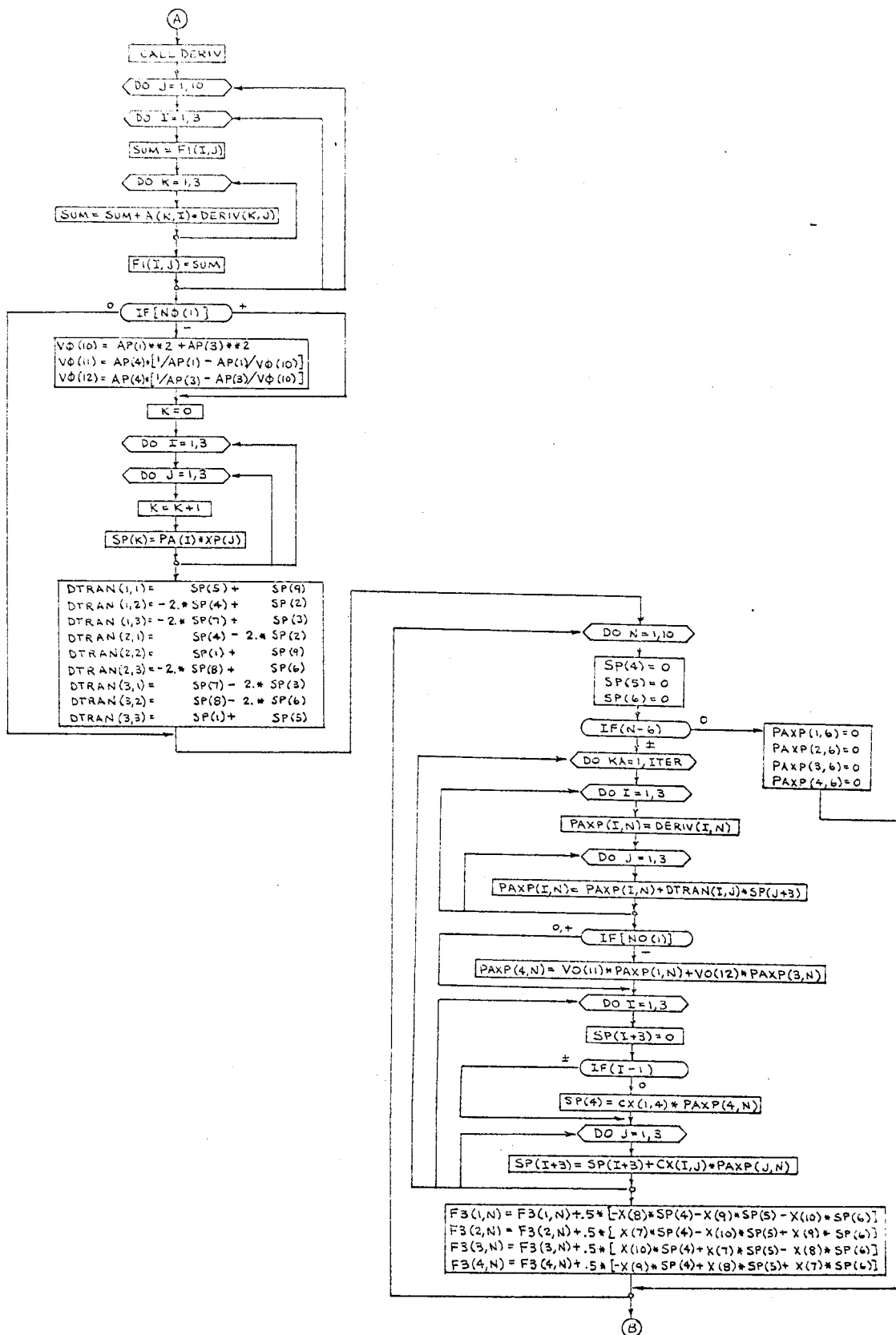
```

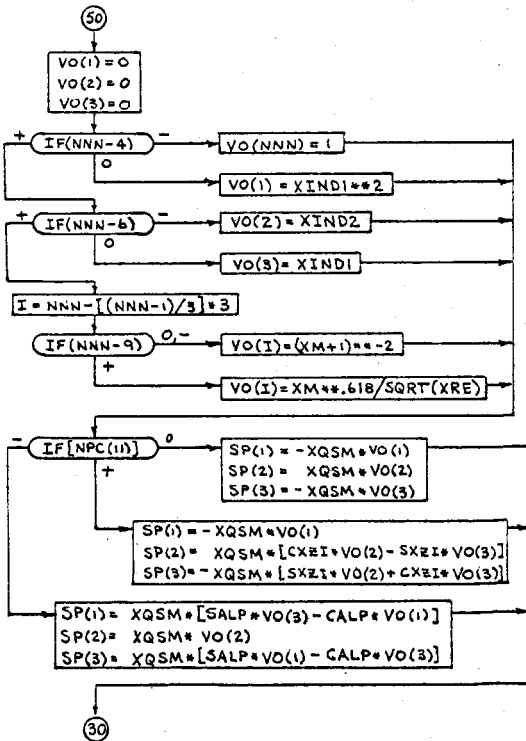
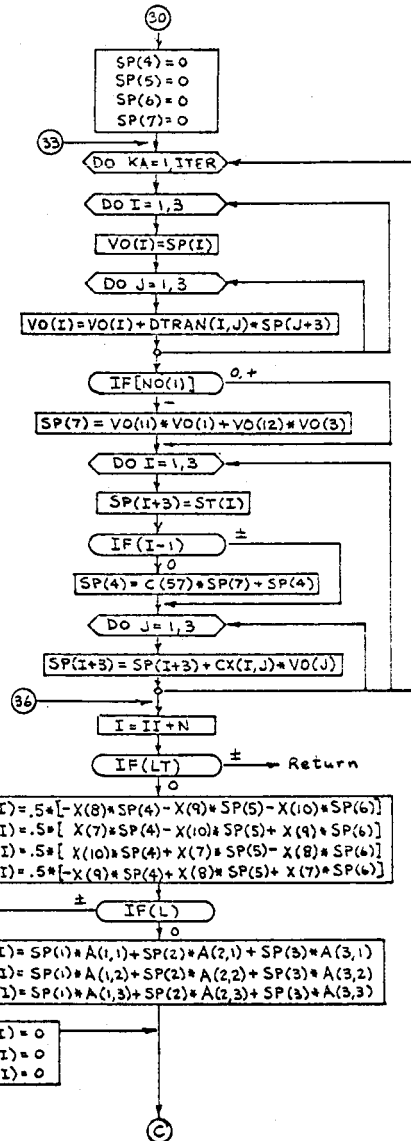
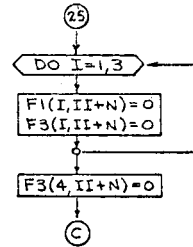
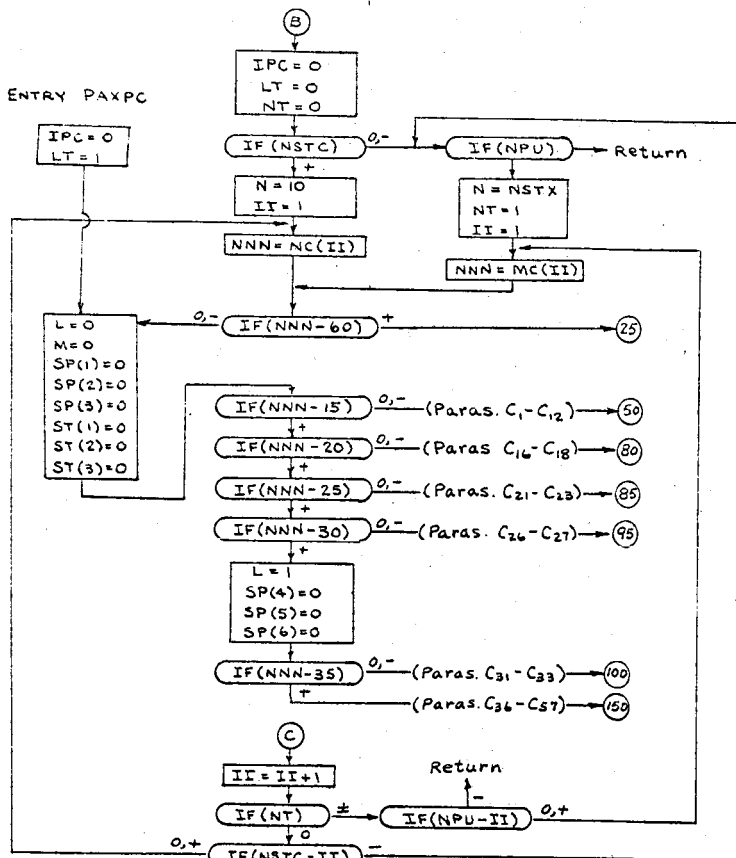
F1(1,6) = 0.
F1(2,6) = 0
F1(3,6) = 0
F1(3,3) = 0
F2(1,1) = 0
F2(1,2) = 0
F2(1,4) = 0
F2(1,5) = 0
F2(2,2) = 0
F2(2,3) = 0
F2(2,5) = 0
F2(3,1) = 0
F2(3,3) = 0
F3(1,3) = 0
F3(2,3) = 0
F3(3,3) = 0
F3(4,3) = 0
F3(1,4) = 0
F3(2,4) = 0
F3(3,4) = 0
F3(4,4) = 0
F3(2,8) = 0
F3(3,9) = 0
F3(4,10) = 0

```

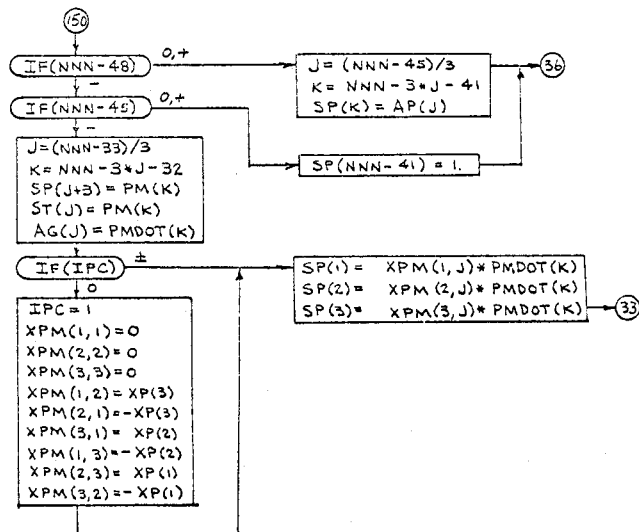
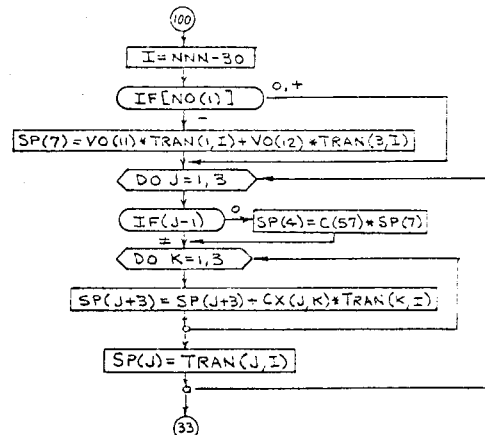
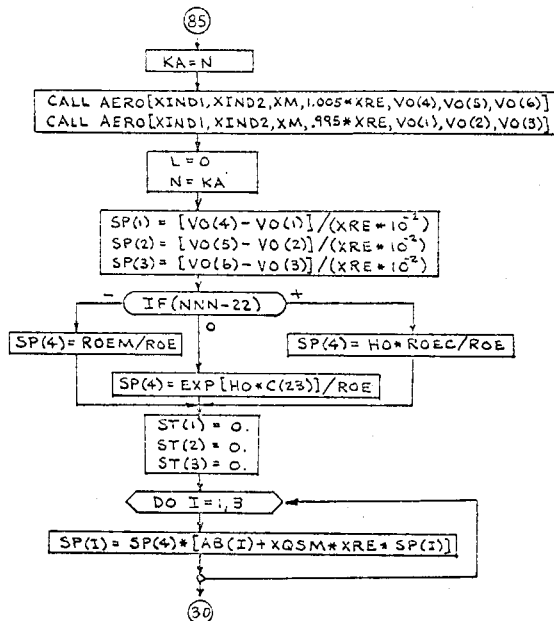
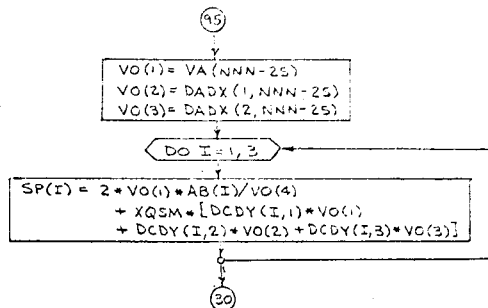
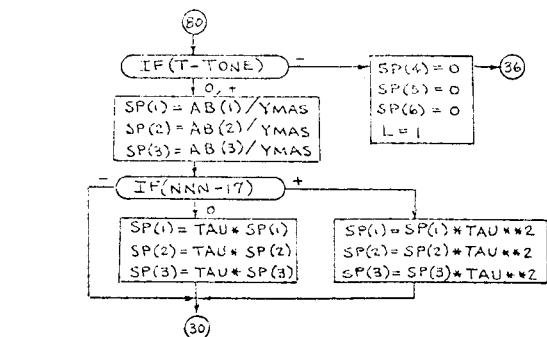
A

Subroutine FXXU (STEP1, STEP2)

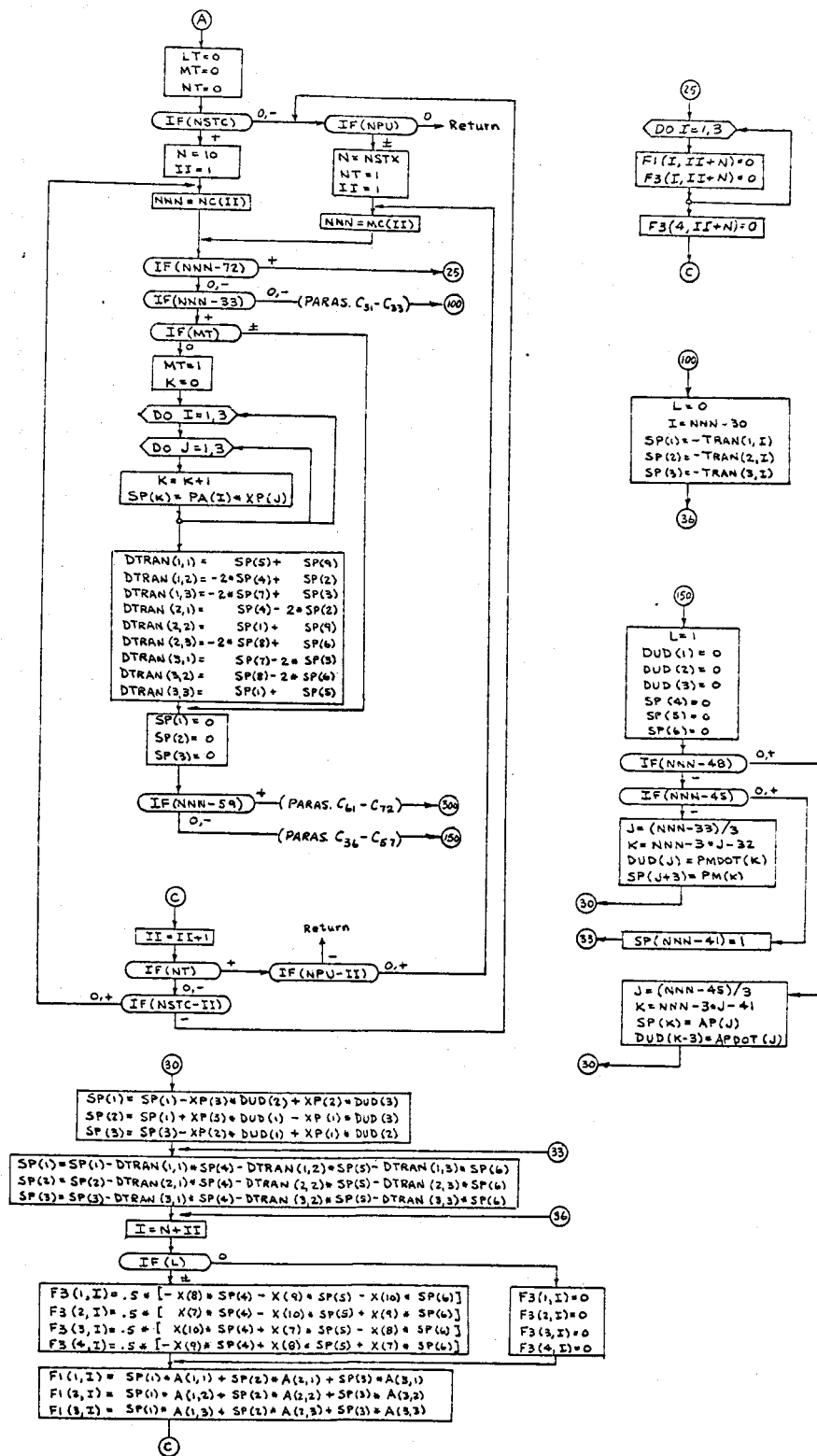




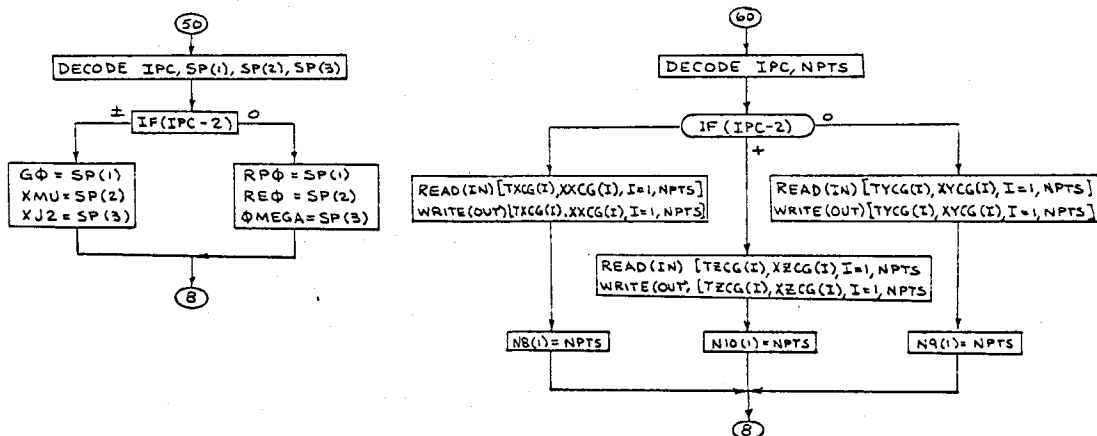
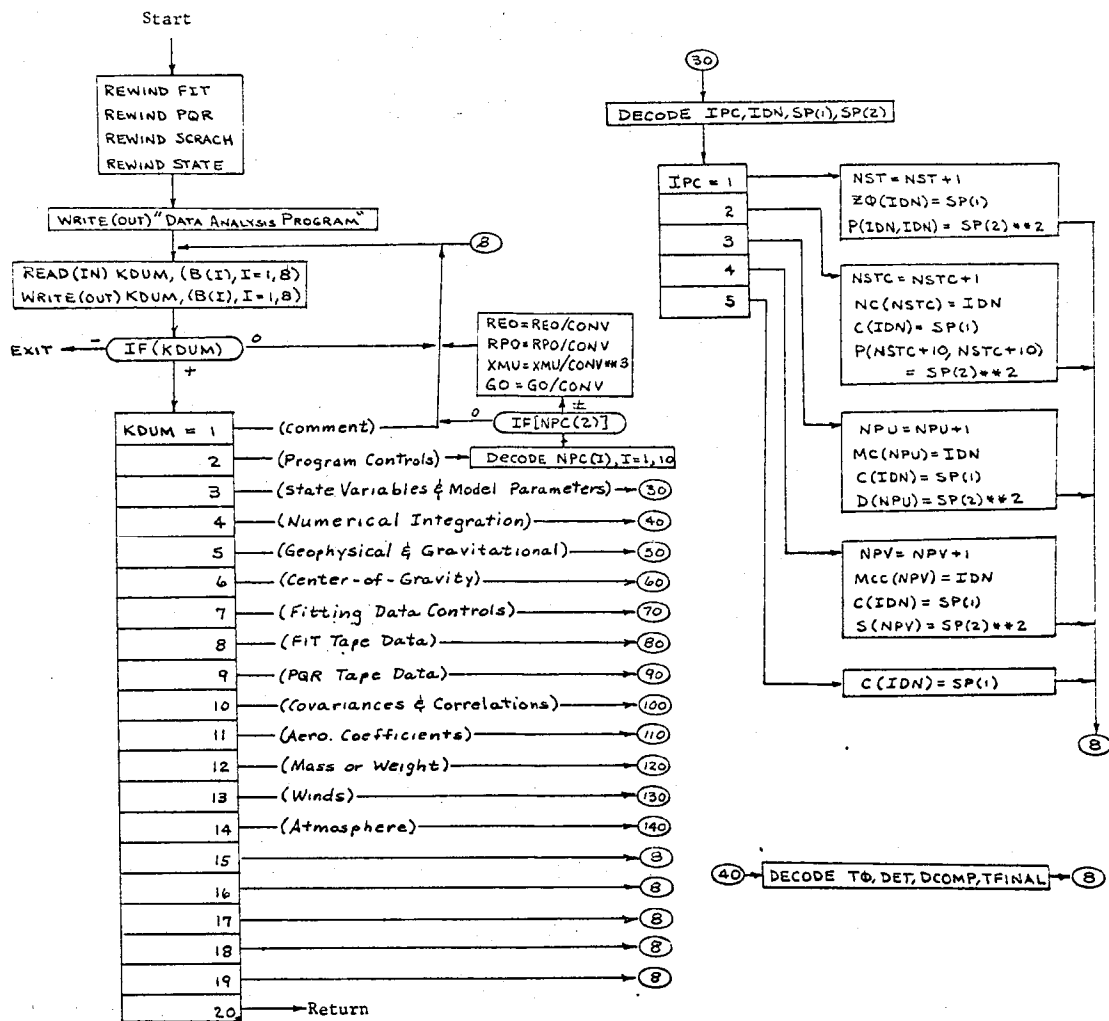
Subroutine FXXU (STEP1) - Continued



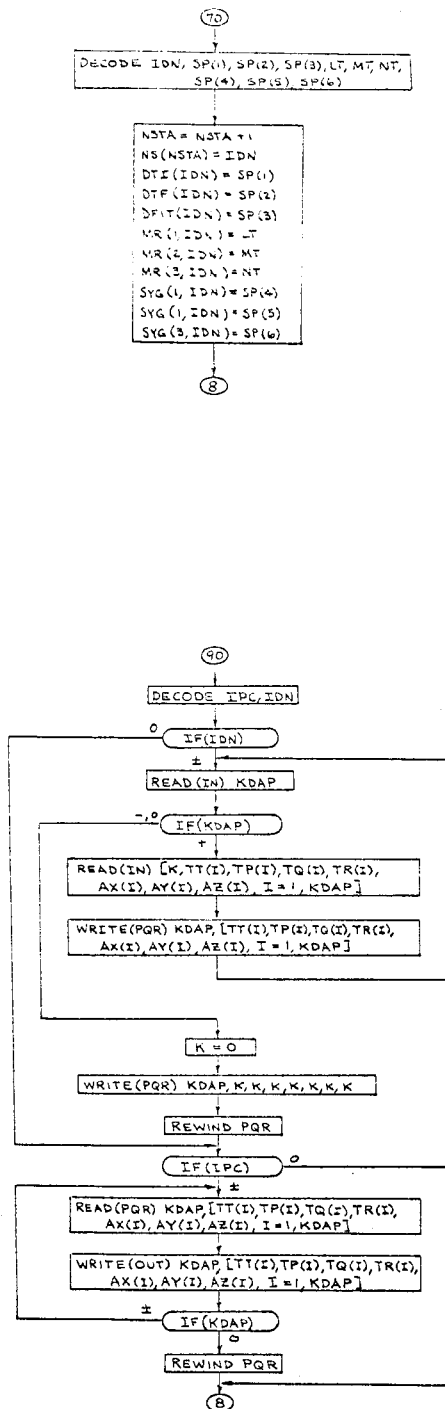
Subroutine FXXU (STEP1) - Continued



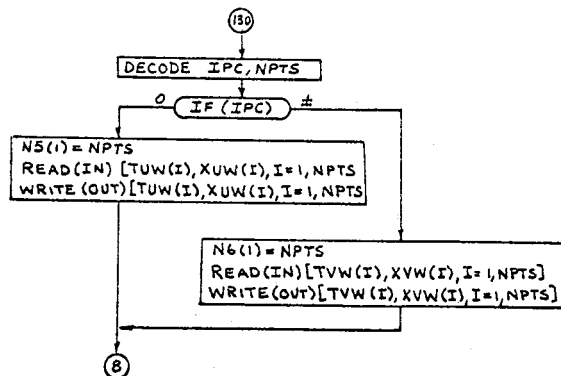
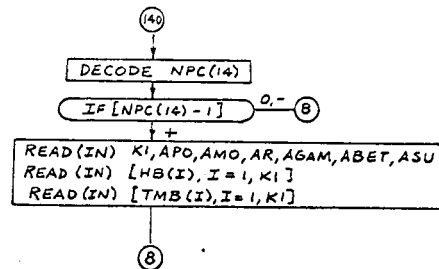
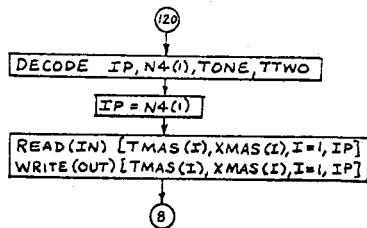
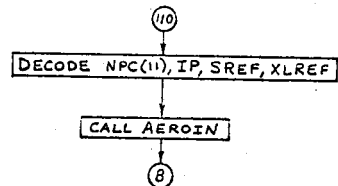
Subroutine FXXU (STEP2) - Continued



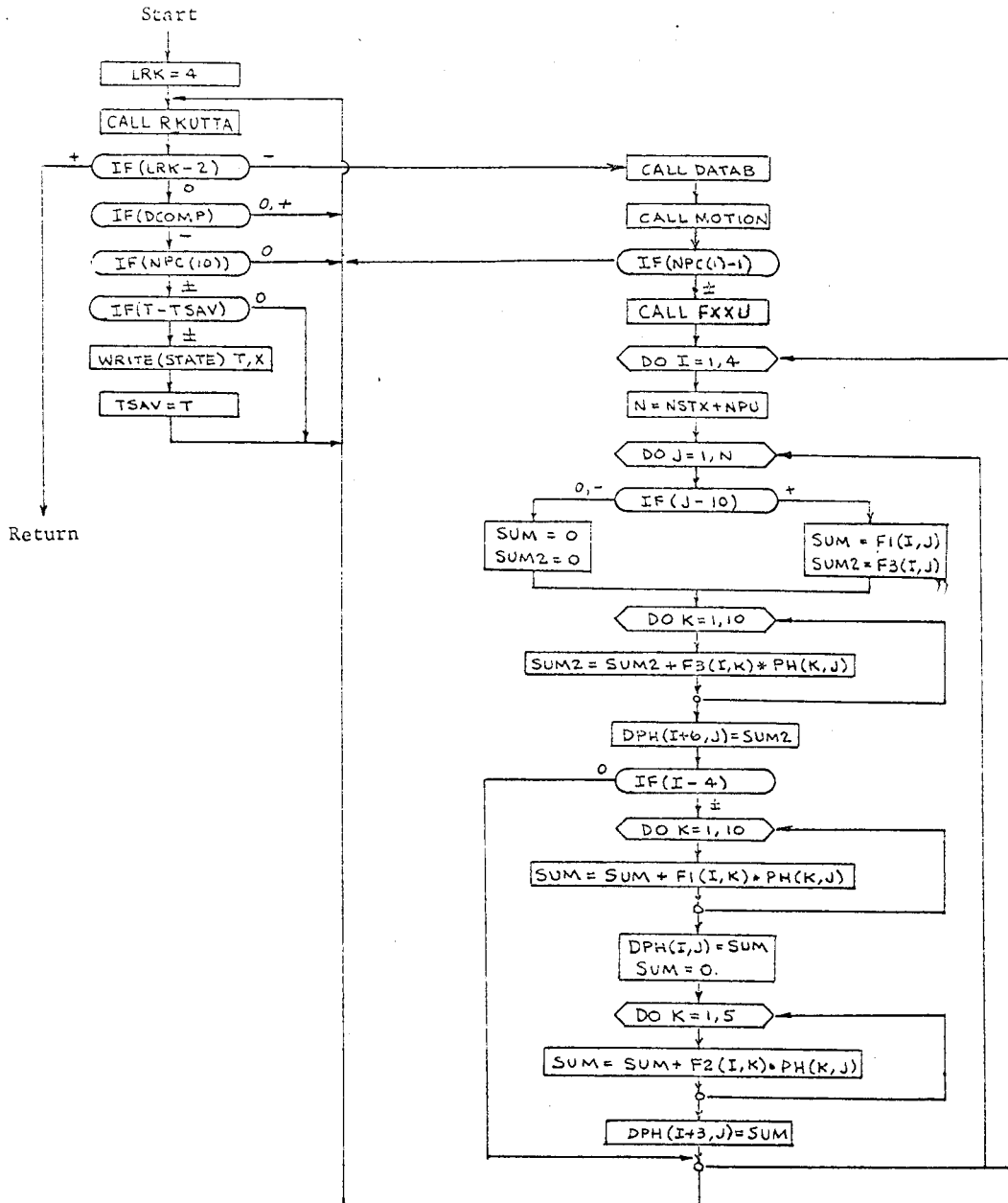
Subroutine INDAT



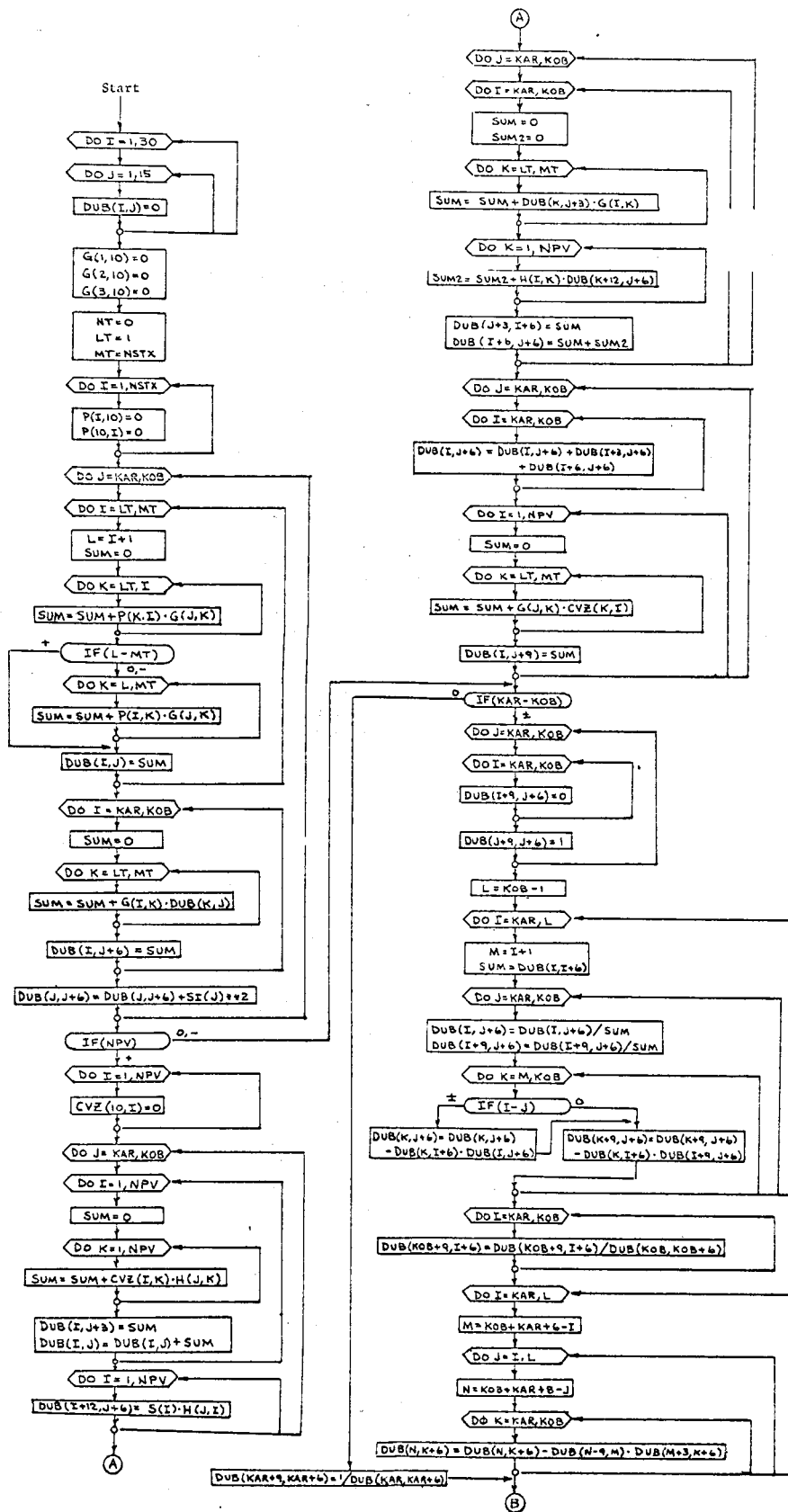
Subroutine INDAT - Continued



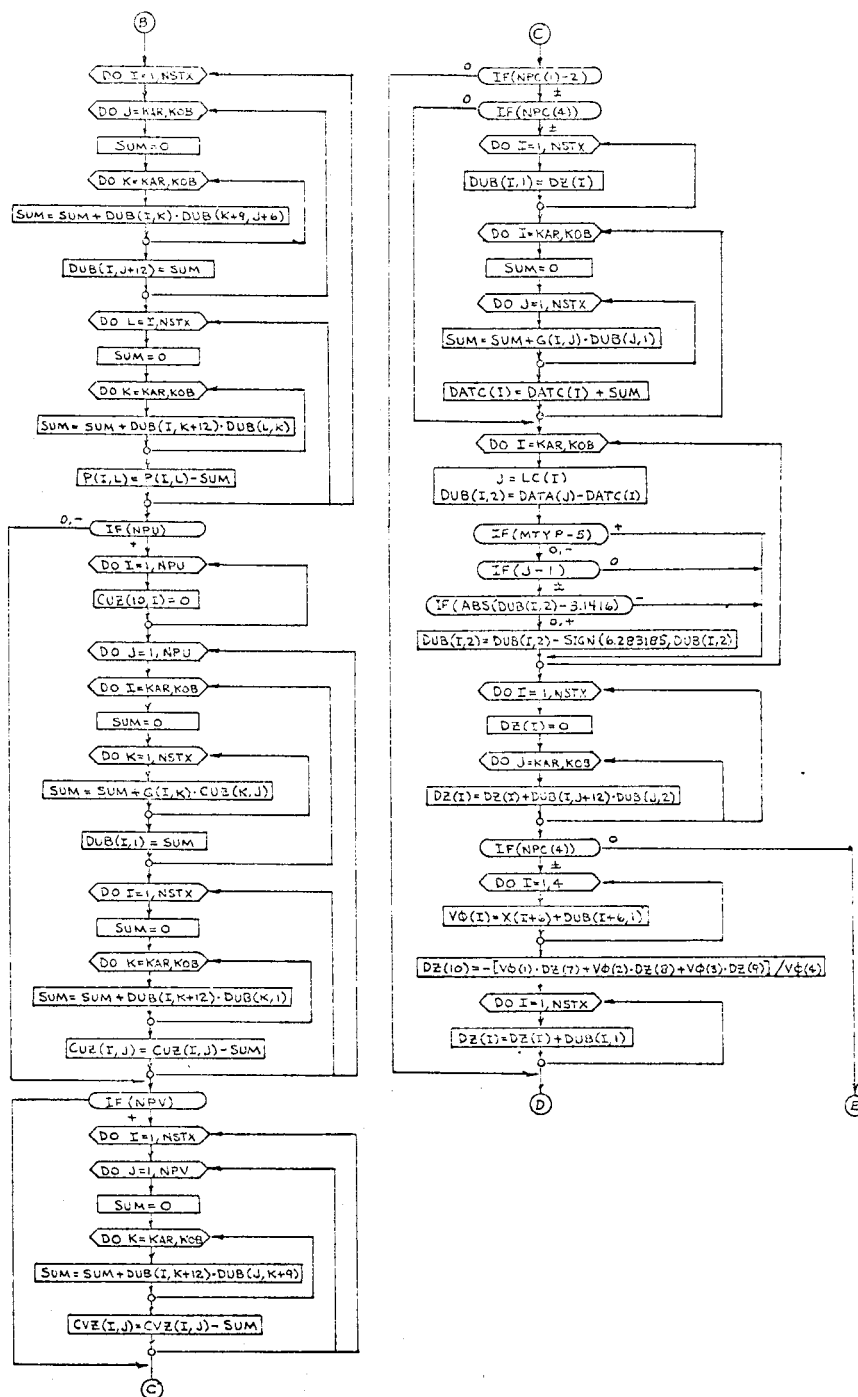
Subroutine INDAT - Concluded



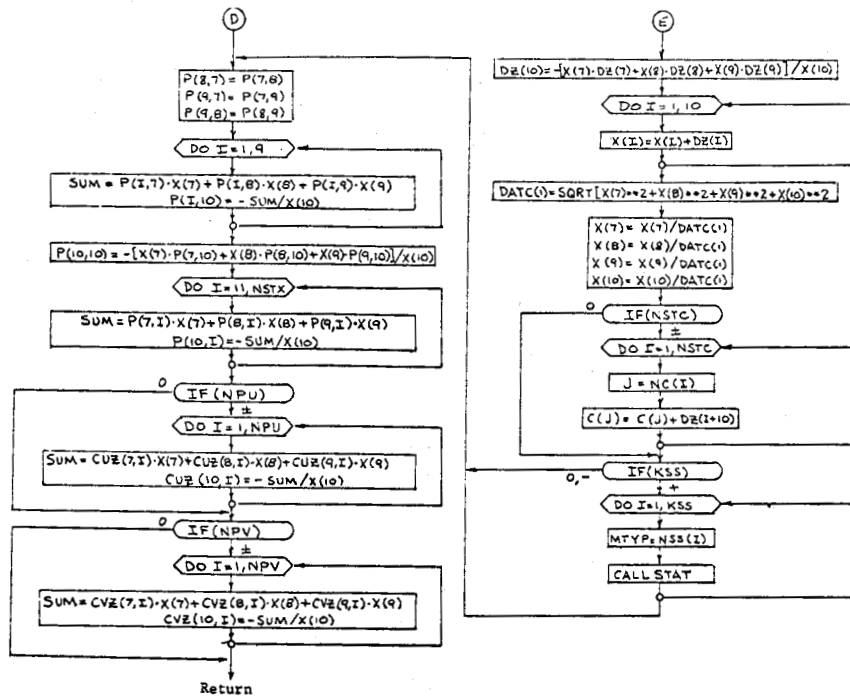
Subroutine INTAG



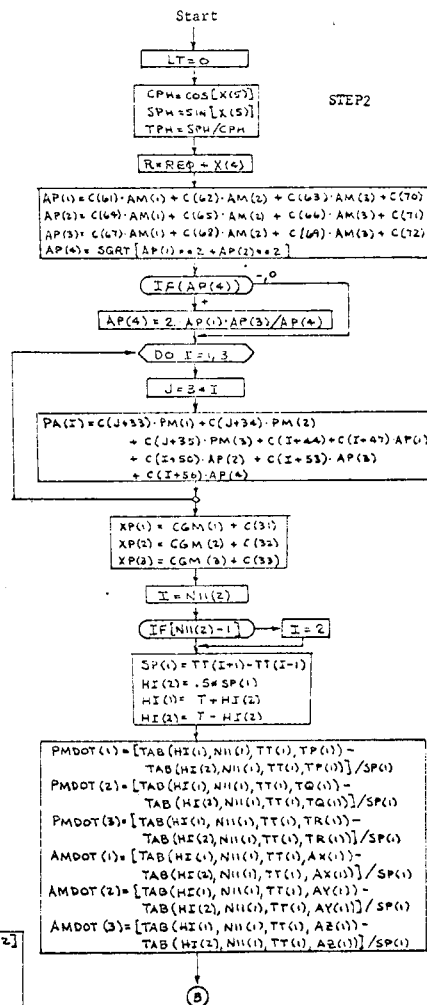
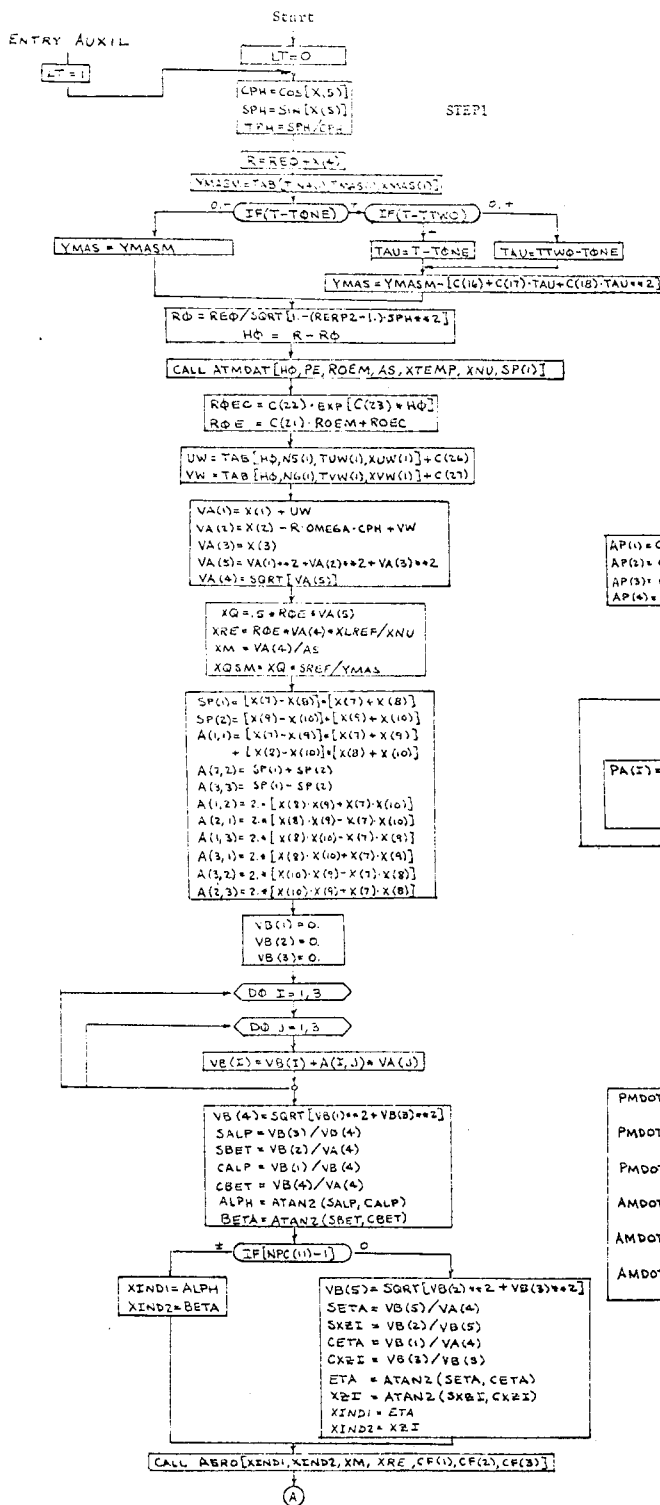
Subroutine MINVAR



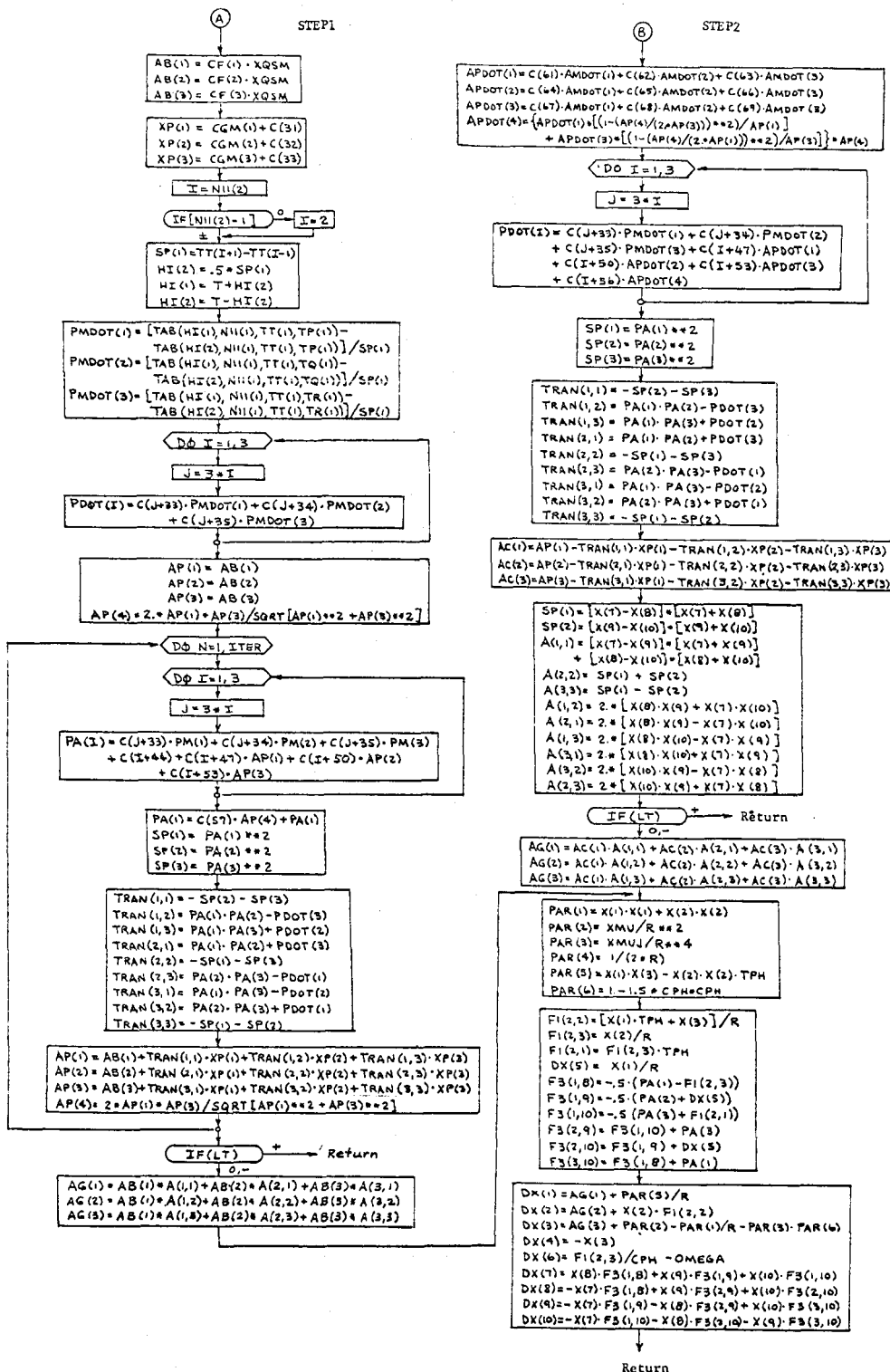
Subroutine MINVAR - Continued



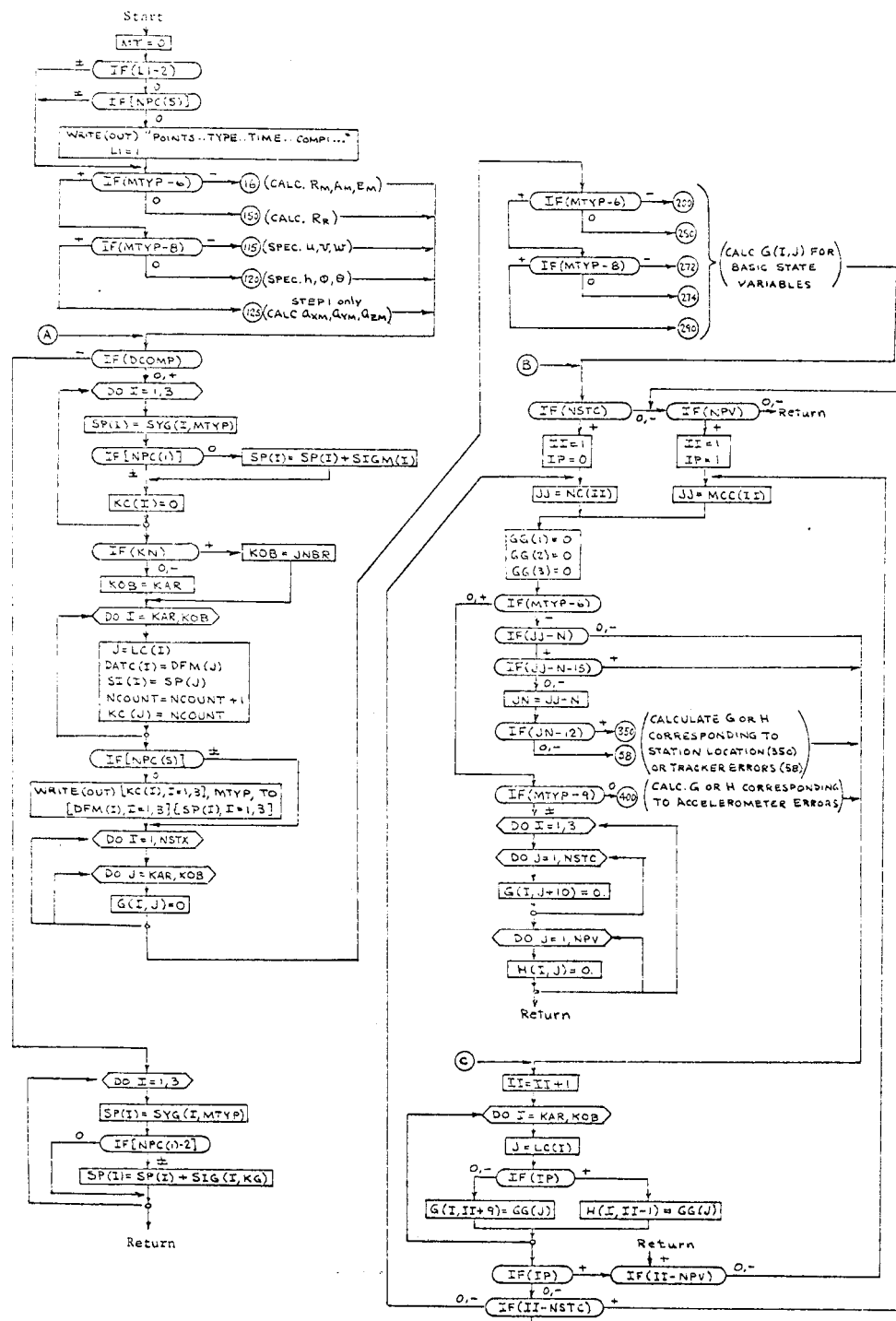
Subroutine MINVAR - Concluded



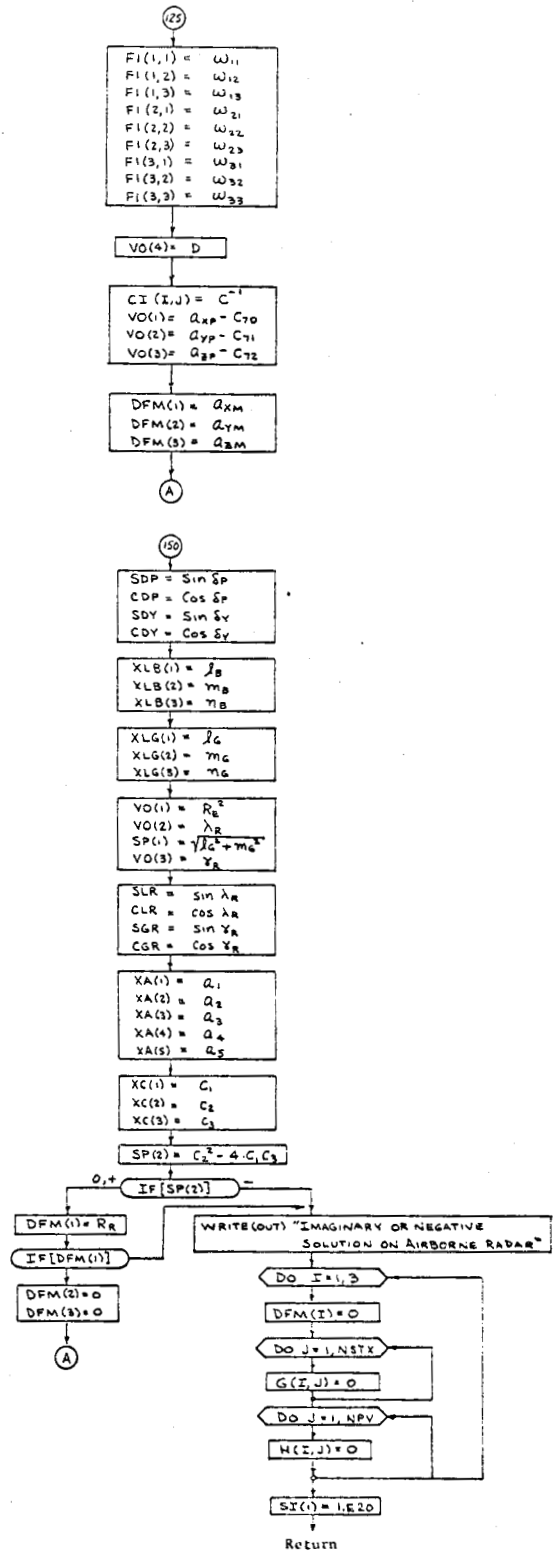
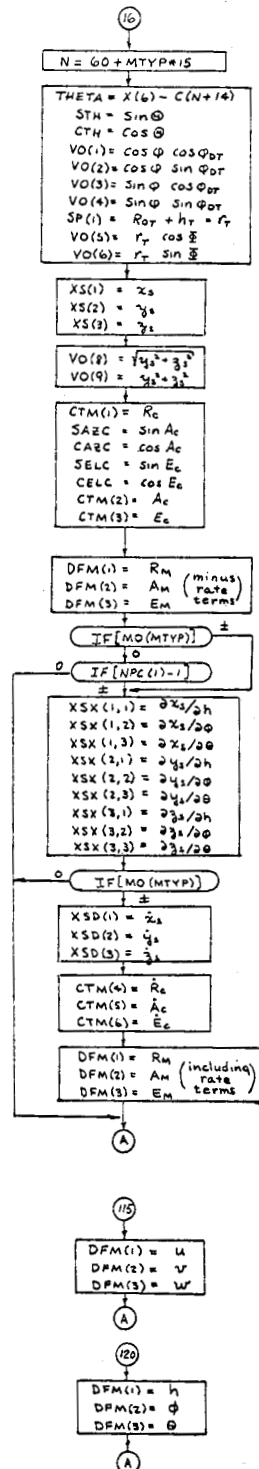
Subroutine MOTION



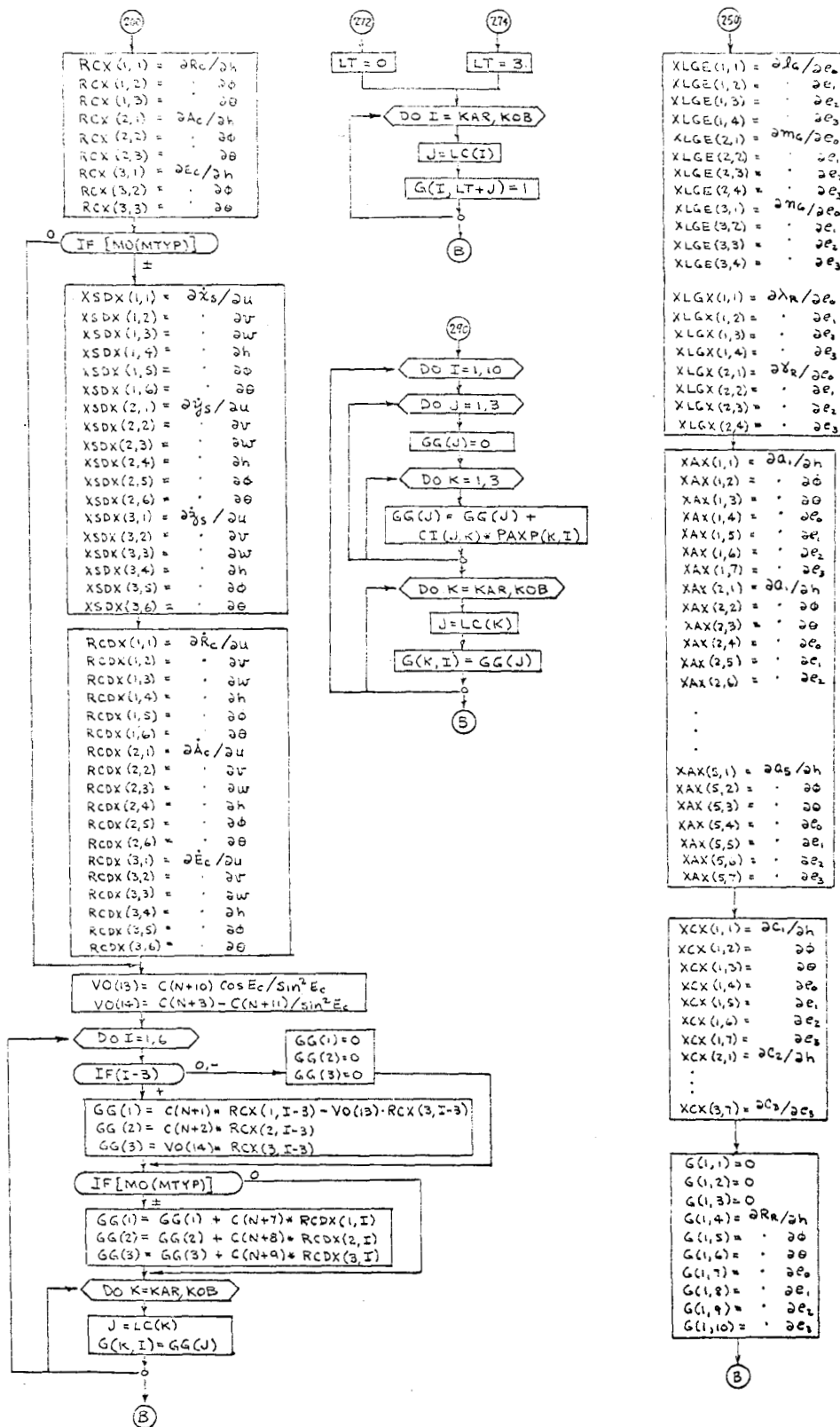
Subroutine MOTION - Concluded



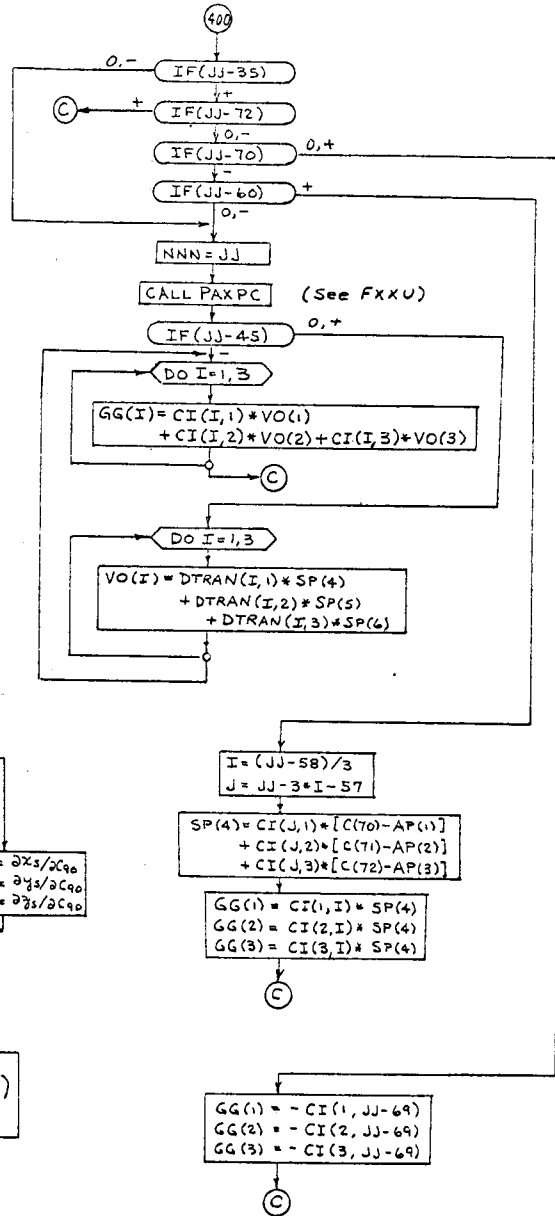
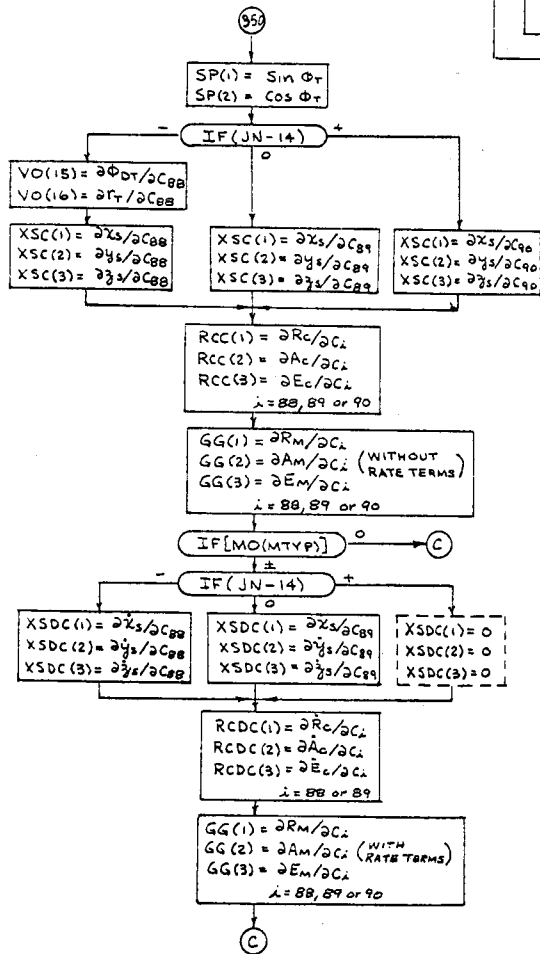
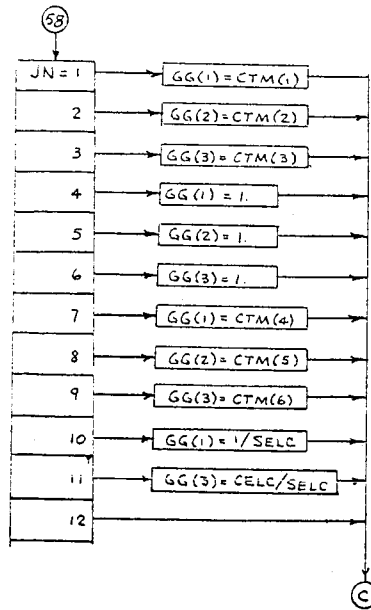
Subroutine OBSERV



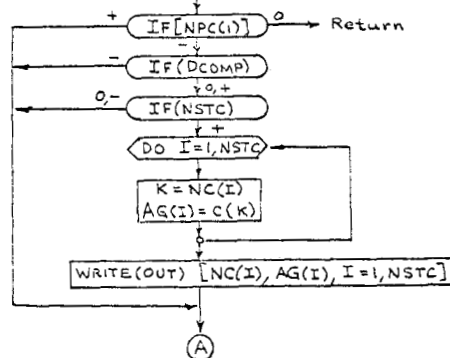
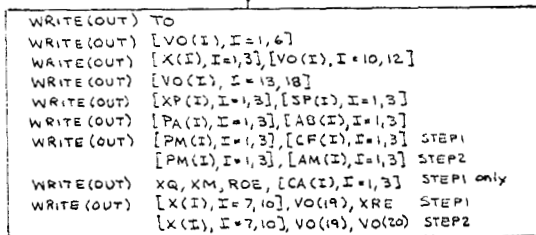
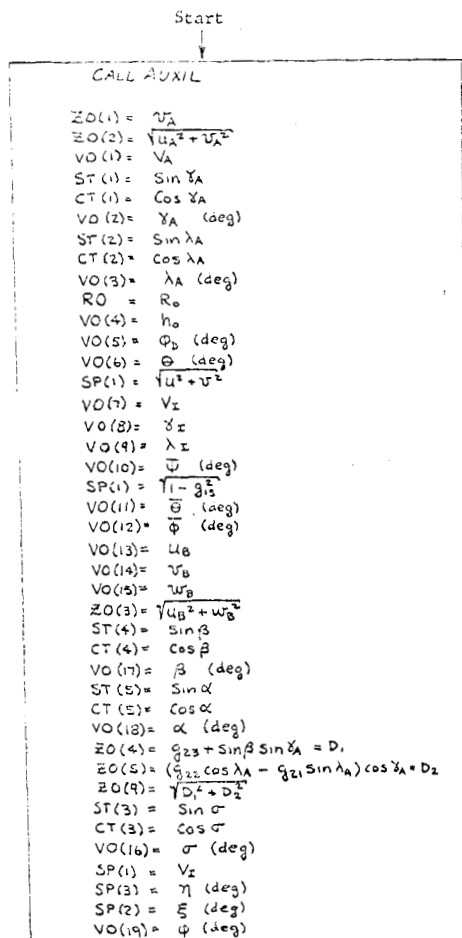
Subroutine OBSERV. - Continued



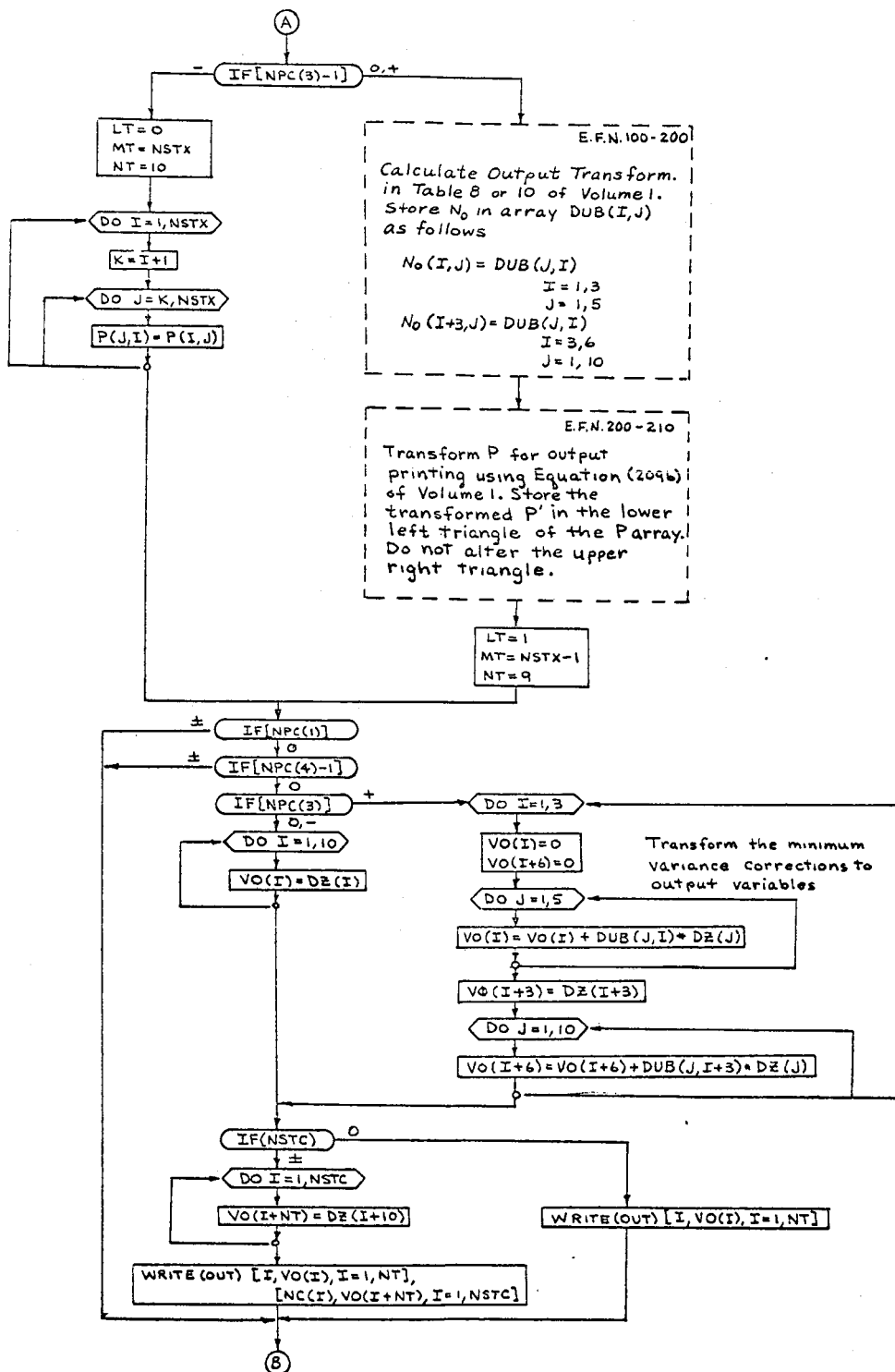
Subroutine OBSERV - Continued



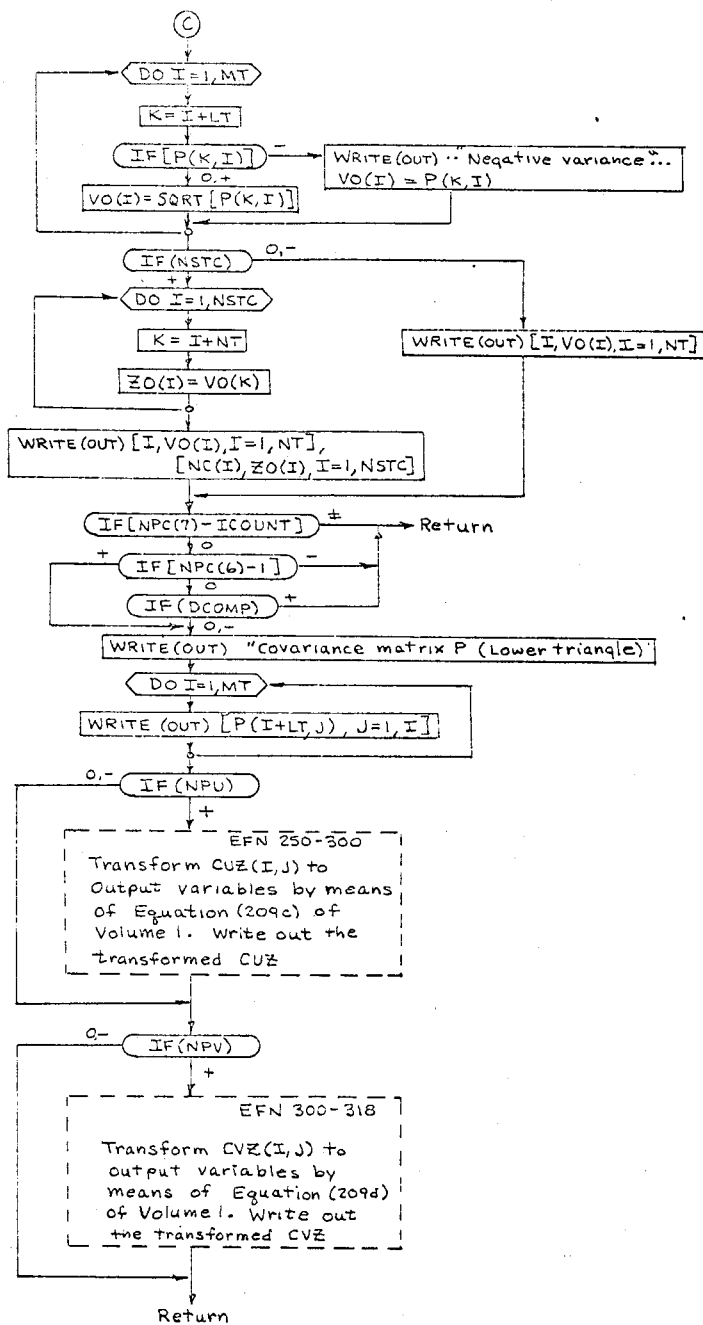
Subroutine OBSERV - Concluded



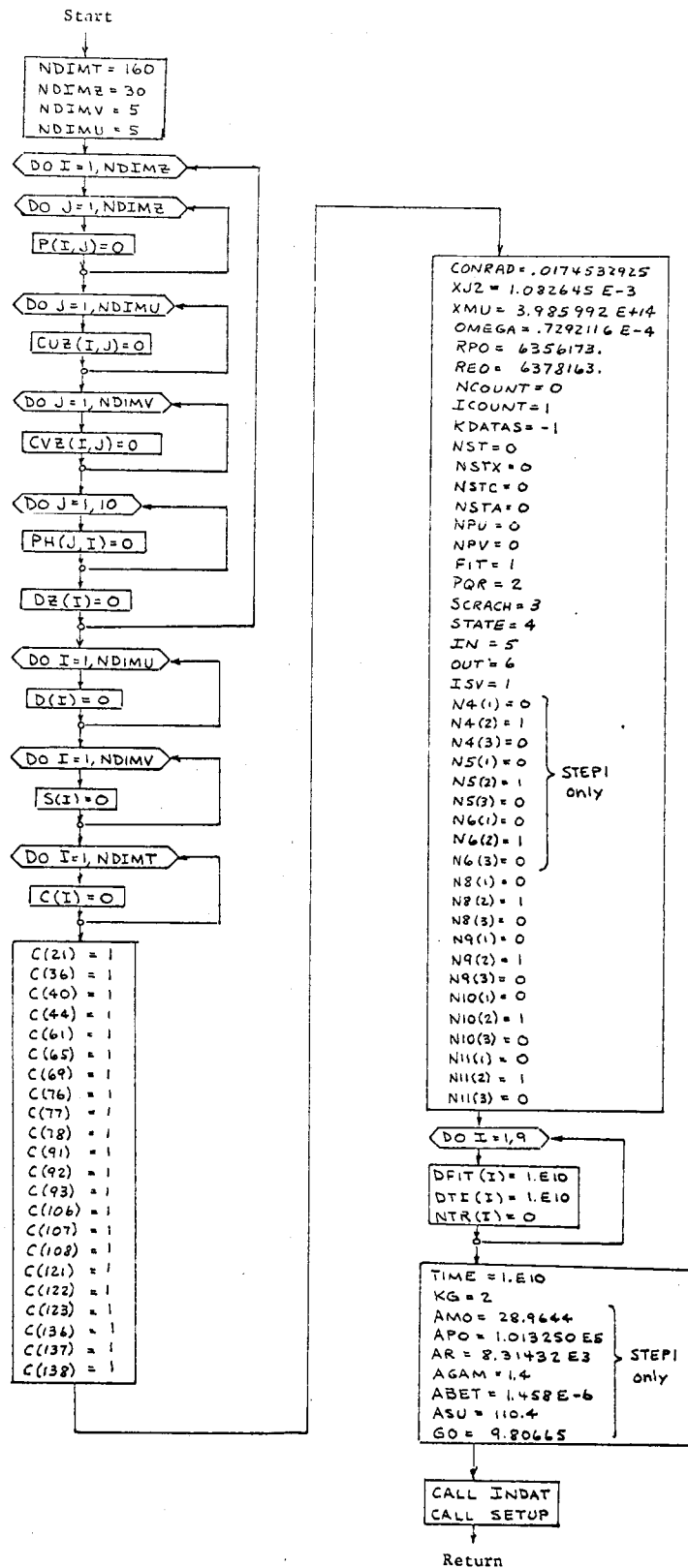
Subroutine OUTPUT

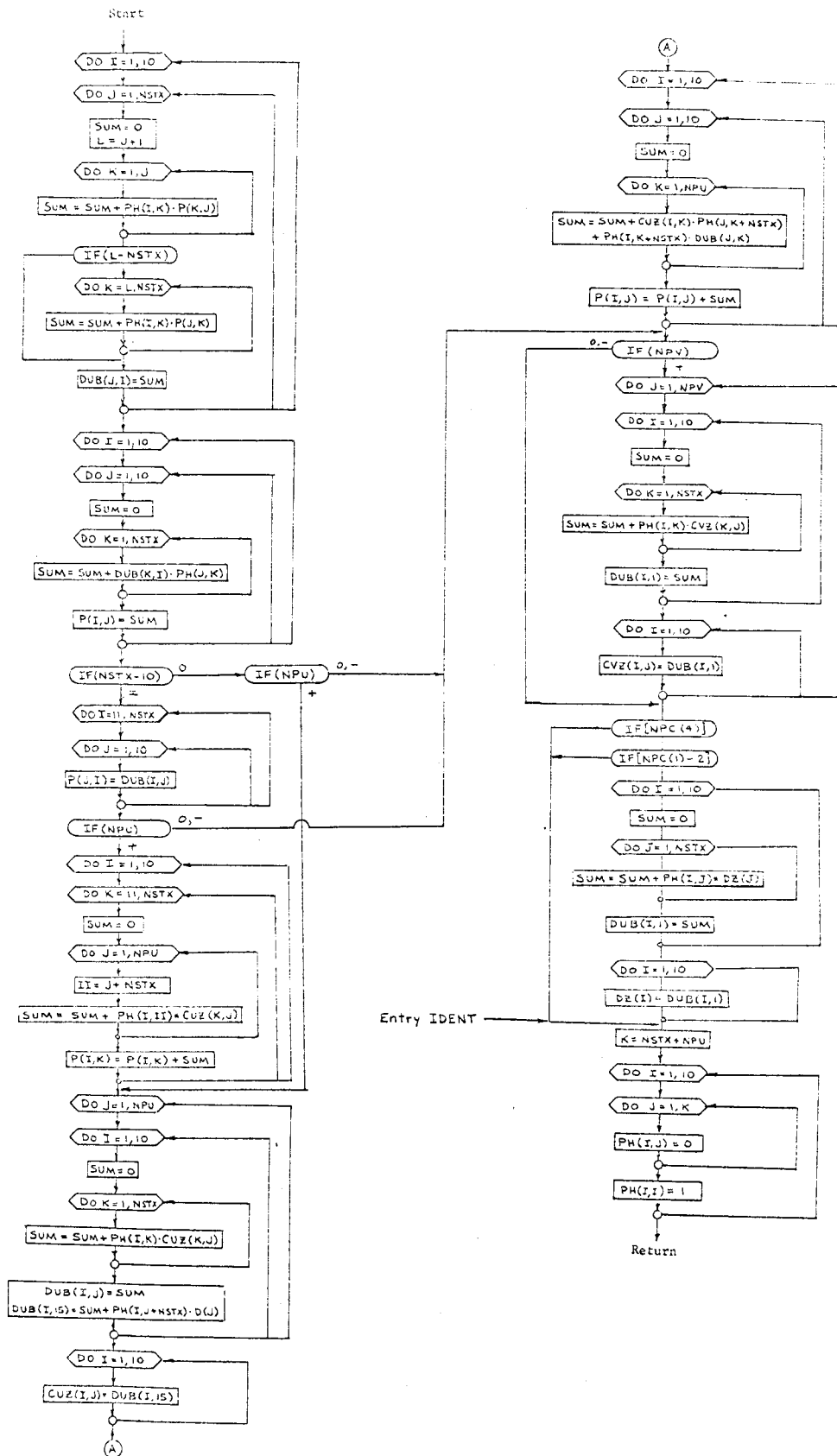


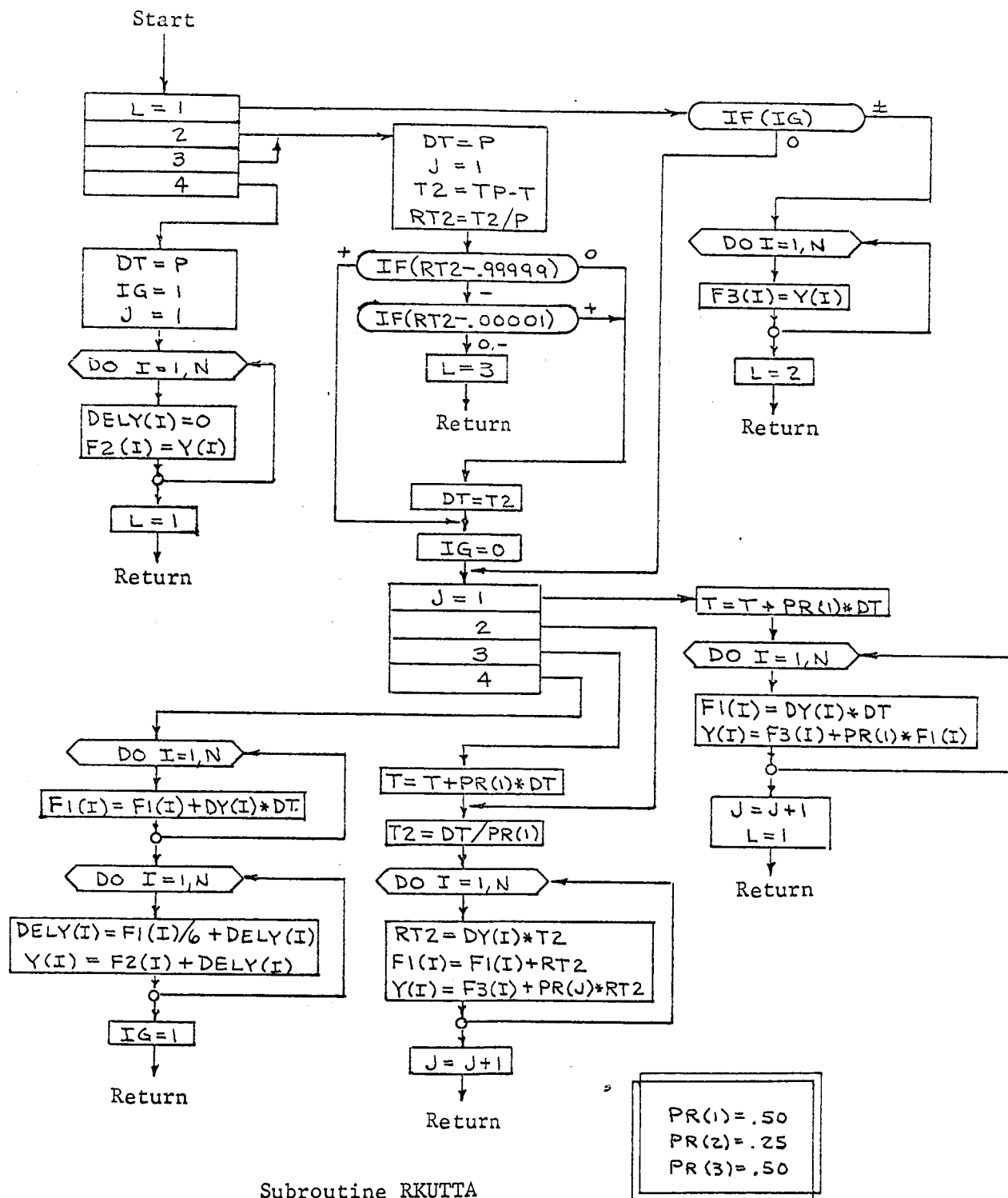
Subroutine OUTPUT - Continued

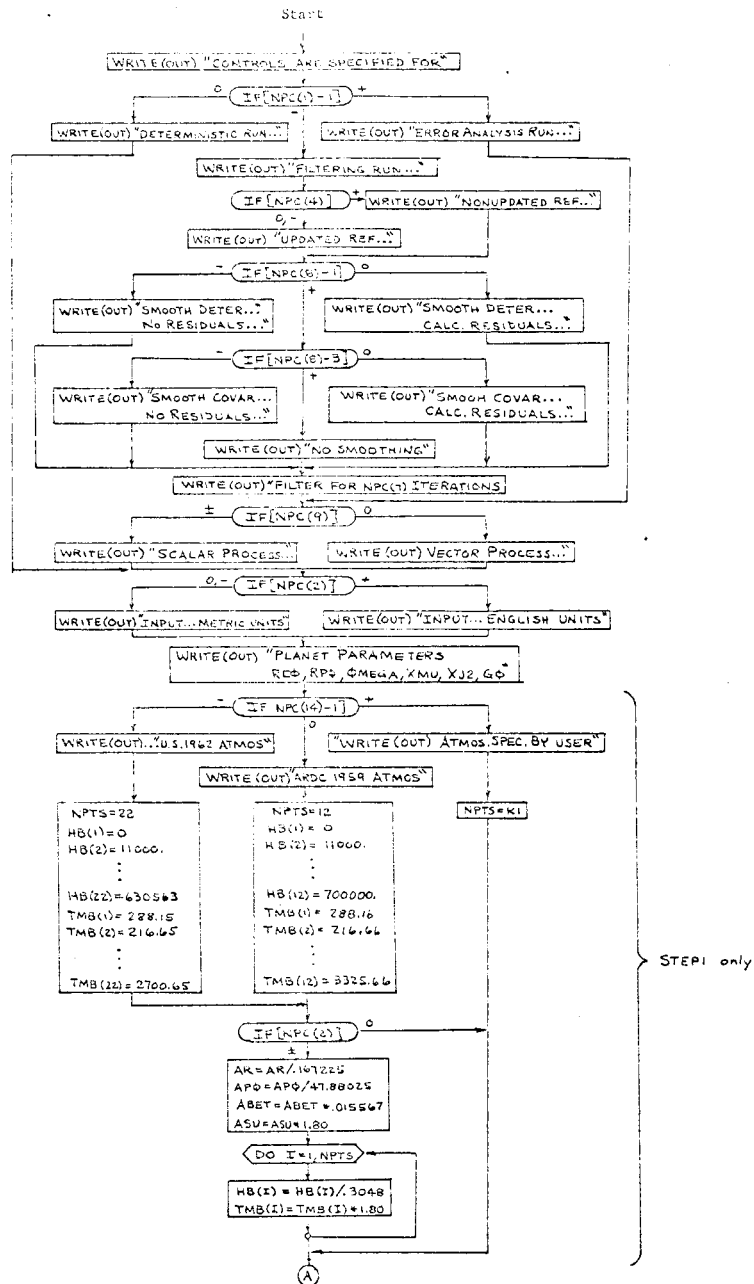


Subroutine OUTPUT - Concluded

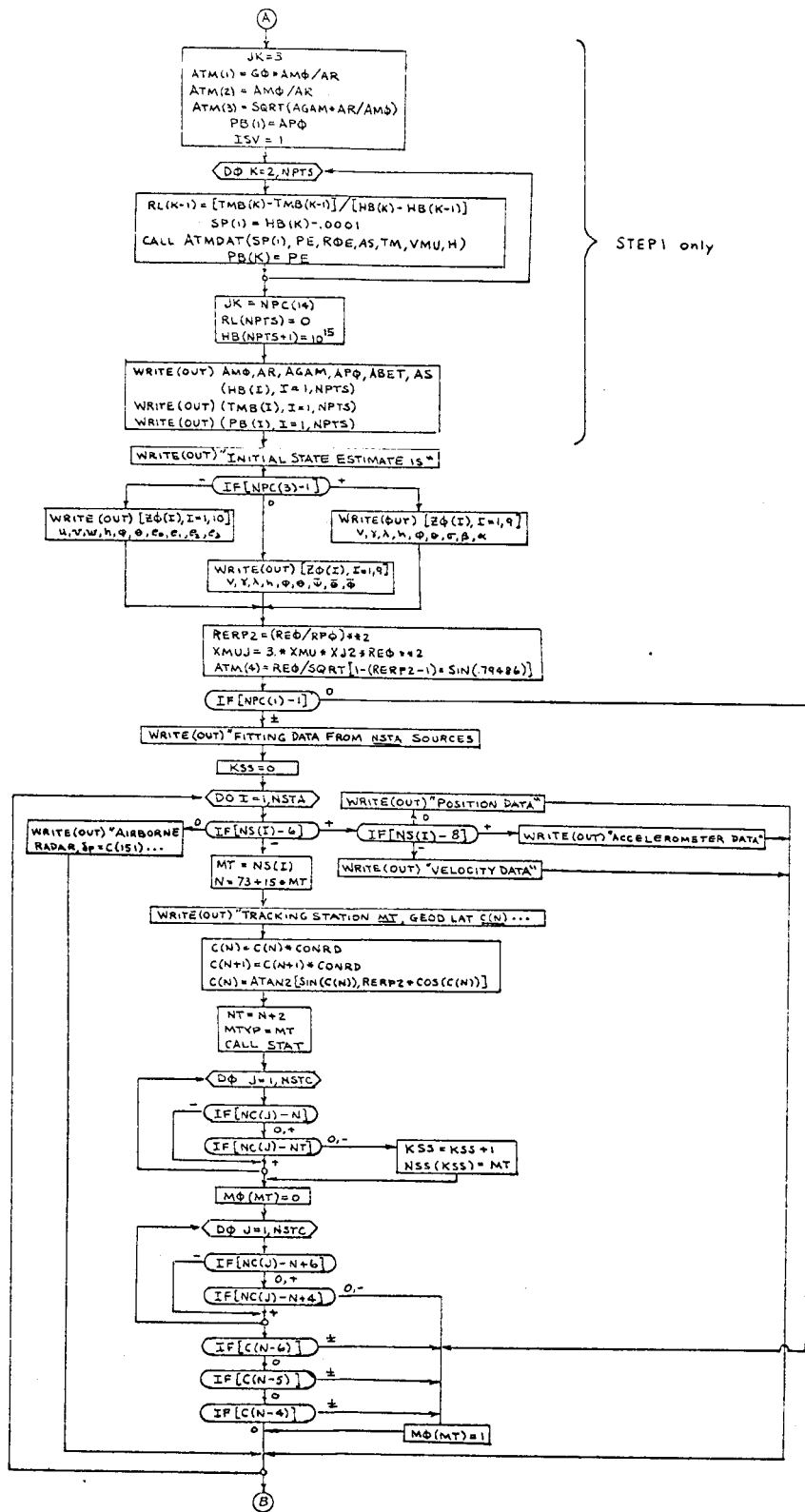




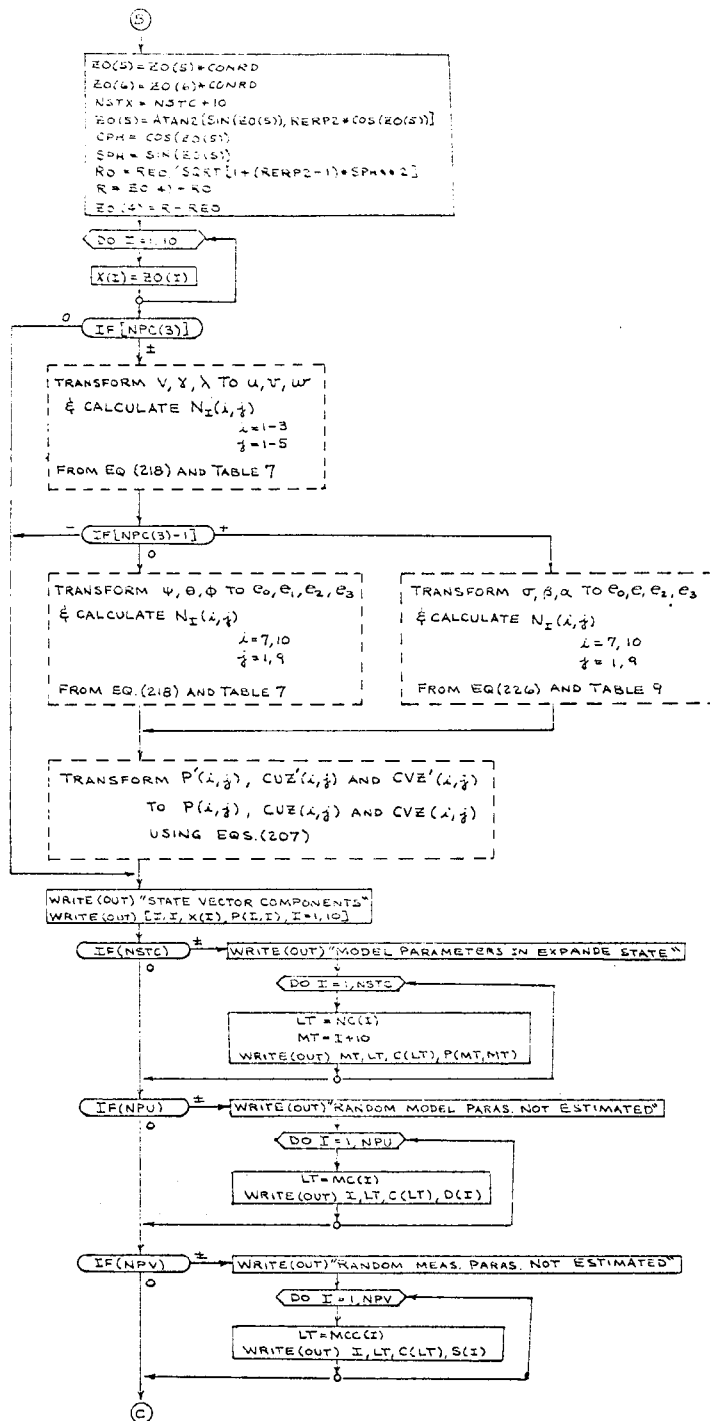




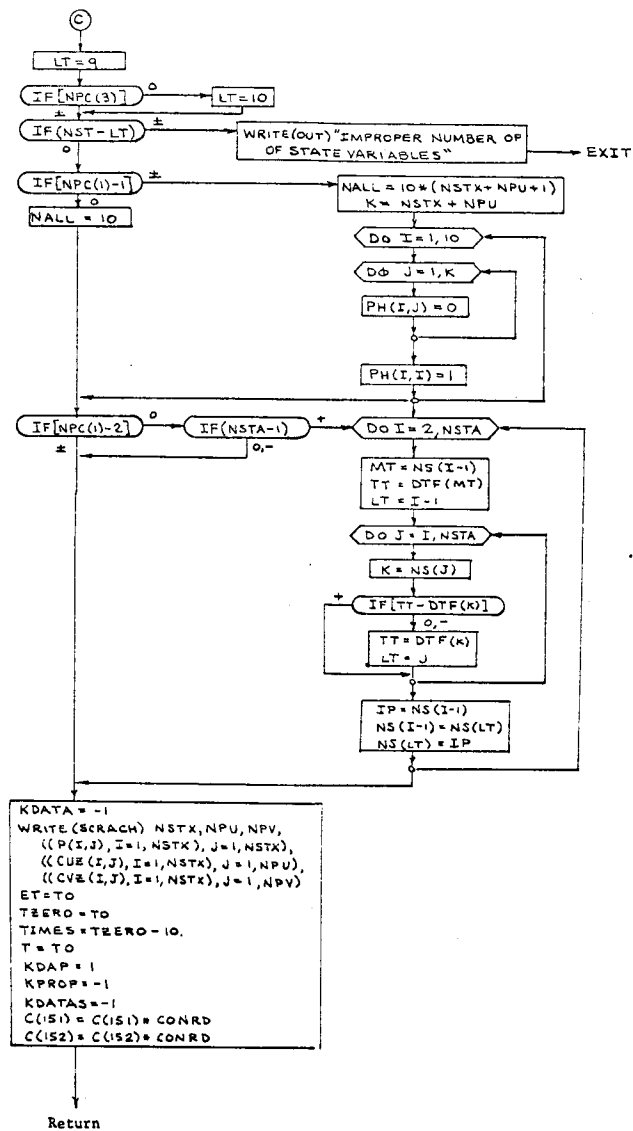
Subroutine SETUP



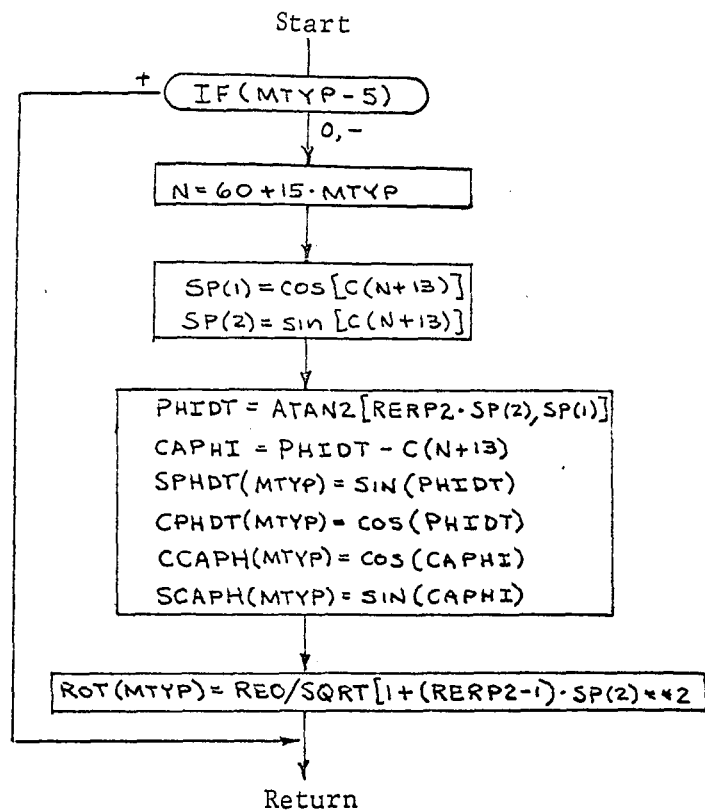
Subroutine SETUP - Continued



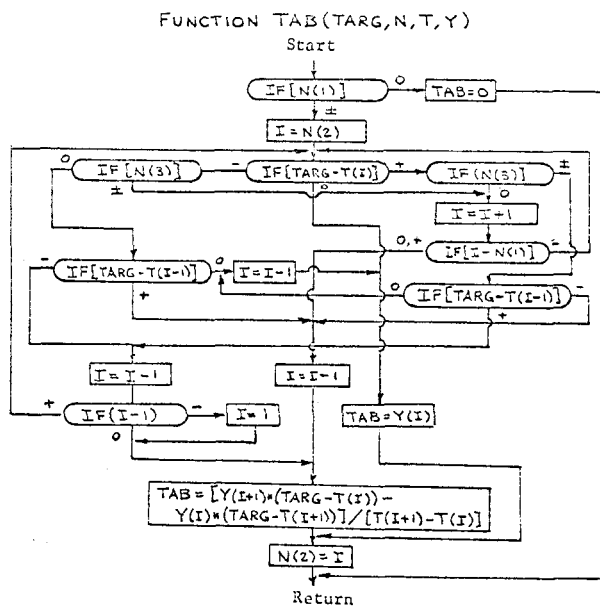
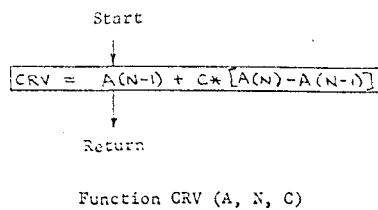
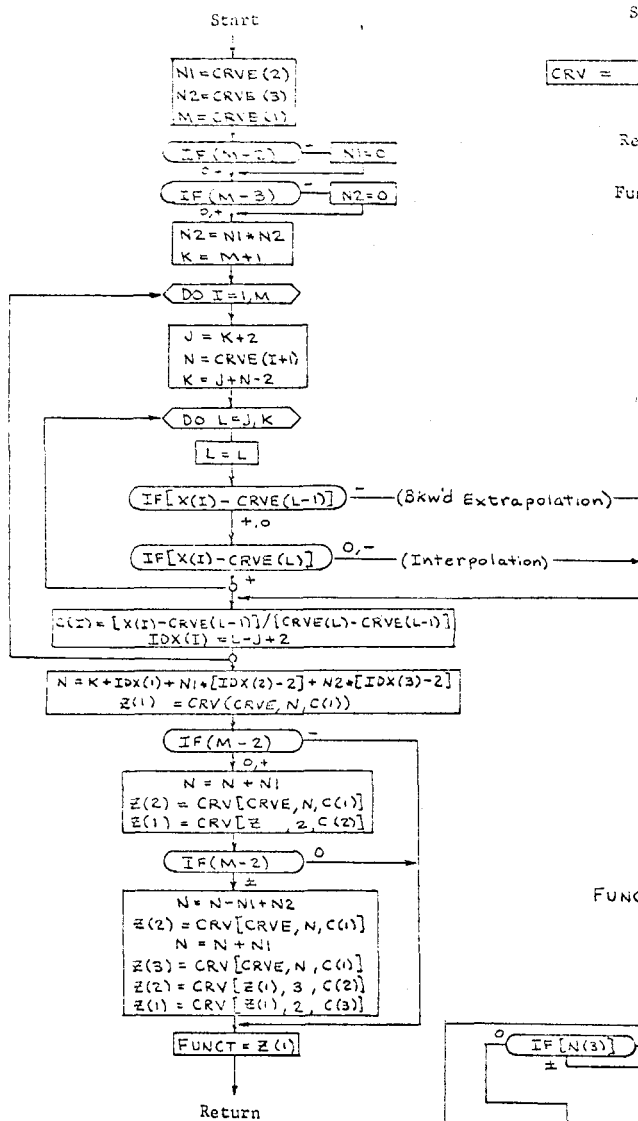
Subroutine SETUP - Continued



Subroutine SETUP - Concluded



Subroutine STAT



VII. SOURCE LISTING

A. STEP1 Listing

The STEP1 source listing is presented in the following subsection. The following listing indicates the pages on which the STEP1 subroutine listings appear:

MAIN	138
AERO	143
AEROIN	145
ATMDAT	148
DATAB	149
DERIVE	152
FUNCT & CRV	155
FXXU	156
INDAT	163
INTAG	168
MINVAR	170
MOTION	174
OBSERV	178
OUTPUT	188
PRESET	195
PROP	198
RKUTTA	201
SETUP	202
SMOOTH	211
STAT	214
TAB	215

The STEP2 listings commence on page 216.

```

PROGRAM MAIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,
2 TAPE7, TAPE1,TAPE2,TAPE3,TAPE4)
COMMON /INTGRL/ JCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRR
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DAD(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DADH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TIWG,TOW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XOSM,XRE,XTEMP,
8 XOW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TAICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VZ(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 P(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,I1,IP,IPC,JU,JN,KA,KD(3),KDUM,KG2
5 K1,NIN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RC,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KADP,KDATA,KDATAS,KG,KI,KK
6 KIN,KOL,KPRCP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 NIP(40),NTYP,NTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A NR(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TH1(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TI(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERC,XC2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPEN0/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /AIMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TM8(23)
COMMON /EXTRA/ GO
C-----STATISTICAL TRAJECTORY ESTIMATION PROGRAM, STEP1
C DEVELOPED BY W.E.WAGNER AND A.C.SEROLD
C MARTIN MARIETTA CORPORATION
C DENVER, COLORADO
2 CONTINUE
CALL PRESET
4 WRITE(OUT,1001)
IF(NPC(1).EQ.0) WRITE(OUT,1000) ICOUNT
1000 FORMAT(19H ITERATION NUMBER I2//)
1001 FORMAT(1H1)
10 IF(KDATA) 12,42,202
12 T2=TC
CALL INTAG
GO TO 44

```

24 T2=TIME	STP10160
IF(T2-ET)260,260,42	STP10170
30 IF(TO-ET) 34,32,32	STP10180
32 IF(JST.EQ.1) GO TO 44	STP10190
34 IF(KDATA) 38,36,36	STP10200
36 IF(KPROP.EQ.1) GO TO 24	STP10210
IF(KDATA) 10,40,10	STP10220
38 IF(NPC(1)-1) 200,40,100	STP10230
40 TIME=TFINAL+100.	STP10240
GO TO 24	STP10250
42 T2=ET	STP10260
C-----PROPAGATION LOOP, TO EFN 44	STP10270
CALL INTAG	STP10280
KPROP=1	STP10290
TO=T2	STP10300
CALL PROP	STP10310
44 CALL OUTPUT	STP10320
L1=2	STP10330
IF(ET-TFINAL) 46,50,50	STP10340
46 ET=ET+DET	STP10350
GO TO 34	STP10360
50 WRITE(SCRACH) KDATA	STP10370
IF(NPC(1).EQ.1) GO TO 2	STP10380
56 IF(NPC(4)) 300,58,300	STP10390
58 CALL SMOOTH	STP10400
IF(L1-1) 2,4,2	STP10410
C-----DETERMINE MEASUREMENT TIME FOR ERROR	STP10420
C	STP10430
100 IF(KPROP.GT.0) GO TO 24	STP10432
JST=1	STP10434
IF(NSTA-1) 40,102,104	STP10440
102 II = NS(1)	STP10450
GO TO 112	STP10460
104 II = NS(1)	STP10470
SP(1) = DTI(II)	STP10480
DO 110 I=2,NSTA	STP10500
J = NS(I)	STP10510
IF(SP(1)-DTI(J)) 110,106,107	STP10520
106 JST=JST+1	STP10530
GO TO 108	STP10540
107 JST=1	STP10550
108 SP(1) = DTI(J)	STP10560
II = J	STP10570
110 CONTINUE	STP10580
112 IF(DTI(II)-DTF(II)) 116,116,114	STP10590
114 NSTA=NSTA-1	STP10600
GO TO 100	STP10610
116 JNBR=0	STP10620
TIME=DTI(II)	STP10630
DTI(II)=DTI(II)+DTFII(II)	STP10640
DO 118 I=1,3	STP10650
IF(MR(I,II).EQ.0) GO TO 118	STP10660
JNBR=JNBR+1	STP10670
LC(JNBR)=I	STP10680
118 CONTINUE	STP10690
IF(JNBR.EQ.0) GO TO 100	STP10700
MTYP = II	STP10710
GO TO 24	STP10720
C-----DATA EDITING LOGIC FOR FILTER PROBLEMS, THRU EFN 250-----	STP10730
200 KG = 1	STP10740

KS = 1	STP10750
TYM(1) = TZERO - 10.	STP10760
GO TO 211	STP10770
202 KG=KG+1	STP10780
MTP(KG)=MTYPS	STP10790
TYM(KG)=TIMES	STP10800
DAT(1,KG)=DATAS(1)	STP10810
DAT(2,KG)=DATAS(2)	STP10820
DAT(3,KG)=DATAS(3)	STP10830
SIG(1,KG)=SIGMS(1)	STP10840
SIG(2,KG)=SIGMS(2)	STP10850
SIG(3,KG)=SIGMS(3)	STP10860
KDATA=KDATAS	STP10870
MTYP=MTYPS	STP10880
TIME=TIMES	STP10890
DATA(1)=DATAS(1)	STP10900
DATA(2)=DATAS(2)	STP10910
DATA(3)=DATAS(3)	STP10920
SIGM(1)=SIGMS(1)	STP10930
SIGM(2)=SIGMS(2)	STP10940
SIGM(3)=SIGMS(3)	STP10950
LC(1)=LCS(1)	STP10960
LC(2)=LCS(2)	STP10970
LC(3)=LCS(3)	STP10980
UNBR=UNBRS	STP10990
204 IF(K1-KS) 206,208,208	STP11000
206 K1=K1+1	STP11010
GO TO 216	STP11020
208 KS=KG	STP11030
210 CONTINUE	STP11040
211 IF(KDATAS.EQ.0) GO TO 212	STP11050
READ(FIT) KDATAS,(MTP(KS+1),TYM(KS+1),(DAT(J,KS+1),J=1,3),(SIG(J	STP11060
X,KS+1),J=1,3),I=1,KDATAS)	STP11070
KS=KS+KDATAS	STP11080
IF(KS-20) 210,215,215	STP11090
212 IF(KG+1-KS) 215,213,213	STP11100
213 KDATA=0	STP11110
GO TO 248	STP11120
215 K1=KG+1	STP11130
216 MTYPS=MTP(K1)	STP11140
TIMES=TYM(K1)	STP11150
IF(TIMES.GT.7FINAL) GO TO 213	STP11160
IF(NTR(MTYPS)) 220,218,220	STP11170
218 IF(TIMES.LT.DII(MTYPS)) GO TO 204	STP11180
TFIT(MTYPS)=TIMES	STP11190
NTR(MTYPS)=1	STP11200
220 CONTINUE	STP11210
222 IF(TIMES-DIF(MTYPS)) 224,224,204	STP11220
224 IF(TIMES-TFIT(MTYPS)) 226,234,228	STP11230
226 NTR(MTYPS)=J	STP11240
GO TO 204	STP11250
228 IF(NTR(MTYPS)-3) 230,232,230	STP11260
230 TFIT(MTYPS)=TFIT(MTYPS)+DFIT(MTYPS)	STP11270
NTR(MTYPS)=3	STP11280
GO TO 224	STP11290
232 TFIT(MTYPS)=TIMES	STP11300
234 NTR(MTYPS)=2	STP11310
UNBRS=0	STP11320
DO 238 I=1,3	STP11330
IF(MK(I,MTYPS)) 236,238,236	STP11340

236	JNBR=JNBR+1	STP11350
	LCS(JNBR)=1	STP11360
238	CONTINUE	STP11370
	IF(JNBR) 240,204,240	STP11380
240	DATAS(1)=DAT(1,K1)	STP11390
	DATAS(2)=DAT(2,K1)	STP11400
	DATAS(3)=LAT(3,K1)	STP11410
	SIGMS(1)=SIG(1,K1)	STP11420
	SIGMS(2)=SIG(2,K1)	STP11430
	SIGMS(3)=SIG(3,K1)	STP11440
	IF(KDATA) 242,244,244	STP11450
242	KDATA=2	STP11455
	IF(TIMES-TZERO) 204,202,202	STP11460
244	IF(TIMES-TIME) 248,246,248	STP11470
246	JST=2	STP11480
	GO TO 250	STP11490
248	JST=1	STP11500
250	GO TO 24	STP11510
C-----PROCESSING LOOP, THRU EFN 278-----		STP11520
260	CALL INTAG	STP11530
	T0=T2	STP11540
	KPROP=0	STP11550
	KN=0	STP11560
	KK = 1	STP11570
	IF(JNBR-1) 270,270,262	STP11580
262	IF(NPC(9)) 268,264,268	STP11590
264	KN=1	STP11600
	GO TO 270	STP11610
268	KK=JNBR	STP11620
	IF(NPC(4)) 264,270,264	STP11630
270	KAR=1	STP11640
272	CALL OBSERV	STP11650
273	IF(T-TSAV) 274,276,274	STP11660
274	CALL PROP	STP11670
	TSAV=T	STP11680
276	IF(NPC(9).NE.0) KOB = KAR	STP11690
	CALL MINVAR	STP11700
	IF(KAR-KK) 278,30,30	STP11710
278	KAR=KAR+1	STP11720
	IF(KN.NE.0) GO TO 276	STP11730
	CALL MOTION	STP11740
	GO TO 272	STP11750
C-----UPDATE STATE, EQ.(55A), THRU EFN 312-----		STP11760
300	DO 306 I=1,10	STP11770
	SUM=0.	STP11780
	DO 304 K=1,10	STP11790
304	SUM=SUM+PH(I,K)*DZ(K)	STP11800
306	DUD(I)=SUM	STP11810
	DO 312 I=1,NSTX	STP11820
	IF(I-10) 308,308,310	STP11830
308	DZ(I)=DUD(I)	STP11840
	X(I)=X(I)+DZ(I)	STP11850
	GO TO 312	STP11860
310	K=NC(I-10)	STP11870
	C(K)=C(K)+DZ(I)	STP11880
	VO(I-10)=C(K)	STP11890
312	CONTINUE	STP11900
C-----NORMALIZE QUATERNION-----		STP11910
	DATC(1)= X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2	STP11920
	X(7) = X(7)/DATC(1)	STP11930

X(8) = X(8)/DATC(1)	STP11940
X(9) = X(9)/DATC(1)	STP11950
X(10)=X(10)/DATC(1)	STP11960
C-----UPDATE TRACKING STATION LOCATIONS-----	STP11970
IF(KSS.LL.0) GO TO 316	STP11980
DO 314 I=1,KSS	STP11990
MTYP=NSS(I)	STP12000
314 CALL STAT	STP12010
316 WRITE(OUT,1003)	STP12020
1003 FORMAT(39H UPDATED MODEL PARAMETERS AT FINAL TIME)	STP12030
WRITE(OUT,1002) (NC(I),VO(I),I=1,NSTC)	STP12040
1002 FORMAT(8(2F 0.13,E15.8))	STP12050
GO TO 58	STP12060
END	STP12070

```

SUBROUTINE AERO (ARG1,ARG2,ARG3,ARG4,XX,YY,ZZ)
COMMON /INTGRL/ LCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40), COMM0010
* NALL,LRK COMM0020
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA, COMM0030
1 CF(3),JCS,CAZ1,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH, COMM0040
2 DRDP,DWUH(2),ETA,HC,N4(3),N5(3),N6(3),PAXP(3,30), COMM0050
3 PE,ROE,ROEC,ROEM,SALP,SBET, COMM0060
4 SETA,SREF,SXZ1,TAU,TMAS(20),TONE, COMM0070
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5), COMM0080
6 VW,XIND1,XIND2,XLREF,XM, COMM0090
7 XMAS(20),XNU,XQ,XCSM,XRE,XTEMP, COMM0100
8 XUV(20),XVW(20),XZI,YMAS,YMASM, COMM0110
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5), COMM0120
1 TPH,VC(20),ZO(20),AG(3),AMDOT(3),APDOT(4), COMM0130
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4), COMM0140
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2), COMM0150
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2, COMM0160
5 K1,NWN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6), COMM0170
6 RO,SPD(5),SPH,TRAN(3,3),XX(50), COMM0180
DIMENSION DUB(30,15) COMM0190
EQUIVALENCE (AG(1),DUB(1,1)) COMM0200
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40), COMM0210
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5), COMM0220
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3), COMM0230
3 LET,DFIT(9),DTF(9),DTI(9),DZ(30),ET, COMM0240
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST, COMM0250
5 K,KAR,KC(3),KDAP,KDATA,KG,KI,KK, COMM0260
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT, COMM0270
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT, COMM0280
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15), COMM0290
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9), COMM0300
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30), COMM0310
B PA(3),PM(3),R,REO,RERP2, COMM0320
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40), COMM0330
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL, COMM0340
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40), COMM0350
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20), COMM0360
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20), COMM0370
H XYCG(20),XZCG(20), COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR COMM0390
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR COMM0400
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK COMM0410
A PB(23),RL(23),TMB(23), COMM0420
COMMON /EXTRA / GO COMM0430
COMMON /AERTAB/ TABLES(580,3),SAVIND(3,3), AER00010
DIMENSION TCX(580),TCY(580),TCZ(580),ISTORE(1), AER00020
EQUIVALENCE (TCX,TABLES(1,1)),(TCY,TABLES(1,2)),(TCZ,TABLES(1,3)), AER00030
1 (ISTORE(1),KD(1)) AER00040
C *** STORE THE INDEPENDENT ARGUMENTS AER00050
ST(1)=ARG1 AER00060
ST(2)=ARG2 AER00070
ST(3)=ARG3 AER00080
C *** INITIALIZE TABLE-LOOKUP-VALUES ARRAY AER00090
60 SP(1)=0. AER00100
SP(2)=0. AER00110
SP(3)=0. AER00120
C *** FIND ALL AERODYNAMIC COEFFICIENTS AER00130
DO 90 L=1,3 AER00140
DUD=TABLES(1,L) AER00150

```

IF(DUD.NE.-1.) GO TO 10	AER00160
SP(L)=0.	AER00170
GO TO 90	AER00180
10 IF(DUD.NE.0) GO TO 15	AER00190
SP(L)=TABLES(5,L)	AER00200
GO TO 90	AER00210
15 J=1	AER00220
K=1	AER00230
NPTS=DUD	AER00240
C *** DELETE INDEPENDENT ARGUMENTS HAVING VALUE ZERO - - -	AER00250
C *** FOR PURPOSES OF TABLE LOOK-UP	AER00260
DO 40 I=1,NPTS	AER00270
J=K+1	AER00280
C IF(J.GT.4) * * * * * ERROR MESSAGE	AER00290
DO 20 K=J,4	AER00300
K=K	AER00310
M=K-1	AER00320
IF(SAVIND(M,L).EQ.0) GO TO 20	AER00330
DUE(I)=ST(M)	AER00340
GO TO 40	AER00350
20 CONTINUE	AER00360
40 CONTINUE	AER00370
SP(L)=FUNCT(TABLES(1,L),DUE)	AER00380
90 CONTINUE	AER00390
CA(1) = SP(1)	AER00400
CA(2) = SP(2)	AER00410
CA(3) = SP(3)	AER00420
C *** ADJUST THE COEFFICIENTS JUST FOUND	AER00430
B(1)=1./(ARG3+1.)**2	AER00440
B(2)=ARG3**.618/SGRT(ARG4)	AER00450
SP(1)=SP(1)+C(1)+C(4)*ARG1**2+C(7)*B(1)+C(10)*B(2)	AER00460
SP(2)=SP(2)+C(2)+C(5)*ARG2 +C(8)*B(1)+C(11)*B(2)	AER00470
SP(3)=SP(3)+C(3)+C(6)*ARG1 +C(9)*B(1)+C(12)*B(2)	AER00480
C *** ADJUST CF VECTOR ACCORDING TO NPC(11) LOGIC CONTROL	AER00490
IF(NPC(11).NE.1) GO TO 100	AER00500
XX=-SP(1)	AER00510
YY= CXZ1*SP(2)-SXZ1*SP(3)	AER00520
ZZ=-SXZ1*SP(2)-CXZ1*SP(3)	AER00530
GO TO 120	AER00540
100 IF(NPC(11).EQ.0) GO TO 110	AER00550
XX=-CALP*SP(1)+SALP*SP(3)	AER00560
YY= SP(2).	AER00570
ZZ=-SALP*SP(1)-CALP*SP(3)	AER00580
GO TO 120	AER00590
110 XX=-SP(1)	AER00600
YY= SP(2)	AER00610
ZZ=-SP(3)	AER00620
120 RETURN	AER00630
END	AER00640

SUBROUTINE AEROIN

```

COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40), COMM0010
* NALL,LRK COMM0020
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA, COMM0030
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH, COMM0040
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30), COMM0050
3 PE,ROE,ROEC,ROEM,SALP,SBET, COMM0060
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE, COMM0070
5 TTWO,TW(20),TVW(20),UW,VA(5),VB(5), COMM0080
6 VW,XIND1,XIND2,XLREF,XM, COMM0090
7 XMAS(20),XNU,XG,XGSM,XRE,XTEMP, COMM0100
8 XOW(20),XVW(20),XZI,YMAS,YMASM, COMM0110
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5), COMM0120
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4), COMM0130
2 B(8),CGM(3),DBM(3),OTRAN(3,3),DUD(10,1),DUE(4), COMM0140
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2), COMM0150
4 IDN,I1,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2, COMM0160
5 K1,NNN,NPTS,PAR(6),PBDOT(3),PMDOT(3),RES(6), COMM0170
6 RO,SPD(5),SPH,TRAN(3,3),XX(50), COMM0180
DIMENSION DUB(30,15) COMM0190
EQUIVALENCE (AG(1),DUB(1,1)) COMM0200
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40), COMM0210
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5), COMM0220
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3), COMM0230
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET, COMM0240
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST, COMM0250
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK, COMM0260
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT, COMM0270
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT, COMM0280
8 MIP(40),MTYP,MTYPS,N,NC(30),NCCOUNT,NPC(15), COMM0290
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9), COMM0300
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30), COMM0310
B PA(3),PM(3),R,REC,RERP2, COMM0320
C RPC,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40), COMM0330
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL, COMM0340
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40), COMM0350
F TK(40),TI(40),TXCG(20),TYCG(20),TYM(40),TZCG(20), COMM0360
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20), COMM0370
H XYCG(20),XZCG(20), COMM0380
INTEGER OUT,FIT,STATE,SCRACH,PQR, COMM0390
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR, COMM0400
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK, COMM0410
A PB(23),RL(23),TMB(23), COMM0420
COMMON /EXTRA/ GO, COMM0430
COMMON /AERTAB/ TABLES(580,3),SAVIND(3,3), ARIN0010
DIMENSION TCX(580),TCY(580),TCZ(580),ISTORE(1), ARIN0020
EQUIVALENCE (TCX,TABLES(1,1)),(TCY,TABLES(1,2)),(TCZ,TABLES(1,3)), ARIN0030
1 (ISTORE(1),KC(1)), ARIN0040
C *** ZERO TABLES ARRAY, ARIN0050
DO 10 I=1,1740, ARIN0060
10 TABLES(I)=0., ARIN0070
DO 20 I=1,9, ARIN0080
20 SAVIND(I)=0., ARIN0090
C *** READ IN ALL THREE AERODYNAMIC-COEFFICIENT TABLES, ARIN0100
DO 200 N=1,3, ARIN0110
NNN=0, ARIN0120
KC(1)=1, ARIN0130
KC(2)=2, ARIN0140
KC(3)=3, ARIN0150

```

C	*** READ IN TABLE IDENTIFIER AND INDEPENDENT	ARIN0160
C	*** VARIABLE-AND-VALUE COUNTERS	ARIN0170
	READ (1N,30) IDN,(ISTORE(J),J=1,4)	ARIN0180
	WRITE(OUT,30) IDN,(ISTORE(J),J=1,4)	ARIN0190
	30 FORMAT(5I4)	ARIN0200
	IF(ISTORE(1).EQ.-1) GO TO 200	ARIN0210
	NT=0	ARIN0220
C	*** (ONE) OR (NO) INDEPENDENT VALUES FOR A GIVEN	ARIN0230
C	*** INDEPENDENT VARIABLE ARE SPECIAL CASES	ARIN0240
	DO 40 LT=2,4	ARIN0250
	IF(ISTORE(LT).EQ.1) ISTORE(LT)=0	ARIN0260
	40 NT=NT+ISTORE(LT)	ARIN0270
	IF(NT.EQ.0) ISTORE(1)=0	ARIN0280
	IF(ISTORE(1).NE.0) GO TO 70	ARIN0290
	READ (1N,50) TABLES(5,IDN)	ARIN0300
	WRITE(OUT,60) TABLES(5,IDN)	ARIN0310
	50 FORMAT(12E6.4)	ARIN0320
	60 FORMAT(12F10.6)	ARIN0330
	GO TO 200	ARIN0340
C	*** SAVE INDEPENDENT VALUE INFORMATION FOR USE IN SUBROUTINE AERO	ARIN0350
	70 DO 80 MT=1,3	ARIN0360
	80 SAVIND(MT,IDN)=ISTORE(MT+1)	ARIN0370
	DO 90 K=1,4	ARIN0380
	90 TABLES(K,IDN)=ISTORE(K)	ARIN0390
	NPTS=4	ARIN0400
C	*** COUNT INDEPENDENT VARIABLES TO BE ENTERED AND	ARIN0410
C	*** SET UP CONVERSION INDICATORS	ARIN0420
	DO 110 L=1,3	ARIN0430
	IF(TABLES(L+1,IDN).NE.0.) GO TO 110	ARIN0440
	NNN=NNN+1	ARIN0450
	DO 100 J=L,3	ARIN0460
	100 KC(J)=KC(J)+1	ARIN0470
	110 CONTINUE	ARIN0480
C	*** COMPRESS INPUT WHEN ENTERING MONOVARIATE OR BIVARIATE TABLES	ARIN0490
	IF(SAVIND(1,IDN).EQ.0.AND.SAVIND(2,IDN).EQ.0) KC(1)=3	ARIN0500
	IF(TABLES(2,IDN).NE.0) GO TO 120	ARIN0510
	TABLES(2,IDN)=TABLES(3,IDN)	ARIN0520
	TABLES(3,IDN)=TABLES(4,IDN)	ARIN0530
	TABLES(4,IDN)=0.	ARIN0540
	IF(TABLES(2,IDN).NE.0) GO TO 130	ARIN0550
	TABLES(2,IDN)=TABLES(3,IDN)	ARIN0560
	TABLES(3,IDN)=0.	ARIN0570
	GO TO 130	ARIN0580
	120 IF(TABLES(3,IDN).NE.0) GO TO 130	ARIN0590
	TABLES(3,IDN)=TABLES(4,IDN)	ARIN0600
	TABLES(4,IDN)=0.	ARIN0610
	130 NPTS=NPTS-NNN	ARIN0620
	KD(1)=TABLES(2,IDN)	ARIN0630
	KD(2)=TABLES(3,IDN)	ARIN0640
	KD(3)=TABLES(4,IDN)	ARIN0650
C	*** SET FACTORS TO BE USED IN COMPUTING LOOP LIMITS BELOW	ARIN0660
	DO 140 K1=1,3	ARIN0670
	IF(KD(K1).EQ.0) KD(K1)=1	ARIN0680
	140 CONTINUE	ARIN0690
C	*** READ IN ALL INDEPENDENT VALUES AND CONVERT WHERE NECESSARY	ARIN0700
	DO 170 I=1,3	ARIN0710
	IF(KD(I).NE.1) GO TO 150	ARIN0720
	GO TO 170	ARIN0730
	150 KDOU=NPTS+1	ARIN0740
	NPTS=NPTS+KD(I)	ARIN0750

```

      READ ( IN,50) (TABLES(J,IDN),J=KDUM,NPTS)
      WRITE(OUT,60) (TABLES(J,IDN),J=KDUM,NPTS)
      IF(KC(I).GE.3) GO TO 180
      DO 100 M=KDUM,NPTS
160  TABLES(M,IDN)=TABLES(M,IDN)*CONRD
170  CONTINUE
C   ***  READ IN ALL DEPENDENT VALUES FOR ONE TABLE
180  II=NPTS+1
      JJ=NPTS+KD(1)*KD(2)*KD(3)
      READ ( IN,50) (TABLES(J,IDN),J=II,JJ)
      WRITE(OUT,60) (TABLES(J,IDN),J=II,JJ)
200  CONTINUE
      RETURN
      END

```

```

ARIN0760
ARIN0770
ARIN0780
ARIN0790
ARIN0800
ARIN0810
ARIN0820
ARIN0830
ARIN0840
ARIN0850
ARIN0860
ARIN0870
ARIN0880
ARIN0890

```

SUBROUTINE ATMDAT(ZE,PE,ROE,CE,TM,VMU,H,ISVX)	
COMMON /ATMCON /ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK	ATMD0010
A ,PB(23),RL(23),TMB(23)	ATMD0020
COMMON /EXTRA / GO	ATMD0030
IF(JK-2) 20,20,22	ATMD0040
20 H= ATM(4)*ZE/(ATM(4)+ZE)	ATMD0050
GO TO 24	ATMD0060
22 H= ZE	ATMD0070
24 CONTINUE	ATMD0080
3 I = ISV	ATMD0090
IF(H-HB(I))4,5,6	ATMD0100
4 IF(H-HB(I-1))7,8,9	ATMD0110
5 TM = TMB(I)	ATMD0120
PE = PB(I)	ATMD0130
GO TO 15	ATMD0140
6 IF(H -HB(I+1))10,11,12	ATMD0150
7 I = I-1	ATMD0160
GO TO 4	ATMD0170
8 I = I - 1	ATMD0180
GO TO 5	ATMD0190
9 I = I - 1	ATMD0200
GO TO 10	ATMD0210
11 I = I + 1	ATMD0220
GO TO 5	ATMD0230
12 I = I + 1	ATMD0240
GO TO 6	ATMD0250
10 TM = TMB(I) + RL(I)*(H-HB(I))	ATMD0260
IF(RL(I))13,14,13	ATMD0270
13 PE = PB(I)*(TMB(I)/TM)**(ATM(1)/RL(I))	ATMD0280
GO TO 15	ATMD0290
14 PE = PB(I)*EXP(-ATM(1)*(H-HB(I))/TMB(I))	ATMD0300
15 ROE= ATM(2)*PE/TM	ATMD0310
CE = ATM(3)*SGRT(TM)	ATMD0320
VMU= ABET*TM**1.5/(TM+ASU)	ATMD0330
ISV = I	ATMD0340
99 RETURN	ATMD0350
END	ATMD0360

```

SUBROUTINE DATAB
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF, SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),QTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHOT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBR5,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHOT(5),SUM,SUM2,SYG(3,9),TFINAL
E TF11(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERG,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,AP0,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
IF(DCOMP.LT.0.) GO TO 20
IF(KPROP.GE.0.) GO TO 10
2 CONTINUE
4 LS = 0
6 IF(KDAP.EQ.0) GO TO 14
READ(PQR) KDAP,(TT(LS+1),TP(LS+1),TQ(LS+1),TR(LS+1),AX(LS+1),
* AY(LS+1),AZ(LS+1),I=1,KDAP)
LS = LS+KDAP
IF(LS.EQ.1) GO TO 6
IF(T.GT.TT(LS)) GO TO 11
IF(LS.LE.20) GO TO 6
N11(2)=3
10 IF(T.LT.TT(LS-1)) GO TO 14
IF(KDAP.EQ.0) GO TO 14
KG2 = KG-2

```

```

WRITE(SCRACH) LS,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,LS),KG2,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KG2)
IF(KG2.LE.0) GO TO 11
KG = 2
DO 13 I=1,2
LT = KG2 + I
MTP(I)= MTP(LT)
TYM(I)= TYM(LT)
DAT(1,I)= DAT(1,LT)
DAT(2,I) = DAT(2,LT)
DAT(3,I) = DAT(3,LT)
SIG(1,I) = SIG(1,LT)
SIG(2,I) = SIG(2,LT)
SIG(3,I) = SIG(3,LT)
13 CONTINUE
11 CONTINUE
DO 12 I=1,2
MT = LS + I - 2
TT(I) = TT(MT)
TP(I) = TP(MT)
TQ(I) = TQ(MT)
TR(I) = TR(MT)
AX(I) = AX(MT)
AY(I) = AY(MT)
AZ(I) = AZ(MT)
12 CONTINUE
LS = 2
GO TO 6
14 N11(1) = LS
IF(KPROP.LT.0) TRCD=TT(1)
KPROP = 1
PM(1) = TAB(T,N11(1),TT(1),TP(1))
PM(2)=TAB(T,N11(1),TT(1),TQ(1))
PM(3)=TAB(T,N11(1),TT(1),TR(1))
CGM(1) = TAB(T,N8(1),TXCG(1),XXCG(1))
CGM(2) = TAB(T,N9(1),TYCG(1),XYCG(1))
CGM(3) = TAB(T,N10(1),TZCG(1),XZCG(1))
99 RETURN
20 IF(T.GT.TT(2)) GO TO 14
IF(TT(1).EQ.TRCD) GO TO 14
BACKSPACE SCRACH
BACKSPACE SCRACH
LT = 40-KG
DO 22 I=1,KG
MT = LT+I
MTP(MT) = MTP(I)
TYM(MT) = TYM(I)
DAT(1,MT) = DAT(1,I)
DAT(2,MT) = DAT(2,I)
DAT(3,MT) = DAT(3,I)
SIG(1,MT) = SIG(1,I)
SIG(2,MT) = SIG(2,I)
22 SIG(3,MT) = SIG(3,I)
READ(SCRACH) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,KDAP),KDATA,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KDATA)
LS=KDAP
N11(2)=LS-2
IF(KDATA.LT.0) GO TO 26

```

```

DATB0160
DATB0170
DATB0180
DATB0190
DATB0200
DATB0210
DATB0220
DATB0230
DATB0240
DATB0250
DATB0260
DATB0270
DATB0280
DATB0290
DATB0300
DATB0310
DATB0320
DATB0330
DATB0340
DATB0350
DATB0360
DATB0370
DATB0380
DATB0390
DATB0400
DATB0410
DATB0420
DATB0430
DATB0440
DATB0450
DATB0460
DATB0470
DATB0480
DATB0490
DATB0500
DATB0510
DATB0520
DATB0530
DATB0540
DATB0550
DATB0560
DATB0570
DATB0580
DATB0590
DATB0600
DATB0610
DATB0620
DATB0630
DATB0640
DATB0650
DATB0660
DATB0670
DATB0680
DATB0690
DATB0700
DATB0710
DATB0720
DATB0730
DATB0740
DATB0750

```

```

LT = LT - KDATA
I = KDATA+1
J = KDATA+KG
DO 24 I=I,J
MT = LT + I
MTP(I) = MTP(MT)
TYM(I) = TYM(MT)
DAT(1,I) = DAT(1,MT)
DAT(2,I) = DAT(2,MT)
DAT(3,I) = DAT(3,MT)
SIG(1,I) = SIG(1,MT)
SIG(2,I) = SIG(2,MT)
24 SIG(3,I) = SIG(3,MT)
KG = KG + KDATA
GO TO 14
26 KG = 1
GO TO 14
END

```

```

DATB0760
DATB0770
DATB0780
DATB0790
DATB0800
DATB0810
DATB0820
DATB0830
DATB0840
DATB0850
DATB0860
DATB0870
DATB0880
DATB0890
DATB0900
DATB0910
DATB0920
DATB0930

```

```

SUBROUTINE DERIVE
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM,
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDCUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 LI,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N6(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
VO(1) = (VA(4)+50.)/AS
VO(2) = (VA(4)-50.)/AS
HI(1) = AS*ROE*XLREF/XNU
DO 2 N=1,2
HI(2) = VO(N)*HI(1)
2 CALL AERO(XIND1,XIND2,VO(N),HI(2),ZO(N),ZO(N+2),ZO(N+4))
DCDY(1,1) = (ZO(1)-ZO(2))*1.E-2
DCDY(2,1) = (ZO(3)-ZO(4))*1.E-2
DCDY(3,1) = (ZO(5)-ZO(6))*1.E-2
VO(1) = H0+50.
VO(2) = H0-50.
HI(1)=VA(4)*XLREF
DO 6 N=1,2
VO(N+2) = TAB(VO(N),N5(1),TUW(1),XUW(1))
VO(N+4) = TAB(VO(N),N6(1),TVW(1),XVW(1))

```


CALL ATMDAT(VO(N),DUD(1),ZO(N),SP(3),DUD(2),DUD(3),DUD(4))	DERI0160
HI(2)=HI(1)*(C(21)*ZO(N)+C(22)*EXP(C(23)*VO(N)))/DUD(3)	DERI0170
ZO(3) = VA(4)/SP(3)	DERI0180
CALL AERO(XIND1,XIND2,ZO(3),HI(2),SP(N+3),SP(N+5),SP(N+7))	DERI0190
6 CONTINUE	DERI0200
DCDY(1,2) =(SP(4)-SP(5))*1.E-2	DERI0210
DCDY(2,2) =(SP(6)-SP(7))*1.E-2	DERI0220
DCDY(3,2) =(SP(8)-SP(9))*1.E-2	DERI0230
DRDH = C(21)*(ZO(1)-ZO(2))*1.E-2 + C(23)*ROEC	DERI0240
DWDH(1) = (VO(3)-VO(4))*1.E-2	DERI0250
DWDH(2) = (VO(5)-VO(6))*1.E-2	DERI0260
HI(1) = ALPH + .01	DERI0270
HI(2) = ALPH - .01	DERI0280
DO 14 N=1,2	DERI0290
IF(NPC(11)) 10,10,12	DERI0300
10 VO(1) = BETA	DERI0310
GO TO 14	DERI0320
12 ZO(1) = SIN(HI(N))	DERI0330
ZO(2) = COS(HI(N))	DERI0340
HI(N) = ATAN2(SQRT((ZO(1)*CBET)**2+SBET**2),ZO(2)*CBET)	DERI0350
VO(1) = ATAN2(SBET,ZO(1)*CBET)	DERI0360
14 CALL AERO(HI(N),VO(1),XM,XRE,VO(N+1),VO(N+3),VO(N+5))	DERI0370
DCDY(1,3) =(VO(2)-VO(3))*5E+2	DERI0380
DCDY(2,3) =(VO(4)-VO(5))*5E+2	DERI0390
DCDY(3,3) =(VO(6)-VO(7))*5E+2	DERI0400
HI(1) = BETA + .01	DERI0410
HI(2) = BETA - .01	DERI0420
DO 22 N=1,2	DERI0430
IF(NPC(11)) 18,18,20	DERI0440
18 VO(1) = ALPH	DERI0450
GO TO 22	DERI0460
20 ZO(1) = SIN(HI(N))	DERI0470
ZO(2) = COS(HI(N))	DERI0480
VO(1) = ATAN2(SQRT((SALP*ZO(2))**2+ZO(1)**2),CALP*ZO(2))	DERI0490
HI(N) = ATAN2(ZO(1),SALP*ZO(2))	DERI0500
22 CALL AERO(VO(1),HI(N),XM,XRE,VO(N+1),VO(N+3),VO(N+5))	DERI0510
DCDY(1,4) =(VO(2)-VO(3))*5E+2	DERI0520
DCDY(2,4) =(VO(4)-VO(5))*5E+2	DERI0530
DCDY(3,4) =(VO(6)-VO(7))*5E+2	DERI0540
DRDP = -(RERP2-1.)*RO*SPH*CPH/(1.+(RERP2-1.)*SPH**2)	DERI0550
SP(1) = 2.*VA(1)/VA(5)	DERI0560
SP(2) = 2.*VA(2)/VA(5)	DERI0570
SP(3) = 2.*VA(3)/VA(5)	DERI0580
SP(6) = DRDH/ROE + SP(1)*DWDH(1) + SP(2)*DWDH(2)	DERI0590
SP(4) = SP(6) - SP(2)*OMEGA*CPH	DERI0600
SP(5) =-SP(6)*DRDP + SP(2)*R*OMEGA*SPH	DERI0610
ZO(5) = SBET/CBET	DERI0620
DO 28 I=1,3	DERI0630
DADX(1,I) = (VB(1)*A(3,I)-VB(3)*A(1,I))/VB(4)**2	DERI0640
DADX(2,I) = (CBET*A(2,I)-ZO(5)*(VA(I)-A(2,I)*VB(2))/VA(4))/VA(4)	DERI0650
28 CONTINUE	DERI0660
DO 30 I=1,2	DERI0670
ZO(1) = OMEGA*DADX(I,2)	DERI0680
DADX(I,4) =-CPH*ZO(1)	DERI0690
DADX(I,5) = SPH*ZO(1)*R	DERI0700
30 DADX(I,6) = 0.	DERI0710
ZO(1) = VA(1)*X(7) + VA(2)*X(10) - VA(3)*X(9)	DERI0720
ZO(2) = VA(1)*X(8) + VA(2)*X(9) + VA(3)*X(10)	DERI0730
ZO(3) = VA(1)*X(9) - VA(2)*X(8) + VA(3)*X(7)	DERI0740
ZO(4) = VA(1)*X(10) - VA(2)*X(7) - VA(3)*X(8)	DERI0750

VO(1) = VB(1)*ZO(3) - VB(3)*ZO(1)	DERI0760
VO(2) = VB(1)*ZO(4) - VB(3)*ZO(2)	DERI0770
VO(3) = VB(1)*ZO(1) + VB(3)*ZO(3)	DERI0780
VO(4) = VB(1)*ZO(2) + VB(3)*ZO(4)	DERI0790
VO(5) = 2./VB(4)**2	DERI0800
DO 32 I=7,10	DERI0810
32 DADX(1,I) = VO(I-6)*VO(5)	DERI0820
ZO(6) = 2./VA(4)	DERI0830
DADX(2,7) = ZO(6)*(-CBET*ZO(4)-ZO(5)*VO(3)/VA(4))	DERI0840
DADX(2,8) = ZO(6)*(-CBET*ZO(3)-ZO(5)*VO(4)/VA(4))	DERI0850
DADX(2,9) = ZO(6)*(-CBET*ZO(2)+ZO(5)*VO(1)/VA(4))	DERI0860
DADX(2,10) = ZO(6)*(-CBET*ZO(1)+ZO(5)*VO(2)/VA(4))	DERI0870
ZO(7) = VA(2)*SPH*OMEGA*R/VA(4)	DERI0880
ZO(8) = (VA(1)*DWDH(1) + VA(2)*(DWDH(2)-OMEGA*CPH))/VA(4)	DERI0890
DO 36 I=1,3	DERI0900
DO 34 J=1,3	DERI0910
34 DERIV(I,J) = AB(I)*SP(J) + XGSM*(VA(J)*DCDY(I,1) /VA(4)	DERI0920
1 + DCDY(I,3)*DADX(1,J) + DCDY(I,4)*DADX(2,J))	DERI0930
DERIV(I,4) = AB(I)*SP(4) + XGSM*(DCDY(I,1)*ZO(8) + DCDY(I,2)	DERI0940
1 + DCDY(I,3)*DADX(1,4) + DCDY(I,4)*DADX(2,4))	DERI0950
DERIV(I,5) = AB(I)*SP(5) + XGSM*(DCDY(I,1)*ZO(7) - DCDY(I,2)*DRDP	DERI0960
1 + DCDY(I,3)*DADX(1,5) + DCDY(I,4)*DADX(2,5))	DERI0970
DO 35 J=7,10	DERI0980
35 DERIV(I,J) = XGSM*(DCDY(I,3)*DADX(1,J) + DCDY(I,4)*DADX(2,J))	DERI0990
36 DERIV(I,6) = 0.	DERI1000
RETURN	DERI1010
END	DERI1020

FUNCTION FUNCT(CRVE,X)	
DIMENSION C(3),IDX(3),CRVE(2),X(3),Z(3)	FUNC0010
DATA IERCNT /0/	FUNC0020
DATA IDX/3*0/	FUNC0030
N1 = CRVE(2)	FUNC0040
N2 = CRVE(3)	FUNC0050
M = CRVE(1)	FUNC0060
IF(M.LT.2) N1 = 0	FUNC0070
IF(M.LT.3) N2 = 0	FUNC0080
N2 = N1*N2	FUNC0090
K = M + 1	FUNC0100
DO 25 I=1,M	FUNC0110
J = K + 2	FUNC0120
N = CRVE(I+1)	FUNC0130
K = J + N - 2	FUNC0140
DO 10 L = J,K	FUNC0150
L=L	FUNC0160
IF(X(I).GE.CRVE(L-1)) GO TO 8	FUNC0170
C *** EXTRAPOLATE BACKWARDS	FUNC0180
C(I)=(X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0190
GO TO 25	FUNC0200
8 IF(X(I).LE.CRVE(L)) GO TO 20	FUNC0210
10 CONTINUE	FUNC0220
C *** EXTRAPOLATE FORWARDS	FUNC0230
C(I)=(X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0240
GO TO 25	FUNC0250
15 CONTINUE	FUNC0260
Z(1) = 0.0	FUNC0270
GOTO 100	FUNC0280
20 C(I) = (X(I)-CRVE(L-1))/(CRVE(L)-CRVE(L-1))	FUNC0290
25 IDX(I) = L - J + 2	FUNC0300
N = K + IDX(1) + N1*(IDX(2)-2) + N2*(IDX(3)-2)	FUNC0310
Z(1) = CRV(CRVE,N,C(1))	FUNC0320
IF(M.LT.2) GO TO 100	FUNC0330
N = N + N1	FUNC0340
Z(2) = CRV(CRVE,N,C(1))	FUNC0350
Z(1) = CRV(Z,2,C(2))	FUNC0360
IF(M.EQ.2) GO TO 100	FUNC0370
N = N - N1 + N2	FUNC0380
Z(2) = CRV(CRVE,N,C(1))	FUNC0390
N = N + N1	FUNC0400
Z(3) = CRV(CRVE,N,C(1))	FUNC0410
Z(2) = CRV(Z(1),3,C(2))	FUNC0420
Z(1) = CRV(Z(1),2,C(3))	FUNC0430
100 FUNCT = Z(1)	FUNC0440
RETURN	FUNC0450
END	FUNC0460
FUNCTION CRV(A,N,C)	
DIMENSION A(2)	CRVT0010
CRV = A(N-1) + C*(A(N)-A(N-1))	CRVT0020
RETURN	CRVT0030
END	CRVT0040

```

SUBROUTINE FXXU
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZ1,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUO(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHOT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
DIMENSION CX(3,4)
DIMENSION XPM(3,3)
EQUIVALENCE (XPM(1,1),DPH(1,1))
EQUIVALENCE (C(48),CX(1,1))
DIMENSION NO(1)
DATA NO(1) /-1/
DATA ITER /5/
SP(1) = PAR(4)*X(2)/CPH**2
F2(2,1) = 1./R
F1(1,3) = F2(2,1)*X(1)
F1(3,1) = -F1(1,3)-F1(1,3)
F1(3,2) = -F1(2,3)-F1(2,3)
F1(1,1) = F2(2,1)*X(3)
F1(1,2) = -F1(2,1)-F1(2,1)
F1(1,4) = (-PAR(5)*F2(2,1)+4.*PAR(3)*SPH*CPH)*F2(2,1)

```

```

COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
COMM0320
COMM0330
COMM0340
COMM0350
COMM0360
COMM0370
COMM0380
COMM0390
COMM0400
COMM0410
COMM0420
COMM0430
FXXU0010
FXXU0020
FXXU0030
FXXU0040
FXXU0050
FXXU0060
FXXU0070
FXXU0080
FXXU0090
FXXU0100
FXXU0110
FXXU0120
FXXU0130
FXXU0140
FXXU0150

```

F1(1,5) = SP(1)*F1(3,2)*R - PAR(3)*(CPH+SPH)*(CPH-SPH)	FXXU0160
F1(2,4) = -F1(2,2)*F1(2,3)	FXXU0170
F1(2,5) = -SP(1)*F1(3,1)*R	FXXU0180
F1(3,4) = (PAR(1)*F2(2,1)-PAR(2)-PAR(2) + 4.*PAR(3)*PAR(6))*	FXXU0190
* F2(2,1)	FXXU0200
F1(3,5) = -3.*PAR(3)*SPH*CPH	FXXU0210
F2(2,4) = -F1(1,3)*F2(2,1)	FXXU0220
F2(3,2) = F2(2,1)/CPH	FXXU0230
F2(3,4) = -F1(2,3)*F2(3,2)	FXXU0240
F2(3,5) = F1(2,1)/CPH	FXXU0250
F3(1,1) = -X(9)*PAR(4)	FXXU0260
F3(2,1) = X(10)*PAR(4)	FXXU0270
F3(3,1) = X(7)*PAR(4)	FXXU0280
F3(4,1) = -X(8)*PAR(4)	FXXU0290
F3(1,2) = (X(8)-X(10)*TPH)*PAR(4)	FXXU0300
F3(2,2) = -(X(7)+X(9)*TPH)*PAR(4)	FXXU0310
F3(3,2) = (X(10)+X(8)*TPH)*PAR(4)	FXXU0320
F3(4,2) = -(X(9)-X(7)*TPH)*PAR(4)	FXXU0330
F3(1,4) = -F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)	FXXU0340
F3(2,4) = -F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)	FXXU0350
F3(3,4) = -F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)	FXXU0360
F3(4,4) = -F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)	FXXU0370
F3(1,5) = -X(10)*SP(1)	FXXU0380
F3(2,5) = -X(9)*SP(1)	FXXU0390
F3(3,5) = X(8)*SP(1)	FXXU0400
F3(4,5) = X(7)*SP(1)	FXXU0410
F1(1,7) = 2.*(X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3))	FXXU0420
F1(1,8) = 2.*(X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3))	FXXU0430
F1(1,9) = 2.*(-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3))	FXXU0440
F1(1,10) = -2.*(X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3))	FXXU0450
F1(2,7) = -F1(1,10)	FXXU0460
F1(2,8) = -F1(1, 9)	FXXU0470
F1(2,9) = F1(1, 8)	FXXU0480
F1(2,10) = F1(1, 7)	FXXU0490
F1(3,7) = F1(1, 9)	FXXU0500
F1(3,8) = -F1(1,10)	FXXU0510
F1(3,9) = -F1(1, 7)	FXXU0520
F1(3,10) = F1(1, 8)	FXXU0530
F3(2,7) = -F3(1,8)	FXXU0540
F3(3,7) = -F3(1, 9)	FXXU0550
F3(3,8) = -F3(2, 9)	FXXU0560
F3(4,7) = -F3(1,10)	FXXU0570
F3(4,8) = -F3(2,10)	FXXU0580
F3(4,9) = -F3(3,10)	FXXU0590
F2(1,3) = -1.	FXXU0600
F1(1,6) = 0.	FXXU0610
F1(2,6) = 0.	FXXU0620
F1(3,6) = 0.	FXXU0630
F1(3,3) = 0.	FXXU0640
F2(1,1) = 0.	FXXU0650
F2(1,2) = 0.	FXXU0660
F2(1,4) = 0.	FXXU0670
F2(1,5) = 0.	FXXU0680
F2(2,2) = 0.	FXXU0690
F2(2,3) = 0.	FXXU0700
F2(2,5) = 0.	FXXU0710
F2(3,1) = 0.	FXXU0720
F2(3,3) = 0.	FXXU0730
F3(1,3) = 0.	FXXU0740
F3(2,3) = 0.	FXXU0750

F3(3,3) = 0.	FXXU0760
F3(4,3) = 0.	FXXU0770
F3(1,6) = 0.	FXXU0780
F3(2,6) = 0.	FXXU0790
F3(3,6) = 0.	FXXU0800
F3(4,6) = 0.	FXXU0810
F3(1,7) = 0.	FXXU0820
F3(2,8) = 0.	FXXU0830
F3(3,9) = 0.	FXXU0840
F3(4,10) = 0.	FXXU0850
CALL DERIVE	FXXU0860
DO 410 J=1,10	FXXU0870
DO 410 I=1,3	FXXU0880
SUM=F1(I,J)	FXXU0890
DO 400 K=1,3	FXXU0900
SUM=SUM+A(K,I)*DERIV(K,J)	FXXU0910
400 CONTINUE	FXXU0920
F1(I,J)=SUM	FXXU0930
410 CONTINUE	FXXU0940
IF(NO(1)) 415,425,420	FXXU0950
415 VO(10)=AP(1)**2+AP(3)**2	FXXU0960
VO(11)=AP(4)*(1./AP(1)-AP(1)/VO(10))	FXXU0970
VO(12)=AP(4)*(1./AP(3)-AP(3)/VO(10))	FXXU0980
420 CONTINUE	FXXU0990
K = 0	FXXU1000
DO 422 I=1,3	FXXU1010
DO 422 J=1,3	FXXU1020
K = K+1	FXXU1030
422 SP(K) = PA(I)*XP(J)	FXXU1040
DTRAN(1,1) = SP(5) + SP(9)	FXXU1050
DTRAN(1,2) = -2.*SP(4) + SP(2)	FXXU1060
DTRAN(1,3) = -2.*SP(7) + SP(3)	FXXU1070
DTRAN(2,1) = SP(4) - 2.*SP(2)	FXXU1080
DTRAN(2,2) = SP(1) + SP(9)	FXXU1090
DTRAN(2,3) = -2.*SP(8) + SP(6)	FXXU1100
DTRAN(3,1) = SP(7) - 2.*SP(3)	FXXU1110
DTRAN(3,2) = SP(8) - 2.*SP(6)	FXXU1120
DTRAN(3,3) = SP(1) + SP(5)	FXXU1130
425 DO 500 N=1,10	FXXU1140
SP(4)=0.	FXXU1150
SP(5)=0.	FXXU1160
SP(6)=0.	FXXU1170
IF(N.NE.6) GO TO 440	FXXU1180
PAXP(1,6) = 0.	FXXU1190
PAXP(2,6) = 0.	FXXU1200
PAXP(3,6) = 0.	FXXU1210
PAXP(4,6) = 0.	FXXU1220
GO TO 500	FXXU1230
440 DO 470 KA=1,ITER	FXXU1240
DO 450 I=1,3	FXXU1250
PAXP(I,N)=DERIV(I,N)	FXXU1260
DO 450 J=1,3	FXXU1270
PAXP(I,N) = PAXP(I,N) + DTRAN(I,J)*SP(J+3)	FXXU1280
450 CONTINUE	FXXU1290
IF(NO(1)) 455,460,460	FXXU1300
455 PAXP(4,N)=VO(11)*PAXP(1,N)+VO(12)*PAXP(3,N)	FXXU1310
460 DO 470 I=1,3	FXXU1320
SP(I+3)=0.	FXXU1330
IF(I.EQ.1) SP(4) = CX(1,4)*PAXP(4,N)	FXXU1340
DO 470 J=1,3	FXXU1350

SP(I+3)=SP(I+3)+CX(I,J)*PAXP(J,N)	FXXU1360
470 CONTINUE	FXXU1370
F3(1,N)=F3(1,N)+.5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU1380
F3(2,N)=F3(2,N)+.5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU1390
F3(3,N)=F3(3,N)+.5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU1400
F3(4,N)=F3(4,N)+.5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU1410
500 CONTINUE	FXXU1420
IPC = 0	FXXU1430
LT = 0	FXXU1440
NT = 0	FXXU1450
IF(NSTC) 1,1,6	FXXU1460
1 IF(NPU) 2,99,2	FXXU1470
2 N = NSTX	FXXU1480
NT = 1	FXXU1490
II = 1	FXXU1500
3 NNN = MC(II)	FXXU1510
GO TO 18	FXXU1520
6 N = 10	FXXU1530
II = 1	FXXU1540
9 NNN = NC(II)	FXXU1550
GO TO 18	FXXU1560
12 II = II+1	FXXU1570
IF(NT) 15,13,15	FXXU1580
13 IF(NSTC-II) 1,9,9	FXXU1590
15 IF(NPU -II) 99,3,3	FXXU1600
18 CONTINUE	FXXU1610
IF(NNN-60) 19,19,25	FXXU1620
19 L=0	FXXU1630
M = 0	FXXU1640
SP(1) = 0.	FXXU1650
SP(2) = 0.	FXXU1660
SP(3) = 0.	FXXU1670
ST(1) = 0.	FXXU1680
ST(2) = 0.	FXXU1690
ST(3) = 0.	FXXU1700
IF(NNN-15) 50,50,20	FXXU1710
20 IF(NNN-20) 80,80,21	FXXU1720
21 IF(NNN-25) 85,85,22	FXXU1730
22 IF(NNN-30) 95,95,23	FXXU1740
23 L=1	FXXU1750
SP(4) = 0.	FXXU1760
SP(5) = 0.	FXXU1770
SP(6) = 0.	FXXU1780
IF(NNN-35) 100,100,150	FXXU1790
25 DO 26 I=1,3	FXXU1800
F1(I,II+N) = 0.	FXXU1810
F3(I,II+N) = 0.	FXXU1820
26 CONTINUE	FXXU1830
F3(4,II+N) = 0.	FXXU1840
GO TO 12	FXXU1850
30 SP(4)=0.	FXXU1860
SP(5)=0.	FXXU1870
SP(6)=0.	FXXU1880
SP(7) = 0.	FXXU1890
33 CONTINUE	FXXU1900
DO 32 KA=1,ITER	FXXU1910
DO 31 I=1,3	FXXU1920
VO(I)=SP(I)	FXXU1930
DO 31 J=1,3	FXXU1940
VO(I) = VO(I) +DTRAN(I,J)*SP(J+3)	FXXU1950

31 CONTINUE	FXXU1960
IF(NO(1)) 600,610,610	FXXU1970
600 SP(7) = VO(11)*VO(1)+VO(12)*VO(3)	FXXU1980
610 DO 32 I=1,3	FXXU1990
SP(I+3)=ST(I)	FXXU2000
IF(I-1) 630,620,630	FXXU2010
620 SP(4)=C(57)*SP(7) + SP(4)	FXXU2020
630 DO 32 J=1,3	FXXU2030
SP(I+3)=SP(I+3)+CX(I,J)*VO(J)	FXXU2040
32 CONTINUE	FXXU2050
36 I=II+N	FXXU2060
IF(LT.NE.0) RETURN	FXXU2070
39 F3(1,I) = .5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU2080
F3(2,I) = .5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU2090
F3(3,I) = .5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU2100
F3(4,I) = .5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU2110
IF(L) 46,45,46	FXXU2120
45 F1(1,I) = SP(1)*A(1,1) + SP(2)*A(2,1) + SP(3)*A(3,1)	FXXU2130
F1(2,I) = SP(1)*A(1,2) + SP(2)*A(2,2) + SP(3)*A(3,2)	FXXU2140
F1(3,I) = SP(1)*A(1,3) + SP(2)*A(2,3) + SP(3)*A(3,3)	FXXU2150
GO TO 12	FXXU2160
46 F1(1,I)=0.	FXXU2170
F1(2,I)=0.	FXXU2180
F1(3,I)=0.	FXXU2190
GO TO 12	FXXU2200
50 VO(1)=0.	FXXU2210
VO(2)=0.	FXXU2220
VO(3)=0.	FXXU2230
IF(NNN-4) 51,52,53	FXXU2240
51 VO(NNN)=1.	FXXU2250
GO TO 60	FXXU2260
52 VO(1)=XIND1**2	FXXU2270
GO TO 60	FXXU2280
53 IF(NNN-6) 54,55,56	FXXU2290
54 VO(2)=XIND2	FXXU2300
GO TO 60	FXXU2310
55 VO(3)=XIND1	FXXU2320
GO TO 60	FXXU2330
56 I=NNN-((NNN-1)/3)*3	FXXU2340
IF(NNN-9) 57,57,58	FXXU2350
57 VO(I)=(XM+1)**-2	FXXU2360
GO TO 60	FXXU2370
58 VO(I)=XM**.618/SQRT(XRE)	FXXU2380
60 CONTINUE	FXXU2390
IF(NPC(11)) 61,62,63	FXXU2400
61 SP(1) =-XQSM*(CALP*VO(1)-SALP*VO(3))	FXXU2410
SP(2)= XQSM* VO(2)	FXXU2420
SP(3) =-XQSM*(SALP*VO(1)+CALP*VO(3))	FXXU2430
GO TO 30	FXXU2440
62 SP(1)=-XQSM*VO(1)	FXXU2450
SP(2)= XQSM*VO(2)	FXXU2460
SP(3)=-XQSM*VO(3)	FXXU2470
GO TO 30	FXXU2480
63 SP(1)=-XQSM*VO(1)	FXXU2490
SP(2) = XQSM*(CXZI*VO(2)-SXZI*VO(3))	FXXU2500
SP(3) =-XQSM*(SXZI*VO(2)+CXZI*VO(3))	FXXU2510
GO TO 30	FXXU2520
80 IF(T.LT.TONE) GO TO 84	FXXU2530
SP(1)=AB(1)/YMAS	FXXU2532
SP(2)=AB(2)/YMAS	FXXU2534

SP(3)=AB(3)/YMAS	FXXU2536
IF(NNN-17) 30,81,82	FXXU2538
81 SP(1)=TAU*SP(1)	FXXU2540
SP(2)=TAU*SP(2)	FXXU2542
SP(3)=TAU*SP(3)	FXXU2544
GO TO 30	FXXU2546
82 SP(1)=SP(1)*TAU**2	FXXU2548
SP(2)=SP(2)*TAU**2	FXXU2550
SP(3)=SP(3)*TAU**2	FXXU2552
GO TO 30	FXXU2554
84 SP(4)=0.	FXXU2556
SP(5)=0.	FXXU2558
SP(6)=0.	FXXU2560
L=1	FXXU2562
GO TO 36	FXXU2564
85 CONTINUE	FXXU2566
KA = N	FXXU2568
CALL AERO(XIND1,XIND2,XM,1.005*XRE,VO(4),VO(5),VO(6))	FXXU2600
CALL AERO(XIND1,XIND2,XM,0.995*XRE,VO(1),VO(2),VO(3))	FXXU2610
L = 0	FXXU2620
N = KA	FXXU2630
SP(1)= (VO(4)-VO(1))/(XRE+E-2)	FXXU2640
SP(2)= (VO(5)-VO(2))/(XRE+E-2)	FXXU2650
SP(3)= (VO(6)-VO(3))/(XRE+E-2)	FXXU2660
IF(NNN-22) 86,87,90	FXXU2670
86 SP(4) = ROEM/ROE	FXXU2680
GO TO 92	FXXU2690
87 SP(4) = EXP(HO*C(23))/ROE	FXXU2700
GO TO 92	FXXU2710
90 SP(4) = HO*ROEC/ROE	FXXU2720
92 CONTINUE	FXXU2730
ST(1)=0.	FXXU2740
ST(2)=0.	FXXU2750
ST(3)=0.	FXXU2760
93 CONTINUE	FXXU2810
DO 94 I=1,3	FXXU2820
94 SP(I) = SP(4)*(AB(I)+XQSM*XRE*SP(I))	FXXU2830
GO TO 30	FXXU2840
95 VO(1)=VA(NNN-25)	FXXU2850
VO(2)=DADX(1,NNN-25)	FXXU2860
VO(3)=DADX(2,NNN-25)	FXXU2870
DO 98 I=1,3	FXXU2880
98 SP(I) =2.*VO(1)*AB(I)/VA(4)+XQSM*(DCDY(I,1)*VO(1)+DCDY(I,2)*VO(2)+	FXXU2890
2 DCDY(I,3)*VO(3))	FXXU2900
GO TO 30	FXXU2910
100 I=NNN-30	FXXU2920
IF(N0(1)) 102,103,103	FXXU2930
102 SP(7) = VO(11)*TRAN(1,I)+VO(12)*TRAN(3,I)	FXXU2940
103 DO 112 J=1,3	FXXU2950
IF(J.EQ.1) SP(4) = C(57)*SP(7)	FXXU2960
106 DO 110 K=1,3	FXXU2970
SP(J+3) =SP(J+3)+CX(J,K)*TRAN(K,I)	FXXU2980
110 CONTINUE	FXXU2990
112 SP(J) = TRAN(J,I)	FXXU3000
GO TO 33	FXXU3010
150 CONTINUE	FXXU3020
IF(NNN-48) 160,250,250	FXXU3030
160 IF(NNN-45) 170,200,200	FXXU3040
170 J = (NNN-33)/3	FXXU3050
K = NNN - 3*J - 32	FXXU3060

```

      SP(J+3) = PM(K)
      ST(J) = PM(K)
      AG(J) = PMDOT(K)
      IF(IPC.EQ.0) GO TO 175
172  SP(1) = XPM(1,J)*PMDOT(K)
      SP(2) = XPM(2,J)*PMDOT(K)
      SP(3) = XPM(3,J)*PMDOT(K)
      GO TO 33
175  IPC = 1
      XPM(1,1) = 0.
      XPM(2,2) = 0.
      XPM(3,3) = 0.
      XPM(1,2) = XP(3)
      XPM(2,1) = -XP(3)
      XPM(3,1) = XP(2)
      XPM(1,3) = -XP(2)
      XPM(2,3) = XP(1)
      XPM(3,2) = -XP(1)
      GO TO 172
200  SP(NNN-41) = 1.
      GO TO 36
250  J = (NNN-45)/3
      K = NNN - 3*J - 41
      SP(K) = AP(J)
      GO TO 36
99   RETURN
      ENTRY PAXPC
      IPC = 0
      LT = 1
      GO TO 19
      END

```

```

FXXU3070
FXXU3080
FXXU3090
FXXU3100
FXXU3110
FXXU3120
FXXU3130
FXXU3140
FXXU3150
FXXU3160
FXXU3170
FXXU3180
FXXU3190
FXXU3200
FXXU3210
FXXU3220
FXXU3230
FXXU3240
FXXU3250
FXXU3260
FXXU3270
FXXU3280
FXXU3290
FXXU3300
FXXU3310
FXXU3320
FXXU3330
FXXU3340
FXXU3350
FXXU3360
FXXU3370

```

```

SUBROUTINE INDAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDMOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,AP0,AR,ASU,ATM(4),HB(23),ISV,JK
A Pb(23),RL(23),TMB(23)
COMMON /EXTRA / GO
DATA CONV /.3048/
REWIND FIT
REWIND PQR
REWIND SCRACH
REWIND STATE
WRITE(OUT,1030)
1030 FORMAT(1H1,22H DATA ANALYSIS PROGRAM//11H INPUT DATA//)
8 READ(IN,1000) KDUM,(B(I),I=1,8)
1000 FORMAT(I2,7A10,A8)
WRITE(OUT,1001) KDUM,(B(I),I=1,8)
1001 FORMAT(5X,I2,5X,7A10,5X,A8)
IF(KDUM) 7,8,9
7 CALL EXIT
9 GO TO (8,20,30,40,50,60,70,80,90,100,110,120,130,140,150,160,170,
A180,190,200),KDUM

```

20	DECODE(40,1002,B) (NPC(I),I=1,10)	INDT0160
1002	FORMAT(1014)	INDT0170
	IF(NPC(2).EQ.0) GO TO 8	INDT0180
	XMU = XMU/CONV**3	INDT0190
	REO = REO/CONV	INDT0200
	RPO = RPO/CONV	INDT0210
	GO = GO/CONV	INDT0220
	GO TO 8	INDT0230
30	DECODE(30,1003,B) IPC,IDN,SP(1),SP(2)	INDT0240
1003	FORMAT(I2,I4,E12.4,E12.4)	INDT0250
	GO TO (32,34,36,38,39),IPC	INDT0260
32	NST=NST+1	INDT0270
	ZO(IDN)=SP(1)	INDT0280
	P(IDN,IDN)=SP(2)**2	INDT0290
	GO TO 8	INDT0300
34	NSTC = NSTC + 1	INDT0310
	NC(NSTC) = IDN	INDT0320
	C(IDN)=SP(1)	INDT0330
	P(NSTC+10,NSTC+10) = SP(2)**2	INDT0340
	GO TO 8	INDT0350
36	NPU=NPU+1	INDT0360
	MC(NPU)=IDN	INDT0370
	C(IDN)=SP(1)	INDT0380
	D(NPU)=SP(2)**2	INDT0390
	GO TO 8	INDT0400
38	NPV=NPV+1	INDT0410
	MCC(NPV)=IDN	INDT0420
	C(IDN)=SP(1)	INDT0430
	S(NPV)=SP(2)**2	INDT0440
	GO TO 8	INDT0450
39	C(IDN) = SP(1)	INDT0460
	GO TO 8	INDT0470
40	DECODE(54,1004,B) TO,DET,DCOMP,TFINAL	INDT0480
1004	FORMAT(6X,4E12.4)	INDT0490
	GO TO 8	INDT0500
50	DECODE(42,1005,B) IPC,SP(1),SP(2),SP(3)	INDT0510
1005	FORMAT(I2,4X,3E12.4)	INDT0520
	IF(IPC.EQ.2) GO TO 54	INDT0530
52	GO = SP(1)	INDT0540
	XMU=SP(2)	INDT0550
	XJ2 = SP(3)	INDT0560
	GO TO 8	INDT0570
54	RPO = SP(1)	INDT0580
	REO = SP(2)	INDT0590
	OMEGA=SP(3)	INDT0600
	GO TO 8	INDT0610
60	DECODE(6,1006,B) IPC,NPTS	INDT0620
1006	FORMAT(I2,I4)	INDT0630
	GO TO(62,64,66),IPC	INDT0640
62	READ(IN,1031) (TXCG(I),XXCG(I),I=1,NPTS)	INDT0650
	WRITE(OUT,1031)(TXCG(I),XXCG(I),I=1,NPTS)	INDT0660
1031	FORMAT(6E12.4)	INDT0670
	N8(1)=NPTS	INDT0680
	GO TO 8	INDT0690
64	READ(IN,1031) (TYCG(I),XYCG(I),I=1,NPTS)	INDT0700
	WRITE(OUT,1031)(TYCG(I),XYCG(I),I=1,NPTS)	INDT0710
	N9(1)=NPTS	INDT0720
	GO TO 8	INDT0730
66	READ(IN,1031) (TZCG(I),XZCG(I),I=1,NPTS)	INDT0740
	WRITE(OUT,1031)(TZCG(I),XZCG(I),I=1,NPTS)	INDT0750

N10(1)=NPTS	INDT0760
GO TO 8	INDT0770
70 DECODE(68,1007,8) IDN,SP(1),SP(2),SP(3),LT,MT,NT,SP(4),SP(5),SP(6)	INDT0780
1007 FORMAT(I2,3E10.4,3I2,3E10.4)	INDT0790
NSTA=NSTA+1	INDT0800
NS(NSTA) = IDN	INDT0810
DTI(IDN)=SP(1)	INDT0820
DTF(IDN)=SP(2)	INDT0830
DFIT(IDN)=SP(3)	INDT0840
MR(1,IDN)=LT	INDT0850
MR(2,IDN)=MT	INDT0860
MR(3,IDN)=NT	INDT0870
SYG(1,IDN)=SP(4)	INDT0880
SYG(2,IDN)=SP(5)	INDT0890
SYG(3,IDN)=SP(6)	INDT0900
GO TO 8	INDT0910
80 DECODE(6,1006,8) IPC,IDN	INDT0920
IF(IDN) 81,83,81	INDT0930
81 READ(IN,1032) KDATA	INDT0940
IF(KDATA.LE.0) GO TO 82	INDT0950
READ(IN,1032) (K,MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,3),	INDT0960
* I=1,KDATA)	INDT0970
WRITE(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT0980
X3),I=1,KDATA)	INDT0990
GO TO 81	INDT1000
1032 FORMAT(2I2,7E10.2)	INDT1010
82 CONTINUE	INDT1020
K = 0	INDT1030
WRITE(FIT)KDATA,K,K,K,K,K,K,K,K	INDT1040
REWIND FIT	INDT1050
83 IF(IPC) 84,8,84	INDT1060
84 READ(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT1070
X3),I=1,KDATA)	INDT1080
WRITE(OUT,1033)KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1	INDT1090
X,3),I=1,KDATA)	INDT1100
1033 FORMAT(2I4,7E16.7/(4X,I4,7E16.7))	INDT1110
IF(KDATA) 84,85,84	INDT1120
85 REWIND FIT	INDT1130
GO TO 8	INDT1140
90 DECODE(6,1006,8) IPC,IDN	INDT1150
IF(IDN) 91,93,91	INDT1160
91 READ(IN,1034) KDAP	INDT1170
IF(KDAP.LE.0) GO TO 92	INDT1180
READ(IN,1034) (K,TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1190
* KDAP)	INDT1200
WRITE(PQR)KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1210
* KDAP)	INDT1220
GO TO 91	INDT1230
1034 FORMAT(I2,7E10.2)	INDT1240
92 CONTINUE	INDT1250
K = 0	INDT1260
WRITE(PQR) KDAP,K,K,K,K,K,K,K,K	INDT1270
REWIND PQR	INDT1280
93 IF(IPC) 94,8,94	INDT1290
94 READ(PQR) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,KDAP	INDT1300
X)	INDT1310
WRITE(OUT,1035) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=	INDT1320
X1,KDAP)	INDT1330
1035 FORMAT(I4,7E16.7/(4X,7E16.7))	INDT1340
IF(KDAP) 94,95,94	INDT1350

95 REWIND PQR	INDT1360
GO TO 8	INDT1370
100 DECODE(6,1006,B) IPC,NPTS	INDT1380
NSTX = NST+NSTC	INDT1390
GO TO (101,102,103,104,106,108),IPC	INDT1400
101 READ(IN,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1410
WRITE(OUT,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1420
GO TO 8	INDT1430
102 READ(IN,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1440
WRITE(OUT,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1450
GO TO 8	INDT1460
103 READ(IN,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1470
WRITE(OUT,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1480
GO TO 8	INDT1490
104 DO 105 I=1,NPTS	INDT1500
READ(IN,1036) LT,MT,P(LT,MT)	INDT1510
P(MT,LT)=P(LT,MT)	INDT1520
1036 FORMAT(4X,2I4,E12.4)	INDT1530
105 WRITE(OUT,1037) LT,MT,P(LT,MT)	INDT1540
1037 FORMAT(10X,2HP(,I3,1H,I3,3H) =E15.6)	INDT1550
GO TO 8	INDT1560
106 DO 107 I=1,NPTS	INDT1570
READ(IN,1036) LT,MT,CUZ(LT,MT)	INDT1580
107 WRITE(OUT,1038) LT,MT,CUZ(LT,MT)	INDT1590
1038 FORMAT(8X,4HCUZ(,I3,1H,I3,3H) =E15.8)	INDT1600
GO TO 8	INDT1610
108 DO 109 I=1,NPTS	INDT1620
READ(IN,1036) LT,MT,CVZ(LT,MT)	INDT1630
109 WRITE(OUT,1039) LT,MT,CVZ(LT,MT)	INDT1640
1039 FORMAT(8X,4HCVZ(,I3,1H,I3,3H) =E15.8)	INDT1650
GO TO 8	INDT1660
1008 FORMAT(I2,I4,2E12.4)	INDT1670
110 DECODE(32,1006,B) NPC(11),IP,SREF,XLREF	INDT1680
CALL AEROIN	INDT1690
GO TO 8	INDT1700
120 DECODE(32,1006,B) IP,N4(1),TONE,TTWO	INDT1710
IP = N4(1)	INDT1720
READ(IN,1031) (TMAS(I),XMAS(I),I=1,IP)	INDT1730
WRITE(OUT,1041) (TMAS(I),XMAS(I),I=1,IP)	INDT1740
1041 FORMAT(5(F10.2,E14.5))	INDT1750
GO TO 8	INDT1760
130 DECODE(6,1006,B) IPC,NPTS	INDT1770
IF(IPC) 134,132,134	INDT1780
132 N5(1) = NPTS	INDT1790
READ(IN,1031) (TUW(I),XUW(I),I=1,NPTS)	INDT1800
WRITE(OUT,1041) (TUW(I),XUW(I),I=1,NPTS)	INDT1810
GO TO 8	INDT1820
134 N6(1) = NPTS	INDT1830
READ(IN,1031) (TVW(I),XVW(I),I=1,NPTS)	INDT1840
WRITE(OUT,1041) (TVW(I),XVW(I),I=1,NPTS)	INDT1850
GO TO 8	INDT1860
140 DECODE(2,1006,B) NPC(14)	INDT1870
IF(NPC(14)-1) 8,8,142	INDT1880
142 READ(IN,1048) K1,APO,AMO,AR,AGAM,ABET,ASU	INDT1890
1048 FORMAT(I4,6E11.4)	INDT1900
READ(IN,1031) (HB(I),I=1,K1)	INDT1910
READ(IN,1031) (TMB(I),I=1,K1)	INDT1920
GO TO 8	INDT1930
150 GO TO 8	INDT1940
160 GO TO 8	INDT1950

170 GO TO 8
180 GO TO 8
190 GO TO 8
200 RETURN
END

INDT1960
INDT1970
INDT1980
INDT1990
INDT2000

```

SUBROUTINE INTAG
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TFWO,TUV(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUV(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A NB(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
2 LRK = 4
6 CALL RKUTTA
IF(LRK-2) 8,10,99
8 CALL DATAB
CALL MOTION
IF(NPC(1)-1) 12,6,12
10 IF(DCOMP.GE.0..OR.NPC(10).EQ.0.OR.T.EQ.TSAV) GO TO 6
WRITE(STATE) T,X
TSAV=T
GO TO 6
12 CALL FXXU
DO 22 I=1,4
N = NSTX+NPU
DO 22 J=1,N
IF(J-10) 13,13,14

```

```

COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
COMM0320
COMM0330
COMM0340
COMM0350
COMM0360
COMM0370
COMM0380
COMM0390
COMM0400
COMM0410
COMM0420
COMM0430
INTG0010
INTG0020
INTG0030
INTG0040
INTG0050
INTG0060
INTG0070
INTG0090
INTG0095
INTG0100
INTG0110
INTG0120
INTG0130
INTG0140
INTG0150

```


13 CONTINUE	INTG0160
SUM = 0.	INTG0170
SUM2= 0.	INTG0180
GO TO 15	INTG0190
14 SUM = F1(I,J)	INTG0200
SUM2= F3(I,J)	INTG0210
15 DO 16 K=1,10	INTG0220
16 SUM2 = SUM2 + F3(I,K)*PH(K,J)	INTG0230
DPH(I+6,J) = SUM2	INTG0240
IF(I.EQ.4) GO TO 22	INTG0250
DO 18 K=1,10	INTG0260
18 SUM = SUM + F1(I,K)*PH(K,J)	INTG0270
DPH(I,J) = SUM	INTG0280
SUM = 0.	INTG0290
DO 20 K=1,5	INTG0300
20 SUM = SUM + F2(I,K)*PH(K,J)	INTG0310
DPH(I+3,J) = SUM	INTG0320
22 CONTINUE	INTG0330
GO TO 6	INTG0340
99 RETURN	INTG0350
END	INTG0360

```

SUBROUTINE MINVAR
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),Z0(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,JJ,IPC,KJ,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBR,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 LI,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROCT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
U SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APQ,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
G(1,10) = 0.
G(2,10) = 0.
G(3,10) = 0.
NT = 0
LT = 1
MT = NSTX
DO 1 I=1,NSTX
P(I,10) = 0.
1 P(10,I) = 0.
2 DO 12 J=KAR,KCB
DO 6 I=LT,MT
L = I+1
SUM = 0.
DO 3 K=LT,I
3 SUM = SUM + P(K,I)*G(J,K)

```

IF(L.GT.MT) GO TO 6	MINV0160
DO 4 K=L,MT	MINV0170
4 SUM = SUM+P(I,K)*G(J,K)	MINV0180
6 DUB(I,J) = SUM	MINV0190
C-----CALCULATE EQ.(54F) -----	MINV0200
DO 10 I=KAR,KOB	MINV0210
SUM = 0.	MINV0220
DO 8 K=LT,MT	MINV0230
8 SUM = SUM+G(I,K)*DUB(K,J)	MINV0240
10 DUB(I,J+6) = SUM	MINV0250
12 DUB(J,J+6) = DUB(J,J+6)+SI(J)**2	MINV0260
IF(NPV) 36,36,14	MINV0270
14 CONTINUE	MINV0280
DO 15 I=1,NPV	MINV0290
15 CVZ(10,I) = 0.	MINV0300
DO 20 J=KAR,KOB	MINV0310
DO 17 I=1,NSTX	MINV0320
SUM= 0.	MINV0330
DO 16 K=1,NPV	MINV0340
16 SUM= SUM+CVZ(I,K)*H(J,K)	MINV0350
DUB(I,J+3) = SUM	MINV0360
17 DUB(I,J) = DUB(I,J)+SUM	MINV0370
DO 18 I=1,NPV	MINV0380
18 DUB(I+12,J+6) = S(I)*H(J,I)	MINV0390
20 CONTINUE	MINV0400
DO 26 J=KAR,KOB	MINV0410
DO 24 I=KAR,KOB	MINV0420
SUM = 0.	MINV0430
SUM2= 0.	MINV0440
DO 22 K=LT,MT	MINV0450
22 SUM = SUM + DUB(K,J+3)*G(I,K)	MINV0460
DO 23 K=1,NPV	MINV0470
23 SUM2= SUM2+ H(I,K)*DUB(K+12,J+6)	MINV0480
DUB(J+3,I+6) = SUM	MINV0490
24 DUB(I+6,J+6) = SUM + SUM2	MINV0500
26 CONTINUE	MINV0510
DO 34 J=KAR,KOB	MINV0520
DO 28 I=KAR,KOB	MINV0530
28 DUB(I,J+6) = DUB(I,J+6) + DUB(I+3,J+6) + DUB(I+6,J+6)	MINV0540
DO 32 I=1,NPV	MINV0550
SUM = 0.	MINV0560
DO 30 K=LT,MT	MINV0570
30 SUM = SUM + G(J,K)*CVZ(K,I)	MINV0580
32 DUB(I,J+9) = SUM	MINV0590
34 CONTINUE	MINV0600
36 CONTINUE	MINV0610
IF(KAR-KOB) 37,46,37	MINV0620
37 CONTINUE	MINV0630
DO 39 J=KAR,KOB	MINV0640
DO 38 I=KAR,KOB	MINV0650
38 DUB(I+9,J+6) = 0.	MINV0660
39 DUB(J+9,J+6) = 1.	MINV0670
L = KOB-1	MINV0680
DO 42 I=KAR,L	MINV0690
M = I+1	MINV0700
SUM = DUB(1,I+6)	MINV0710
DO 42 J=KAR,KOB	MINV0720
DUB(1,J+6) = DUB(1,J+6)/SUM	MINV0730
DUB(1+9,J+6) = DUB(1+9,J+6)/SUM	MINV0740
DO 42 K=M,KOB	MINV0750

IF(I-J) 40,41,40	MINV0760
40 DUB(K ,J+6) = DUB(K ,J+6)-DUB(K,I+6)*DUB(I ,J+6)	MINV0770
41 DUB(K+9,J+6) = DUB(K+9,J+6)-DUB(K,I+6)*DUB(I+9,J+6)	MINV0780
42 CONTINUE	MINV0790
DO 44 I=KAR,KOB	MINV0800
44 DUB(KOB+9,I+6) = DUB(KOB+9,I+6)/DUB(KOB,KOB+6)	MINV0810
DO 45 I=KAR,L	MINV0820
M = KOB+KAR+6-I	MINV0830
DO 45 J=1,L	MINV0840
N = KOB+KAR+8-J	MINV0850
DO 45 K=KAR,KOB	MINV0860
45 DUB(N,K+6) = DUB(N,K+6)-DUB(N-9 ,M)*DUB(M+3,K+6)	MINV0870
GO TO 48	MINV0880
46 DUB(KAR+9,KAR+6) = 1./DUB(KAR,KAR+6)	MINV0890
48 CONTINUE	MINV0900
C-----CALCULATE EQ.(54E) -----	MINV0910
DO 54 I=1,NSTX	MINV0920
DO 51 J=KAR,KOB	MINV0930
SUM = 0.	MINV0940
DO 50 K=KAR,KOB	MINV0950
50 SUM = SUM + DUB(I,K)*DUB(K+9,J+6)	MINV0960
51 DUB(I,J+12) = SUM	MINV0970
DO 54 L=I,NSTX	MINV0980
SUM = 0.	MINV0990
C-----CALCULATE EQ.(54B) -----	MINV1000
DO 52 K=KAR,KOB	MINV1010
52 SUM = SUM + DUB(I,K+12)*DUB(L,K)	MINV1020
P(I,L) = P(I,L) - SUM	MINV1030
54 CONTINUE	MINV1040
IF(NPU) 66,66,56	MINV1050
C-----CALCULATE EQ.(54C) -----	MINV1060
56 CONTINUE	MINV1070
DO 57 I=1,NPU	MINV1080
57 CUZ(10,I) = 0.	MINV1090
DO 64 J=1,NPU	MINV1100
DO 60 I=KAR,KOB	MINV1110
SUM = 0.	MINV1120
DO 58 K=1,NSTX	MINV1130
58 SUM = SUM + G(I,K)*CUZ(K,J)	MINV1140
60 DUB(I,1) = SUM	MINV1150
DO 64 I=1,NSTX	MINV1160
SUM = 0.	MINV1170
DO 62 K=KAR,KOB	MINV1180
62 SUM = SUM + DUB(I,K+12)*DUB(K,1)	MINV1190
64 CUZ(I,J) = CUZ(I,J)-SUM	MINV1200
66 IF(NPV) 72,72,67	MINV1210
C-----CALCULATE EQ.(54D) -----	MINV1220
67 DO 70 I=1,NSTX	MINV1230
DO 70 J=1,NPV	MINV1240
SUM = 0.	MINV1250
DO 68 K=KAR,KOB	MINV1260
68 SUM = SUM + DUB(I,K+12)*DUB(J,K+9)	MINV1270
70 CVZ(I,J) = CVZ(I,J) - SUM	MINV1280
72 IF(NPC(1)-2) 74,108,74	MINV1290
74 IF(NPC(4)) 75,88,75	MINV1300
75 DO 82 I=1,NSTX	MINV1310
80 DUB(I,1) = OZ(I)	MINV1320
82 CONTINUE	MINV1330
C-----CALCULATE EQ.(54A) -----	MINV1340
DO 86 I=KAR,KOB	MINV1350

SUM = 0.	MINV1360
DO 84 J=1,NSTX	MINV1370
84 SUM = SUM + G(I,J)*DUB(J,1)	MINV1380
86 DATC(I) = DATC(I)+SUM	MINV1390
88 DO 90 I=KAR,KOB	MINV1400
J = LC(I)	MINV1410
DUB(I,2) = DATA(J)-DATC(I)	MINV1420
IF(MTYP.GT.5) GO TO 90	MINV1430
IF(J.EQ.1) GO TO 90	MINV1440
IF(ABS(DUB(I,2)).LT.3.1416) GO TO 90	MINV1450
DUB(I,2) = DUB(I,2)-SIGN(6.283185307179586,DUB(I,2))	MINV1460
90 CONTINUE	MINV1470
DO 92 I=1,NSTX	MINV1480
DZ(I) = 0.	MINV1490
DO 92 J=KAR,KOB	MINV1500
92 DZ(I) = DZ(I)+DUB(I,J+12)*DUB(J,2)	MINV1510
IF(NPC(4)) 294,298,294	MINV1520
294 DO 296 I=1,4	MINV1530
296 VO(I) = X(I+6) + DUB(I+6,1)	MINV1540
DZ(10) = -(VO(1)*DZ(7)+VO(2)*DZ(8)+VO(3)*DZ(9))/VO(4)	MINV1550
94 DO 96 I=1,NSTX	MINV1560
96 DZ(I) = DZ(I)+DUB(I,1)	MINV1570
GO TO 108	MINV1580
298 DZ(10) = -(X(7)*DZ(7)+X(8)*DZ(8)+X(9)*DZ(9))/X(10)	MINV1590
98 DO 100 I=1,10	MINV1600
100 X(I) = X(I)+DZ(I)	MINV1610
DATC(1) = SORT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	MINV1620
X(7) = X(7)/DATC(1)	MINV1630
X(8) = X(8)/DATC(1)	MINV1640
X(9) = X(9)/DATC(1)	MINV1650
X(10)=X(10)/DATC(1)	MINV1660
IF(NSTC.EQ.0) GO TO 103	MINV1670
DO 102 I=1,NSTC	MINV1680
J = NC(I)	MINV1690
102 C(J) = C(J)+DZ(I+10)	MINV1700
103 CONTINUE	MINV1710
IF(KSS) 108,108,104	MINV1720
104 DO 106 I=1,KSS	MINV1730
MTYP = NSS(I)	MINV1740
106 CALL STAT	MINV1750
108 P(8,7) = P(7,8)	MINV1760
P(9,7) = P(7,9)	MINV1770
P(9,8) = P(8,9)	MINV1780
DO 110 I=1,9	MINV1790
SUM = P(I,7)*X(7) + P(I,8)*X(8) + P(I,9)*X(9)	MINV1800
110 P(I,10) = -SUM/X(10)	MINV1810
P(10,10) = -(X(7)*P(7,10)+X(8)*P(8,10)+X(9)*P(9,10))/X(10)	MINV1820
DO 114 I=11,NSTX	MINV1830
SUM = P(7,I)*X(7) + P(8,I)*X(8) + P(9,I)*X(9)	MINV1840
114 P(10,I) = -SUM/X(10)	MINV1850
IF(NPU.EQ.0) GO TO 117	MINV1860
DO 116 I=1,NPU	MINV1870
SUM = CUZ(7,I)*X(7) + CUZ(8,I)*X(8) + CUZ(9,I)*X(9)	MINV1880
116 CUZ(10,I) = -SUM/X(10)	MINV1890
117 IF(NPV.EQ.0) GO TO 99	MINV1900
DO 118 I=1,NPV	MINV1910
SUM = CVZ(7,I)*X(7) + CVZ(8,I)*X(8) + CVZ(9,I)*X(9)	MINV1920
118 CVZ(10,I) = -SUM/X(10)	MINV1930
99 CONTINUE	MINV1940
RETURN	MINV1950
END	MINV1960

```

SUBROUTINE MOTION
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,V0(20),Z0(20),AG(5),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),G6(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KD,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
COMMON /MOD2/ X(3),Y(3),Z(3),AX(40),AY(40)
1 AZ(40),C(100),CCAPH(5),CONRO,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBR5,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPV,NPV,NS(9),NSS(5),NST,NSTC,NSTX,NT,NTR(9)
A NS(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPEN0/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
DATA ITER /5/
LT = 0
1 CONTINUE
CPH = COS(X(5))
SPH = SIN(X(5))
R = REO + X(4)
C-----CALCULATE EQ.(149)-----
YMASM=TAB(T,N4(1),TMAS(1),XMAS(1))
IF(T.GT.TONE) GO TO 3
YMAS=YMASM
GO TO 6
3 IF(T.LT.TTWO) GO TO 4
TAU=TTWO-TONE
GO TO 5

```

```

4 TAU=T -TONE
5 CONTINUE
YMAS=YMASM-(C(16)+C(17)*TAU+C(18)*TAU**2)
C-----CALCULATE EQ.(145)-----
6 RO=REO/SQRT(1.+(RERP2-1.)*SPH**2)
C-----CALCULATE EQ.(144)-----
HO = R-RO
CALL ATMDAT(HO,PE,ROEM,AS,XTEMP,XNU,SP(1))
C-----CALCULATE EQ.(151)-----
ROEC=C(22)*EXP(C(23)*HO)
ROE =C(21)*ROEM+ROEC
C-----CALCULATE EQ.(152)-----
UW = TAB(HO,N5(1),TOW(1),XUW(1)) + C(26)
VW = TAB(HO,N6(1),TVW(1),XVW(1)) + C(27)
C-----CALCULATE EQ.(140)-----
VA(1)=X(1)+UW
VA(2)=X(2)-R*OMEGA*CPH+VW
VA(3)=X(3)
C-----CALCULATE EQ.(141)-----
VA(5)=VA(1)**2+VA(2)**2+VA(3)**2
VA(4)=SQRT(VA(5))
C-----CALCULATE EQ.(142)-----
XQ=.5*ROE*VA(5)
C-----CALCULATE EQ.(148)-----
XRE=ROE*VA(4)*XLREF/XNU
C-----CALCULATE EQ.(143)-----
XM=VA(4)/AS
XQSM=XQ*SREF/YMAS
C-----CALCULATE EQ.(133)-----
SP(1) = (X( 7)-X( 8))*(X( 7)+X( 8))
SP(2) = (X( 9)-X(10))*(X( 9)+X(10))
A(1,1) = (X( 7)-X( 9))*(X( 7)+X( 9)) + (X( 8)-X(10))*(X( 8)+X(10))
A(2,2) = SP(1) + SP(2)
A(3,3) = SP(1) - SP(2)
A(1,2) = 2.*(X( 8)*X( 9)+X( 7)*X(10))
A(2,1) = 2.*(X( 8)*X( 9)-X( 7)*X(10))
A(1,3) = 2.*(X( 8)*X(10)-X( 7)*X( 9))
A(3,1) = 2.*(X( 8)*X(10)+X( 7)*X( 9))
A(3,2) = 2.*(X(10)*X( 9)-X( 7)*X( 8))
A(2,3) = 2.*(X(10)*X( 9)+X( 7)*X( 8))
C-----CALCULATE EQ.(139)-----
VB(1)=0.
VB(2)=0.
VB(3)=0.
DO 7 I=1,3
DO 7 J=1,3
7 VB(I)=VB(I)+A(I,J)*VA(J)
VB(4)=SQRT(VB(1)**2+VB(3)**2)
C-----CALCULATE EQ.(135)-----
SALP=VB(3)/VB(4)
CALP=VB(1)/VB(4)
C-----CALCULATE EQ.(136)-----
SBET=VB(2)/VA(4)
CBET=VB(4)/VA(4)
ALPH =ATAN2(SALP,CALP)
BETA =ATAN2(SBET,CBET)
IF(NPC(11).EQ.1) GO TO 8
XIND1=ALPH
XIND2=BETA
GO TO 9

```

```

MOTN0160
MOTN0170
MOTN0180
MOTN0190
MOTN0200
MOTN0210
MOTN0220
MOTN0230
MOTN0240
MOTN0250
MOTN0260
MOTN0270
MOTN0280
MOTN0290
MOTN0300
MOTN0310
MOTN0320
MOTN0330
MOTN0340
MOTN0350
MOTN0360
MOTN0370
MOTN0380
MOTN0390
MOTN0400
MOTN0410
MOTN0420
MOTN0430
MOTN0440
MOTN0450
MOTN0460
MOTN0470
MOTN0480
MOTN0490
MOTN0500
MOTN0510
MOTN0520
MOTN0530
MOTN0540
MOTN0550
MOTN0560
MOTN0570
MOTN0580
MOTN0590
MOTN0600
MOTN0610
MOTN0620
MOTN0630
MOTN0640
MOTN0650
MOTN0660
MOTN0670
MOTN0680
MOTN0690
MOTN0700
MOTN0710
MOTN0720
MOTN0730
MOTN0740
MOTN0750

```

8	VB(5)=SQRT(VB(2)**2+VB(3)**2)	MOTN0760
C-----	CALCULATE EQ.(137)	MOTN0770
	SETA=VB(5)/VA(4)	MOTN0780
	CETA=VB(1)/VA(4)	MOTN0790
C-----	CALCULATE EQ.(138)	MOTN0800
	SXZI=VB(2)/VB(5)	MOTN0810
	CXZI=VB(3)/VB(5)	MOTN0820
	ETA =ATAN2(SETA,CETA)	MOTN0830
	XZI =ATAN2(SXZI,CXZI)	MOTN0840
	XIND1=ETA	MOTN0850
	XIND2=XZI	MOTN0860
9	CALL AERO(XIND1,XIND2,XM,XRE,CF(1),CF(2),CF(3))	MOTN0870
	AB(1)=CF(1)*XGSM	MOTN0880
	AB(2)=CF(2)*XGSM	MOTN0890
	AB(3)=CF(3)*XGSM	MOTN0900
	XP(1) = CGM(1) + C(31)	MOTN0910
	XP(2) = CGM(2) + C(32)	MOTN0920
	XP(3) = CGM(3) + C(33)	MOTN0930
C-----	CALCULATE EQ.(153)	MOTN0940
	I=N11(2)	MOTN0950
	IF(N11(2)-1)12,10,12	MOTN0960
10	I = 2	MOTN0970
12	CONTINUE	MOTN0980
	SP(1)= TT(I+1)-TT(I-1)	MOTN0990
	HI(2)= .5*SP(1)	MOTN1000
	HI(1)= T + HI(2)	MOTN1010
	HI(2)= T - HI(2)	MOTN1020
	PMDOT(1)= (TAB(HI(1),N11(1),TT(1),TP(1))-TAB(HI(2),N11(1),TT(1),TP(1)))/SP(1)	MOTN1030
	X(1))/SP(1)	MOTN1040
	PMDOT(2)= (TAB(HI(1),N11(1),TT(1),TQ(1))-TAB(HI(2),N11(1),TT(1),TQ(1)))/SP(1)	MOTN1050
	X(1))/SP(1)	MOTN1060
	PMDOT(3)= (TAB(HI(1),N11(1),TT(1),TR(1))-TAB(HI(2),N11(1),TT(1),TR(1)))/SP(1)	MOTN1070
	X(1))/SP(1)	MOTN1080
C-----	CALCULATE EQ.(156)	MOTN1090
13	DO 14 I=1,3	MOTN1100
	J = 3*I	MOTN1110
	PDOT(I) = C(J+33)*PMDOT(1) + C(J+34)*PMDOT(2) + C(J+35)*PMDOT(3)	MOTN1120
14	CONTINUE	MOTN1130
C	SOLVE EQ.(III.114)	MOTN1140
	AP(1)=AB(1)	MOTN1150
	AP(2)=AB(2)	MOTN1160
	AP(3)=AB(3)	MOTN1170
	AP(4) = 2.*AP(1)*AP(3)/SQRT(AP(1)**2+AP(3)**2)	MOTN1180
C-----	CALCULATE EQ.(158)	MOTN1190
	DO 16 N = 1,ITER	MOTN1200
	DO 11 I=1,3	MOTN1210
	J = 3*I	MOTN1220
	PA(I)=C(J+33)*PM(1)+C(J+34)*PM(2)+C(J+35)*PM(3)+C(I+44)+C(I+47)*	MOTN1230
X	AP(1) + C(I+50)*AP(2) + C(I+53)*AP(3)	MOTN1240
11	CONTINUE	MOTN1250
	PA(1) = C(57)*AP(4)+PA(1)	MOTN1260
	SP(1) = PA(1)**2	MOTN1270
	SP(2) = PA(2)**2	MOTN1280
	SP(3) = PA(3)**2	MOTN1290
	TRAN(1,1)=-SP(2)-SP(3)	MOTN1300
	TRAN(1,2)= PA(1)*PA(2)-PDOT(3)	MOTN1310
	TRAN(1,3)= PA(1)*PA(3)+PDOT(2)	MOTN1320
	TRAN(2,1)= PA(1)*PA(2)+PDOT(3)	MOTN1330
	TRAN(2,2)=-SP(1)-SP(3)	MOTN1340
	TRAN(2,3)= PA(2)*PA(3)-PDOT(1)	MOTN1350

TRAN(3,1)= PA(1)*PA(3)-PDOT(2)	MOTN1360
TRAN(3,2)= PA(2)*PA(3)+PDOT(1)	MOTN1370
TRAN(3,3)=-SP(1)-SP(2)	MOTN1380
AP(1)=AB(1)+TRAN(1,1)*XP(1)+TRAN(1,2)*XP(2)+TRAN(1,3)*XP(3)	MOTN1390
AP(2)=AB(2)+TRAN(2,1)*XP(1)+TRAN(2,2)*XP(2)+TRAN(2,3)*XP(3)	MOTN1400
AP(3)=AB(3)+TRAN(3,1)*XP(1)+TRAN(3,2)*XP(2)+TRAN(3,3)*XP(3)	MOTN1410
AP(4) = 2.*AP(1)*AP(3)/SQRT(AP(1)**2+AP(3)**2)	MOTN1420
16 CONTINUE	MOTN1430
IF(LT) 15,15,99	MOTN1440
15 CONTINUE	MOTN1450
C-----CALCULATE EQ.(132) -----	MOTN1460
AG(1) = AB(1)*A(1,1)+AB(2)*A(2,1)+AB(3)*A(3,1)	MOTN1470
AG(2) = AB(1)*A(1,2)+AB(2)*A(2,2)+AB(3)*A(3,2)	MOTN1480
AG(3) = AB(1)*A(1,3)+AB(2)*A(2,3)+AB(3)*A(3,3)	MOTN1490
C PARAMETERS USED FREQUENTLY IN REMAINING SUBROUTINES	MOTN1500
PAR(1) = X(1)*X(1) + X(2)*X(2)	MOTN1510
PAR(2)=XMU/R**2	MOTN1520
PAR(3)=XMUJ/R**4	MOTN1530
PAR(4) = 1./(2.*R)	MOTN1540
PAR(5) = X(1)*X(3)-X(2)*X(2)*TPH	MOTN1550
PAR(6) = 1. - 1.5*CPH*CPH	MOTN1560
F1(2,2)= (X(1)*TPH+X(3))/R	MOTN1570
F1(2,3)= X(2)/R	MOTN1580
F1(2,1)= F1(2,3)*TPH	MOTN1590
DX(5) = X(1)/R	MOTN1600
F3(1,8) = -.5*(PA(1)-F1(2,3))	MOTN1610
F3(1,9) = -.5*(PA(2)+DX(5))	MOTN1620
F3(1,10) = -.5*(PA(3)+F1(2,1))	MOTN1630
F3(2,9) = F3(1,10) + PA(3)	MOTN1640
F3(2,10) = F3(1,9) + DX(5)	MOTN1650
F3(3,10) = F3(1,8) + PA(1)	MOTN1660
C-----CALCULATE EQ.(127) -----	MOTN1670
DX(1) = AG(1) + PAR(5)/R - PAR(3)*SPH*CPH	MOTN1680
DX(2) = AG(2) + X(2)*F1(2,2)	MOTN1690
DX(3) = AG(3) + PAR(2) - PAR(1)/R - PAR(3)*PAR(6)	MOTN1700
C-----CALCULATE EQ.(128) -----	MOTN1710
DX(4) = -X(3)	MOTN1720
DX(6) = F1(2,3)/CPH - OMEGA	MOTN1730
C-----CALCULATE EQ.(129) -----	MOTN1740
DX(7) = X(8)*F3(1, 8) + X(9)*F3(1, 9) + X(10)*F3(1,10)	MOTN1750
DX(8) = -X(7)*F3(1, 8) + X(9)*F3(2, 9) + X(10)*F3(2,10)	MOTN1760
DX(9) = -X(7)*F3(1, 9) - X(8)*F3(2, 9) + X(10)*F3(3,10)	MOTN1770
DX(10) = -X(7)*F3(1,10) - X(8)*F3(2,10) - X(9)*F3(3,10)	MOTN1780
99 RETURN	MOTN1790
ENTRY AUXIL	MOTN1800
LT = 1	MOTN1810
GO TO 1	MOTN1820
END	MOTN1830

```

SUBROUTINE OBSERV
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHOT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
DIMENSION CTM(6),RCC(3),RCD(3),RCDX(3,6),RCX(3,6),
A XA(5),XAX(5,7),XC(3),XCX(3,7),XLB(3),XLG(3),
B XLGE(3,4),XLGX(2,4),XS(3),XSC(3),XSD(3),XSDC(3),
C XSDX(3,6),XSX(3,3),CI(3,3),CJ(3,3)
EQUIVALENCE (DPH(1,1),CTM(1)),(DPH(7,1),RCC(1)),
N (DPH(10,1),RCD(1)),(DPH(3,2),RCDX(1,1)),
O (DPH(1,4),RCX(1,1)),(DPH(9,5),XA(1)),
P (DPH(4,6),XAX(1,1)),(DPH(9,9),XC(1)),
G (DPH(2,10),XCX(1,1)),(DPH(3,12),XLB(1)),
R (DPH(6,12),XLG(1)),(DPH(9,12),XLGE(1,1)),
S (DPH(1,14),XLGX(1,1)),(DPH(9,14),XS(1)),
T (DPH(2,15),XSC(1)),(DPH(5,15),XSD(1)),
U (DPH(8,15),XSDC(1)),(DPH(1,16),XSDX(1,1)),
V (DPH(9,17),XSX(1,1)),(DPH(8,18),CI(1,1)),
W (DPH(7,19),CJ(1,1)),(DPH(6,20),CAZC),
OBSV0010
OBSV0020
OBSV0030
OBSV0040
OBSV0050
OBSV0060
OBSV0070
OBSV0080
OBSV0090
OBSV0100
OBSV0110
OBSV0120
OBSV0130
OBSV0140
OBSV0150

```

```

X          (DPH(7,20),CDP      ), (DPH(8,20),CDY      ), OBSV0160
Y          (DPH(9,20),CELC     ), (DPH(10,20),CGR     ), OBSV0170
Z          (DPH(1,21),CLR      ), (DPH(2,21),CTH     ), OBSV0180
1          (DPH(3,21),SAZC     ), (DPH(4,21),SDP     ), OBSV0190
2          (DPH(5,21),SDY      ), (DPH(6,21),SELC     ), OBSV0200
3          (DPH(7,21),SGR      ), (DPH(8,21),SLR     ), OBSV0210
4          (DPH(9,21),STH      ), (DPH(10,21),THETA    ), OBSV0220
MT = 0
IF(L1-2) 14,10,14 OBSV0230
10 IF(NPC(5)) 14,12,14 OBSV0240
12 WRITE(OUT,1000) OBSV0250
1000 FORMAT(5X,6HPOINTS,5X,4HTYPE,4X,4HTIME,8X,5HCOMP1,10X,5HCOMP2,10X, OBSV0270
15HCOMP3,10X,4HSIG1,11X,4HSIG2,11X,4HSIG3) OBSV0280
L1=1 OBSV0290
14 IF(MTYP-6) 16,150,15 OBSV0300
15 IF(MTYP-8) 115,120,125 OBSV0310
16 N = 60+MTYP*15 OBSV0320
C-----CALCULATE EQ.(236) ----- OBSV0330
100 THETA=X(6)-C(N+14) OBSV0340
STH=SIN(THETA) OBSV0350
CTH=COS(THETA) OBSV0360
VO(1)= CPH*CPHDT(MTYP) OBSV0370
VO(2)= CPH*SPHDT(MTYP) OBSV0380
VO(3)= SPH*CPHDT(MTYP) OBSV0390
VO(4)= SPH*SPHDT(MTYP) OBSV0400
SP(1) = ROT(MTYP) + C(N+15) OBSV0410
VO(5) = SP(1)*CCAPH(MTYP) OBSV0420
VO(6) = SP(1)*SCAPH(MTYP) OBSV0430
C-----CALCULATE EQ.(235) ----- OBSV0440
102 XS(1)= R*(CTH*VO(1)+VO(4))-VO(5) OBSV0450
XS(2)= R*STH*CPH OBSV0460
XS(3)= -R*(CTH*VO(2)-VO(3))+VO(6) OBSV0470
VO(8)= SGRT(XS(2)**2+XS(3)**2) OBSV0480
VO(9)= VO(8)**2 OBSV0490
C-----CALCULATE EQ.(238A)----- OBSV0500
CTM(1)= SQRT(XS(1)**2+VO(9)) OBSV0510
C-----CALCULATE EQ.(238B)----- OBSV0520
SAZC= XS(2)/VO(8) OBSV0530
CAZC= XS(3)/VO(8) OBSV0540
C-----CALCULATE EQ.(238C)----- OBSV0550
SELC= XS(1)/CTM(1) OBSV0560
CELC= VO(8)/CTM(1) OBSV0570
CTM(2)= ATAN2(XS(2),XS(3)) OBSV0580
CTM(3)= ATAN2(XS(1),VO(8)) OBSV0590
C-----CALCULATE EQ.(239) ----- OBSV0600
DFM(1)= C(N+1)*CTM(1)+C(N+4)+C(N+10)/SELC OBSV0610
DFM(2)= C(N+2)*CTM(2)+C(N+5) OBSV0620
DFM(3)= C(N+3)*CTM(3)+C(N+6)+C(N+11)*CELC/SELC OBSV0630
IF(MO(MTYP)) 106,104,106 OBSV0640
104 IF(NPC(1)-1) 106,18,106 OBSV0650
C-----CALCULATE EQ.(246) ----- OBSV0660
106 XSX(1,1)= (XS(1)+VO(5))/R OBSV0670
XSX(1,2)= R*(VO(2)-CTH*VO(3)) OBSV0680
XSX(1,3)= -XS(2)*CPHDT(MTYP) OBSV0690
XSX(2,1)= XS(2)/R OBSV0700
XSX(2,2)= -R*STH*SPH OBSV0710
XSX(2,3)= R*CTH*CPH OBSV0720
XSX(3,1)= (XS(3)-VO(6))/R OBSV0730
XSX(3,2)= R*(CTH*VO(4)+VO(1)) OBSV0740
XSX(3,3)= XS(2)*SPHDT(MTYP) OBSV0750

```

IF(MO(MTYP)) 108,18,108	OBSV0760
C-----CALCULATE EQ.(241) -----	OBSV0770
108 DO 112 I=1,3	OBSV0780
SUM=0.	OBSV0790
DO 110 J=1,3	OBSV0800
110 SUM=SUM+XSX(I,J)*DX(J+3)	OBSV0810
112 XSD(I)=SUM	OBSV0820
C-----CALCULATE EQ.(240) -----	OBSV0830
CTM(4)= (XS(1)*XSD(1)+XS(2)*XSD(2)+XS(3)*XSD(3))/CTM(1)	OBSV0840
CTM(5)= (XS(3)*XSD(2)-XS(2)*XSD(3))/VO(9)	OBSV0850
CTM(6)= (CTM(1)*XSD(1)-XS(1)*CTM(4))/(CTM(1)*VO(8))	OBSV0860
DFM(1)= DFM(1)+C(N+7)*CTM(4)	OBSV0870
DFM(2)= DFM(2)+C(N+8)*CTM(5)	OBSV0880
DFM(3)= DFM(3)+C(N+9)*CTM(6)	OBSV0890
GO TO 18	OBSV0900
115 DFM(1)=X(1)	OBSV0910
DFM(2)= X(2)	OBSV0920
DFM(3)= X(3)	OBSV0930
GO TO 18	OBSV0940
120 DFM(1)=X(4)	OBSV0950
DFM(2)= X(5)	OBSV0960
DFM(3)= X(6)	OBSV0970
GO TO 18	OBSV0980
C-----CALCULATE EQ.(264) -----	OBSV0990
125 F1(1,1)= C(65)*C(69)-C(66)*C(68)	OBSV1000
F1(1,2)= -C(62)*C(69)+C(63)*C(68)	OBSV1010
F1(1,3)= C(62)*C(66)-C(63)*C(65)	OBSV1020
F1(2,1)= -C(64)*C(69)+C(66)*C(67)	OBSV1030
F1(2,2)= C(61)*C(69)-C(63)*C(67)	OBSV1040
F1(2,3)= -C(61)*C(66)+C(63)*C(64)	OBSV1050
F1(3,1)= C(64)*C(68)-C(65)*C(67)	OBSV1060
F1(3,2)= -C(61)*C(68)+C(62)*C(67)	OBSV1070
F1(3,3)= C(61)*C(65)-C(62)*C(64)	OBSV1080
C-----CALCULATE EQ.(265) -----	OBSV1090
VO(4)= C(61)*F1(1,1)+C(62)*F1(2,1)+C(63)*F1(3,1)	OBSV1100
DO 128 I=1,3	OBSV1110
DO 127 J=1,3	OBSV1120
C-----CALCULATE EQ.(266) -----	OBSV1130
127 CI(I,J)= F1(I,J)/VO(4)	OBSV1140
128 VO(I)= AP(I)- C(69+I)	OBSV1150
C-----CALCULATE EQ.(258) -----	OBSV1160
DO 130 I=1,3	OBSV1170
DFM(I)= 0.	OBSV1180
DO 130 J=1,3	OBSV1190
130 DFM(I)= DFM(I) + CI(I,J)*VO(J)	OBSV1200
GO TO 18	OBSV1210
C 150 CALCULATE AMR	OBSV1220
150 SDP= SIN(C(151))	OBSV1230
CDP= COS(C(151))	OBSV1240
SDY= SIN(C(152))	OBSV1250
CDY= COS(C(152))	OBSV1260
C-----CALCULATE EQ.(269) -----	OBSV1270
XLB(1)= CDY*CDP	OBSV1280
XLB(2)= SDY	OBSV1290
XLB(3)= CDY*SDP	OBSV1300
C-----CALCULATE EQ.(270) -----	OBSV1310
DO 152 I=1,3	OBSV1320
XLG(I)=0.	OBSV1330
DO 152 J=1,3	OBSV1340
152 XLG(I)=XLG(I)+A(J,I)*XLB(J)	OBSV1350

VO(1)= REO**2	OBSV1360
C-----CALCULATE EQ.(271A)-----	OBSV1370
VO(2)= ATAN2(XLG(2),XLG(1))	OBSV1380
C-----CALCULATE EQ.(271B)-----	OBSV1390
SP(1)= SQRT(XLG(1)**2+XLG(2)**2)	OBSV1400
VO(3)=-ATAN2(XLG(3),SP(1))	OBSV1410
SLR= SIN(VO(2))	OBSV1420
CLR= COS(VO(2))	OBSV1430
SGR= SIN(VO(3))	OBSV1440
CGR= COS(VO(3))	OBSV1450
C-----CALCULATE EQ.(277) -----	OBSV1460
XA(1)= SLR*CGR	OBSV1470
XA(2)= R*CPH	OBSV1480
XA(3)= CPH*SGR-SPH*CLR*CGR	OBSV1490
XA(4)= R*SPH	OBSV1500
XA(5)= SPH*SGR+CPH*CLR*CGR	OBSV1510
C-----CALCULATE EQ.(276) -----	OBSV1520
XC(1)= XA(1)**2 + XA(3)**2 + RERP2*XA(5)**2	OBSV1530
XC(2)= 2.*(XA(2)*XA(3)+ RERP2*XA(4)*XA(5))	OBSV1540
XC(3)= XA(2)**2 + RERP2*XA(4)**2 - VO(1)	OBSV1550
SP(2)= XC(2)**2 - 4.*XC(1)*XC(3)	OBSV1560
IF(SP(2)) 154,156,156	OBSV1570
154 WRITE(OUT,5022)	OBSV1580
5022 FORMAT(49H IMAGINARY OR NEGATIVE SOLUTION ON AIRBORNE RADAR)	OBSV1590
DO 160 I=1,3	OBSV1600
DFM(I) = 0.	OBSV1610
DO 158 J=1,NSTX	OBSV1620
158 G(I,J) = 0.	OBSV1630
DO 160 J=1,NPV	OBSV1640
H(I,J) = 0.	OBSV1650
160 CONTINUE	OBSV1660
SI(1) = 1.E20	OBSV1670
RETURN	OBSV1680
C-----CALCULATE EQ.(273) -----	OBSV1690
156 DFM(1)= -.5*(XC(2)+SQRT(SP(2)))/XC(1)	OBSV1700
IF(DFM(1).LT.0.) GO TO 154	OBSV1710
DFM(2)= 0.	OBSV1720
DFM(3)= 0.	OBSV1730
18 IF(DCOMP.LT.0.) GO TO 80	OBSV1740
DO 20 I=1,3	OBSV1750
SP(I) = SYG(I,MTYP)	OBSV1760
IF(NPC(1).EQ.0) SP(I) = SP(I)+SIGM(I)	OBSV1770
20 KC(I)=0	OBSV1780
IF(KN) 22,22,24	OBSV1790
22 KOB=KAR	OBSV1800
GO TO 26	OBSV1810
24 KOB=JNBR	OBSV1820
26 DO 28 I=KAR,KOB	OBSV1830
J=LC(I)	OBSV1840
DATC(I)=DFM(J)	OBSV1850
SI(I)=SP(J)	OBSV1860
NCOUNT=NCOUNT+1	OBSV1870
28 KC(J) = NCOUNT	OBSV1880
30 IF(NPC(5)) 34,32,34	OBSV1890
32 CONTINUE	OBSV1900
WRITE(OUT,1002) (KC(I),I=1,3),MTYP,TO,(DFM(I),I=1,3),(SP(I),I=1,3)	OBSV1910
1002 FORMAT(1X,I4,1H,I4,1H,I4,2X,I2,1X,F10.4,F15.2,5F15.6)	OBSV1920
34 DO 36 I=1,NSTX	OBSV1930
DO 36 J=KAR,KOB	OBSV1940
36 G(J,I)=0.	OBSV1950

IF(MTYP-6) 200,250,270	OBSV1960
C 200 CALCULATE G(1-10) FOR R,A,E	OBSV1970
C-----CALCULATE EQ.(244)-----	OBSV1980
200 DO 202 I=1,3	OBSV1990
RCX(1,I)= (XSX(1,I)*XS(1)+XSX(2,I)*XS(2)+XSX(3,I)*XS(3))/CTM(1)	OBSV2000
RCX(2,I)= (XSX(2,I)*XS(3)-XSX(3,I)*XS(2))/VO(9)	OBSV2010
202 RCX(3,I)= (XSX(1,I)-RCX(1,I)*SELC)/VO(8)	OBSV2020
IF(MO(MTYP)) 204,218,204	OBSV2030
204 SP(1)= R*CPH	OBSV2040
SP(2)= DX(5)/R	OBSV2050
SP(3)= X(2)/(R*SP(1))	OBSV2060
SP(4)= X(2)*TPH/SP(1)	OBSV2070
C-----CALCULATE EQ.(247)-----	OBSV2080
DO 206 I=1,3	OBSV2090
XSDX(I,1)= XSX(I,2)/R	OBSV2100
XSDX(I,2)= XSX(I,3)/SP(1)	OBSV2110
XSDX(I,3)=-XSX(I,1)	OBSV2120
XSDX(I,4)=-XSX(I,2)*SP(2)-XSX(I,3)*SP(3)	OBSV2130
206 XSDX(I,5)= XSX(I,3)*SP(4)	OBSV2140
VO(10)=-X(3)/R	OBSV2150
SP(4)= DX(6)/R	OBSV2160
SP(5)= DX(5)/R	OBSV2170
SP(6)=-TPH*DX(6)	OBSV2180
SP(7)=-R*DX(5)	OBSV2190
SP(1)= CTH*DX(6)/STH - TPH*DX(5)	OBSV2200
SP(3)= SP(1)	OBSV2210
SP(2)=-STH*DX(6)/CTH - TPH*DX(5)	OBSV2220
DO 208 I=1,3	OBSV2230
XSDX(I,4)= XSDX(I,4)+XSX(I,3)*SP(4)+XSX(I,2)*SP(5)	OBSV2240
XSDX(I,5)= XSDX(I,5)+XSX(I,2)*VO(10)+XSX(I,3)*SP(6)+XSX(I,1)*SP(7)	OBSV2250
208 XSDX(I,6)= XSX(I,3)*VO(10)+XSX(I,3)*SP(I)	OBSV2260
VO(11)=-XSD(3)+2.*CTM(5)*XS(2)	OBSV2270
VO(12)= XSD(2)-2.*CTM(5)*XS(3)	OBSV2280
SP(1)= -CTM(6)*XS(2)/CELC	OBSV2290
SP(2)= -CTM(6)*XS(3)/CELC	OBSV2300
SP(3)= XSD(1)-CTM(6)*VO(8)	OBSV2310
C-----CALCULATE EQ.(245)-----	OBSV2320
DO 216 I=1,6	OBSV2330
IF(I-3) 210,210,212	OBSV2340
210 RCDX(1,I)=0.	OBSV2350
RCDX(2,I)=0.	OBSV2360
RCDX(3,I)=0.	OBSV2370
GO TO 214	OBSV2380
212 RCDX(1,I)=XSX(1,I-3)*XSD(1)+XSX(2,I-3)*XSD(2)+XSX(3,I-3)*XSD(3)	OBSV2390
X -RCX(1,I-3)*CTM(4)	OBSV2400
RCDX(2,I)=XSX(3,I-3)*VO(12)+XSX(2,I-3)*VO(11)	OBSV2410
RCDX(3,I)=-XSX(1,I-3)*CTM(4)+XSX(2,I-3)*SP(1)+XSX(3,I-3)*SP(2)	OBSV2420
X +RCX(1,I-3)*SP(3)	OBSV2430
214 RCDX(1,I)=(RCDX(1,I)+XSDX(1,I)*XS(1)+XSDX(2,I)*XS(2)	OBSV2440
X +XSDX(3,I)*XS(3))/CTM(1)	OBSV2450
RCDX(2,I)=(RCDX(2,I)+XSDX(2,I)*XS(3)-XSDX(3,I)*XS(2))/VO(9)	OBSV2460
216 RCDX(3,I)=((RCDX(3,I)-RCDX(1,I)*XS(1))/CTM(1)+XSDX(1,I))/VO(8)	OBSV2470
218 VO(13)= C(N+10)*CELC/SELC**2	OBSV2480
VO(14)= C(N+3)-C(N+11)/SELC**2	OBSV2490
DO 230 I=1,6	OBSV2500
IF(I-3) 220,220,222	OBSV2510
220 GG(1)=0.	OBSV2520
GG(2)=0.	OBSV2530
GG(3)=0.	OBSV2540
GO TO 224	OBSV2550

```

C-----CALCULATE EQ.(243)-----
222 GG(1)= C(N+1)*RCX(1,I-3)-VO(13)*RCX(3,I-3)
    GG(2)= C(N+2)*RCX(2,I-3)
    GG(3)= VO(14)*RCX(3,I-3)
224 IF(MO(MTYP)) 226,228,226
226 GG(1)= GG(1)+ C(N+7)*RCDX(1,I)
    GG(2)= GG(2)+ C(N+8)*RCDX(2,I)
    GG(3)= GG(3)+ C(N+9)*RCDX(3,I)
228 DO 230 K=KAR,KOB
    J=LC(K)
230 G(K,I)=GG(J)
232 CONTINUE
    GO TO 38
C-----CALCULATE EQ.(286)-----
250 XLGE(1,1)= 2.*( X( 7)*XLB(1)-X(10)*XLB(2)+X( 9)*XLB(3))
    XLGE(1,2)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
    XLGE(1,3)= 2.*(-X( 9)*XLB(1)+X( 8)*XLB(2)+X( 7)*XLB(3))
    XLGE(1,4)= 2.*(-X(10)*XLB(1)-X( 7)*XLB(2)+X( 8)*XLB(3))
    XLGE(2,1)= 2.*( X(10)*XLB(1)+X( 7)*XLB(2)-X( 8)*XLB(3))
    XLGE(2,2)= 2.*( X( 9)*XLB(1)-X( 8)*XLB(2)-X( 7)*XLB(3))
    XLGE(2,3)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
    XLGE(2,4)= 2.*( X( 7)*XLB(1)-X(10)*XLB(2)+X( 9)*XLB(3))
    XLGE(3,1)= 2.*(-X( 9)*XLB(1)+X( 8)*XLB(2)+X( 7)*XLB(3))
    XLGE(3,2)= 2.*( X(10)*XLB(1)+X( 7)*XLB(2)-X( 8)*XLB(3))
    XLGE(3,3)= 2.*(-X( 7)*XLB(1)+X(10)*XLB(2)-X( 9)*XLB(3))
    XLGE(3,4)= 2.*( X( 8)*XLB(1)+X( 9)*XLB(2)+X(10)*XLB(3))
    SP(4)= SGR/CGR
    SP(3)= XLG(1)**2 + XLG(2)**2
    SP(1)= SQRT(SP(3))
    DO 258 I=1,4
C-----CALCULATE EQ.(284)-----
    XLGX(1,I) = (XLG(1)*XLGE(2,I)-XLG(2)*XLGE(1,I))/SP(3)
C-----CALCULATE EQ.(285)-----
258 XLGX(2,I) =-SP(1)*XLGE(3,I)-SP(4)*(XLG(1)*XLGE(1,I)+XLG(2)*XLGE(2,
1I))
    VO(4)= -SLR*SGR
    VO(5)= CLR*CGR
    VO(6)= CPH*CGR+SPH*CLR*SGR
    VO(7)= SPH*XA(1)
    VO(9)= SPH*CGR-CPH*CLR*SGR
    VO(10)= CPH*XA(1)
C-----CALCULATE EQ.(283)-----
    DO 260 I=1,5
    DO 260 J=1,7
260 XAX(1,J)= 0.
    DO 262 I=1,4
    XAX(1,I+3) = VO(4)*XLGX(2,I) + VO(5)*XLGX(1,I)
    XAX(3,I+3) = VO(6)*XLGX(2,I) + VO(7)*XLGX(1,I)
262 XAX(5,I+3) = VO(9)*XLGX(2,I) - VO(10)*XLGX(1,I)
    XAX(2,1) = CPH
    XAX(2,2) =-XA(4)
    XAX(3,2) =-XA(5)
    XAX(4,1) = SPH
    XAX(4,2) = XA(2)
    XAX(5,2) = XA(3)
C-----CALCULATE EQ.(282)-----
    DO 264 I=1,7
    XCX(1,I)= 2.*(XA(1)*XAX(1,I)+XA(3)*XAX(3,I)+RERP2*XA(5)*XAX(5,I))
    XCX(2,I)= 2.*(XA(2)*XAX(3,I)+XA(3)*XAX(2,I)+RERP2*(XA(4)*XAX(5,I)
1 + XA(5)*XAX(4,I)))

```

```

OBSV2560
OBSV2570
OBSV2580
OBSV2590
OBSV2600
OBSV2610
OBSV2620
OBSV2630
OBSV2640
OBSV2650
OBSV2660
OBSV2670
OBSV2680
OBSV2690
OBSV2700
OBSV2710
OBSV2720
OBSV2730
OBSV2740
OBSV2750
OBSV2760
OBSV2770
OBSV2780
OBSV2790
OBSV2800
OBSV2810
OBSV2820
OBSV2830
OBSV2840
OBSV2850
OBSV2860
OBSV2870
OBSV2880
OBSV2890
OBSV2900
OBSV2910
OBSV2920
OBSV2930
OBSV2940
OBSV2950
OBSV2960
OBSV2970
OBSV2980
OBSV2990
OBSV3000
OBSV3010
OBSV3020
OBSV3030
OBSV3040
OBSV3050
OBSV3060
OBSV3070
OBSV3080
OBSV3090
OBSV3100
OBSV3110
OBSV3120
OBSV3130
OBSV3140
OBSV3150

```

264	XCX(3,I)= 2.*(XA(2)*XAX(2,I)+RERP2*XA(4)*XAX(4,I))	OBSV3160
	G(1,1)= 0.	OBSV3170
	G(1,2)= 0.	OBSV3180
	G(1,3)= 0.	OBSV3190
	VO(11)= 2.*XC(1)*DFM(1)+XC(2)	OBSV3200
	VO(12)= (DFM(1)+ XC(3)/VO(11))/XC(1)	OBSV3210
	VO(13)= (.5-.5*XC(2)/VO(11))/XC(1)	OBSV3220
	VO(14)= 1./VO(11)	OBSV3230
C-----	CALCULATE EQ.(281) -----	OBSV3240
	DO 266 I=1,7	OBSV3250
266	G(1,I+3)= -VO(12)*XCX(1,I)-VO(13)*XCX(2,I)-VO(14)*XCX(3,I)	OBSV3260
	GO TO 38	OBSV3270
270	IF(MTYP-8) 272,274,290	OBSV3280
272	LT=0	OBSV3290
	GO TO 276	OBSV3300
274	LT=3	OBSV3310
276	DO 284 I=KAR,KOB	OBSV3320
	J=LC(I)	OBSV3330
284	G(I,LT+J) = 1.	OBSV3340
	GO TO 38	OBSV3350
290	DO 296 I=1,10	OBSV3360
	DO 292 J=1,3	OBSV3370
	GG(J)=0.	OBSV3380
	DO 292 K=1,3	OBSV3390
292	GG(J)= GG(J)+CI(J,K)*PAXP(K,I)	OBSV3400
	DO 294 K=KAR,KOB	OBSV3410
	J=LC(K)	OBSV3420
294	G(K,I)=GG(J)	OBSV3430
296	CONTINUE	OBSV3440
38	CONTINUE	OBSV3450
	IF(NSTC) 40,40,46	OBSV3460
40	IF(NPV) 99,99,42	OBSV3470
42	II=1	OBSV3480
	IP=1	OBSV3490
44	JJ=MCC(II)	OBSV3500
	GO TO 50	OBSV3510
46	II=1	OBSV3520
	IP=0	OBSV3530
48	JJ=NC(II)	OBSV3540
50	GG(1)=0.	OBSV3550
	GG(2)=0.	OBSV3560
	GG(3)=0.	OBSV3570
	IF(MTYP.GE.6) GO TO 375	OBSV3580
	IF(JJ-N) 60,60,54	OBSV3590
54	IF(JJ-N-15) 56,56,60	OBSV3600
56	JN=JJ-N	OBSV3610
	IF(JN-12) 58,58,350	OBSV3620
58	GO TO(300,301,302,303,304,305,306,307,308,309,310,311),JN	OBSV3630
60	II=II+1	OBSV3640
	DO 66 I=KAR,KOB	OBSV3650
	J=LC(I)	OBSV3660
	IF(IP) 62,62,64	OBSV3670
62	G(I,II+ 9) = GG(J)	OBSV3680
	GO TO 66	OBSV3690
64	H(I,II-1) = GG(J)	OBSV3700
66	CONTINUE	OBSV3710
	IF(IP) 68,68,70	OBSV3720
68	IF(II-NSTC) 48,48,40	OBSV3730
70	IF(II-NPV) 44,44,99	OBSV3740
C-----	CALCULATE EQ.(248) -----	OBSV3750

300 GG(1) = CTM(1)	OBSV3760
GO TO 60	OBSV3770
301 GG(2) = CTM(2)	OBSV3780
GO TO 60	OBSV3790
302 GG(3) = CTM(3)	OBSV3800
GO TO 60	OBSV3810
303 GG(1) = 1.	OBSV3820
GO TO 60	OBSV3830
304 GG(2) = 1.	OBSV3840
GO TO 60	OBSV3850
305 GG(3) = 1.	OBSV3860
GO TO 60	OBSV3870
306 GG(1) = CTM(4)	OBSV3880
GO TO 60	OBSV3890
307 GG(2) = CTM(5)	OBSV3900
GO TO 60	OBSV3910
308 GG(3) = CTM(6)	OBSV3920
GO TO 60	OBSV3930
309 GG(1) = 1./SELC	OBSV3940
GO TO 60	OBSV3950
310 GG(3) = CELC/SELC	OBSV3960
311 GO TO 60	OBSV3970
350 SP(1)= SIN(C(N+13))	OBSV3980
SP(2)= COS(C(N+13))	OBSV3990
IF(JN-14) 352,354,356	OBSV4000
352 VO(15)=RERP2*(CPHDT(MTYP)/SP(2))**2	OBSV4010
VO(16)=- (ROT(MTYP)/REO)**2*(RERP2-1.)*SP(1)*SP(2)*ROT(MTYP)	OBSV4020
C-----CALCULATE EQ.(252) -----	OBSV4030
XSC(1)= XS(3)*VO(15)-VO(6)-VO(16)*CCAPH(MTYP)	OBSV4040
XSC(2)= 0.	OBSV4050
XSC(3)=-XS(1)*VO(15)-VO(5)+ VO(16)*SCAPH(MTYP)	OBSV4060
GO TO 358	OBSV4070
354 XSC(1)=-XSX(1,3)	OBSV4080
XSC(2)=-XSX(2,3)	OBSV4090
XSC(3)=-XSX(3,3)	OBSV4100
GO TO 358	OBSV4110
356 XSC(1)=-CCAPH(MTYP)	OBSV4120
XSC(2)= 0.	OBSV4130
XSC(3)= SCAPH(MTYP)	OBSV4140
C-----CALCULATE EQ.(250) -----	OBSV4150
358 RCC(1)=(XSC(1)*XS(1)+XSC(2)*XS(2)+XSC(3)*XS(3))/CTM(1)	OBSV4160
RCC(2)=(XSC(2)*XS(3)-XSC(3)*XS(2))/VO(9)	OBSV4170
RCC(3)=(XSC(1)-RCC(1)*SELC)/VO(8)	OBSV4180
C-----CALCULATE EQ.(249) -----	OBSV4190
GG(1)= C(N+1)*RCC(1)-VO(13)*RCC(3)	OBSV4200
GG(2)= C(N+2)*RCC(2)	OBSV4210
GG(3)= VO(14)*RCC(3)	OBSV4220
IF(MO(MTYP)) 360,60,360	OBSV4230
360 IF(JN-14) 362,364,366	OBSV4240
362 SP(3)= VO(15)-1.	OBSV4250
SP(5)= XS(2)*DX(6)	OBSV4260
C-----CALCULATE EQ.(253A)-----	OBSV4270
XSDC(1)= VO(10)*(XSC(1)+VO(16)*CCAPH(MTYP)-VO(6)*SP(3))	OBSV4280
X +VO(15)*(XSX(3,2)*DX(5)+SP(5)*SPHDT(MTYP))	OBSV4290
XSDC(2)= 0.	OBSV4300
XSDC(3)= VO(10)*(XSC(3)-VO(16)*SCAPH(MTYP)-VO(5)*SP(3))	OBSV4310
X +VO(15)*(-XSX(1,2)*DX(5)+SP(5)*CPHDT(MTYP))	OBSV4320
GO TO 368	OBSV4330
364 SP(1)= XSX(2,3)*DX(6)+XSX(2,2)*DX(5)	OBSV4340
C-----CALCULATE EQ.(253B)-----	OBSV4350

```

XSDC(1)= V0(10)*XSC(1)+ SP(1)*CPHDT(MTYP)
XSDC(2)= V0(10)*XSC(2)+ XS(2)*DX(6)+R*CTH*SPH*DX(5)
XSDC(3)= V0(10)*XSC(3)- SP(1)*SPHDT(MTYP)
GO TO 368
366 RCDC(1)= 0.
RCDC(2)= 0.
RCDC(3)= 0.
GO TO 370
C-----CALCULATE EQ.(251)-----
368 RCDC(1)= XSDC(1)*XS(1)+XSDC(2)*XS(2)+XSDC(3)*XS(3)
RCDC(2)= XSDC(2)*XS(3)-XSDC(3)*XS(2)
RCDC(3)= XSDC(1)*CTM(1)
370 SP(1)= CTM(6)*XS(2)/CELC
SP(2)= CTM(6)*XS(3)/CELC
SP(3)= XSD(1)-CTM(6)*V0(8)
SP(4)= CTM(1)*V0(8)
RCDC(1)=(RCDC(1)+XSC(1)*XSD(1)+XSC(2)*XSD(2)+XSC(3)*XSD(3)
X -RCC(1)*CTM(4))/CTM(1)
RCDC(2)=(RCDC(2)+XSC(2)*V0(11)+XSC(3)*V0(12))/V0(9)
RCDC(3)=(RCDC(3)-RCDC(1)*XS(1)-XSC(1)*CTM(4)-XSC(2)*SP(1)
X -XSC(3)*SP(2)+RCC(1)*SP(3))/SP(4)
GG(1)= GG(1) + C(N+7)*RCDC(1)
GG(2)= GG(2) + C(N+8)*RCDC(2)
GG(3)= GG(3) + C(N+9)*RCDC(3)
GO TO 60
375 IF(MTYP.EQ.9) GO TO 400
DO 390 I=1,3
DO 385 J=1,NSTC
385 G(I,J+10) = 0.
DO 390 J=1,NPV
390 H(I,J) = 0.
RETURN
400 IF(JJ.LE.35) GO TO 405
IF(JJ.GT.72) GO TO 60
IF(JJ.GE.70) GO TO 435
IF(JJ.GT.60) GO TO 440
405 NNN = JJ
CALL PAXPC
IF(JJ.GE.45) GO TO 415
407 DO 410 I=1,3
410 GG(I) = CI(1,1)*V0(1) + CI(I,2)*V0(2) + CI(I,3)*V0(3)
C OBSV4770 THRU OBSV4880 HAVE BEEN DELETED
GO TO 60
415 DO 420 I=1,3
420 V0(I) = DTRAN(I,1)*SP(4)+DTRAN(I,2)*SP(5)+DTRAN(I,3)*SP(6)
GO TO 407
435 GG(1) =-CI(1,JJ-69)
GG(2) =-CI(2,JJ-69)
GG(3) =-CI(3,JJ-69)
GO TO 60
440 I = (JJ-58)/3
J = JJ - 3*I - 57
SP(4) = CI(J,1)*(C(70)-AP(1)) + CI(J,2)*(C(71)-AP(2))
+ CI(J,3)*(C(72)-AP(3))
GG(1) = CI(1,I)*SP(4)
GG(2) = CI(2,I)*SP(4)
GG(3) = CI(3,I)*SP(4)
GO TO 60
80 DO 82 I=1,3
SP(I)=SYG(I,MTYP)

```

OBSV4360
OBSV4370
OBSV4380
OBSV4390
OBSV4400
OBSV4410
OBSV4420
OBSV4430
OBSV4440
OBSV4450
OBSV4460
OBSV4470
OBSV4480
OBSV4490
OBSV4500
OBSV4510
OBSV4520
OBSV4530
OBSV4540
OBSV4550
OBSV4560
OBSV4570
OBSV4580
OBSV4590
OBSV4600
OBSV4610
OBSV4620
OBSV4630
OBSV4640
OBSV4650
OBSV4660
OBSV4670
OBSV4680
OBSV4690
OBSV4700
OBSV4710
OBSV4720
OBSV4730
OBSV4740
OBSV4750
OBSV4760
OBSV4770
OBSV4890
OBSV4900
OBSV4910
OBSV4920
OBSV4930
OBSV4940
OBSV4950
OBSV4960
OBSV4970
OBSV4980
OBSV4990
OBSV5000
OBSV5010
OBSV5020
OBSV5030
OBSV5040
OBSV5050
OBSV5060

IF(NPC(1).NE.2) SP(I)=SP(I)+SIG(I,K6)
82 CONTINUE
99 CONTINUE
RETURN
END

OBSV5070
OBSV5080
OBSV5090
OBSV5100
OBSV5110

```

SUBROUTINE OUTPUT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DAOX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PR,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TMO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XO,XGSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHOT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
2 CALL AUXIL
4 ZO(1) = VA(2)
ZO(2) = SQRT(VA(1)**2+VA(2)**2)
VO(1) = VA(4)
IF(VO(1).EQ.0.) VO(1)=.00001
ST(1)=-X(3)/VO(1)
CT(1)= ZO(2)/VO(1)
VO(2)=ATAN2(ST(1),CT(1))/CONRD
IF(ZO(2).EQ.0.) ZO(2)=.00001
ST(2)= ZO(1)/ZO(2)
CT(2)= VA(1)/ZO(2)
VO(3)=ATAN2(ST(2),CT(2))/CONRD
RO=REO/SQRT(1.-(1.-RERP2)*SPH**2)
VO(4)= X(4)+RO-RO
VO(5)=ATAN2(RERP2*SPH,CPH)/CONRD

```

```

VO(6)= X(6)/CONRD
SP(1)=SQRT(X(1)**2+X(2)**2)
VO(7)= SQRT(SP(1)**2+X(3)**2)
IF(SP(1).EQ.0.) SP(1)=.00001
VO(8)=ATAN2(-X(3),SP(1))/CONRD
VO(9)=ATAN2(X(2),X(1))/CONRD
VO(10)=ATAN2(A(1,2),A(1,1))/CONRD
SP(1) =SQRT(1.-A(1,3)**2)
VO(11)=-ATAN2(A(1,3),SP(1))/CONRD
VO(12)=ATAN2(A(2,3),A(3,3))/CONRD
VO(13) = VB(1)
VO(14) = VB(2)
VO(15) = VB(3)
ZO(3) = VB(4)
ST(4) = VB(2)/VA(4)
CT(4) = VB(4)/VA(4)
VO(17)=ATAN2(ST(4),CT(4))/CONRD
ST(5) = VB(3)/VB(4)
CT(5) = VB(1)/VB(4)
VO(18)=ATAN2(ST(5),CT(5))/CONRD
ZO(4)=A(2,3)+ST(4)*ST(1)
ZO(5)=(A(2,2)*CT(2)-A(2,1)*ST(2))*CT(1)
ZO(9)=SQRT(ZO(4)**2+ZO(5)**2)
IF(ZO(9).EQ.0.) ZO(9)=.000001
ST(3)=ZO(4)/ZO(9)
CT(3)=ZO(5)/ZO(9)
VO(16)=ATAN2(ST(3),CT(3))/CONRD
SP(1)=SQRT(VO(14)**2+VO(15)**2)
SP(3)=ATAN2(SP(1),VO(11))/CONRD
SP(2)=ATAN2(VO(14),VO(15))/CONRD
VO(19)=X(5)/CONRD
WRITE(OUT,1001)
1001 FORMAT(//)
WRITE(OUT,1000) TO
WRITE(OUT,1002) (VO(I),I=1,6)
WRITE(OUT,1004) X(1),X(2),X(3),VO(10),VO(11),VO(12)
WRITE(OUT,1006) (VO(I),I=13,18)
WRITE(OUT,1008) (XP(I),I=1,3),(SP(I),I=1,3)
WRITE(OUT,1010) (PA(I),I=1,3),(AB(I),I=1,3)
WRITE(OUT,1012) (PM(I),I=1,3),(CF(I),I=1,3)
WRITE(OUT,1011) XG,XM,ROE,(CA(I),I=1,3)
WRITE(OUT,1014) (X(I),I=7,10),VO(19),XRE
WRITE(OUT,1015) UW,VW
1000 FORMAT(5H TIME,E15.8)
1002 FORMAT(5H V(R),E15.8,5H G(R)E15.8,5H L(R)E15.8,5H ALT E15.8,5H LATOUTP0600
1 E15.8,5H LON E15.8)
1004 FORMAT(5H U(1),E15.8,5H V(1)E15.8,5H W(1)E15.8,5H PSI E15.8,5H THEOUTP0620
2 E15.8,5H PHI E15.8)
1006 FORMAT(5H U(B),E15.8,5H V(B)E15.8,5H W(B)E15.8,5H SIG E15.8,5H BETOUTP0640
3 E15.8,5H ALF E15.8)
1008 FORMAT(5H XP ,E15.8,5H YP E15.8,5H ZP E15.8,5H V(T)E15.8,5H XZIOUTP0660
4 E15.8,5H ETA E15.8)
1010 FORMAT(5H P ,E15.8,5H Q E15.8,5H R E15.8,5H AX E15.8,5H AY OUTP0680
5 E15.8,5H AZ E15.8)
1011 FORMAT(5H DP ,E15.8,5H M ,E15.8,5H RHO ,E15.8,5H C1 ,E15.8,5H OUTP0700
1C2 ,E15.8,5H C3 ,E15.8)
1012 FORMAT(5H PM ,E15.8,5H QM E15.8,5H RM E15.8,5H CX E15.8,5H CY OUTP0720
6 E15.8,5H CZ E15.8)
1014 FORMAT(5H EO ,E15.8,5H E1 E15.8,5H E2 E15.8,5H E3 E15.8,5H LATOUTP0740
7CE15.8,5H RE E15.8)

```

1015	FORMAT(5H UW ,E15.8,5H VW E15.8)	OUTP0760
	IF(NPC(1)-1) 20,99,28	OUTP0770
20	IF(DCOMP) 28,22,22	OUTP0780
22	IF(NSTC) 28,28,24	OUTP0790
24	DO 26 I=1,NSTC	OUTP0800
	K=NC(I)	OUTP0810
26	AG(I) = C(K)	OUTP0820
	WRITE(OUT,1016) (NC(I),AG(I),I=1,NSTC)	OUTP0830
1016	FORMAT(6(2H C,I3,E15.8))	OUTP0840
28	IF(NPC(3)-1) 30,100,100	OUTP0850
100	DO 102 I=1,6	OUTP0860
	DO 102 K=1,10	OUTP0870
102	DUB(K,I)=0.	OUTP0880
	ZO(6) = VA(5)	OUTP0890
	ZO(7)=ZO(6)*ZO(2)	OUTP0900
	ZO(8) =-DWDH(2)+OMEGA*CPH	OUTP0910
	DUB(1,1) = VA(1)/VA(4)	OUTP0920
	DUB(2,1) = VA(2)/VA(4)	OUTP0930
	DUB(3,1)= X(3)/VO(1)	OUTP0940
	DUB(4,1) = DUB(1,1)*DWDH(1) - DUB(2,1)*ZO(8)	OUTP0950
	DUB(5,1) =-(DUB(1,1)*DWDH(1)+DUB(2,1)*DWDH(2))*DRDP+DUB(2,1)*R*	OUTP0960
1	OMEGA*SPH	OUTP0970
	SP(1)= X(3)/(VO(1)*ZO(2))	OUTP0980
	DUB(1,2)= SP(1)*DUB(1,1)	OUTP0990
	DUB(2,2)= SP(1)*DUB(2,1)	OUTP1000
	DUB(3,2)=-ZO(2)/ZO(6)	OUTP1010
	DUB(4,2)= SP(1)*DUB(4,1)	OUTP1020
	DUB(5,2)= SP(1)*DUB(5,1)	OUTP1030
	SP(1)=ZO(2)**2	OUTP1040
	SP(2) = VA(2)*DWDH(1) - VA(1)*DWDH(2)	OUTP1050
	DUB(1,3) = -VA(2)/SP(1)	OUTP1060
	DUB(2,3) = VA(1)/SP(1)	OUTP1070
	DUB(4,3) = -(SP(2)+VA(1)*OMEGA*CPH)/SP(1)	OUTP1080
	DUB(5,3) = (SP(2)*DRDH+VA(1)*R*OMEGA*SPH)/SP(1)	OUTP1090
	IF(NPC(3)-1) 120,110,120	OUTP1100
110	SP(1)= 2./(A(1,1)**2+A(1,2)**2)	OUTP1110
	DUB(7,4)=SP(1)*(X(10)*A(1,1)-X(7)*A(1,2))	OUTP1120
	DUB(8,4)=SP(1)*(X(9)*A(1,1)-X(8)*A(1,2))	OUTP1130
	DUB(9,4)=SP(1)*(X(8)*A(1,1)+X(9)*A(1,2))	OUTP1140
	DUB(10,4)=SP(1)*(X(7)*A(1,1)+X(10)*A(1,2))	OUTP1150
	SP(1)= 2./SQRT(1.-A(1,3)**2)	OUTP1160
	DUB(7,5)= X(9)*SP(1)	OUTP1170
	DUB(8,5)=-X(10)*SP(1)	OUTP1180
	DUB(9,5)= X(7)*SP(1)	OUTP1190
	DUB(10,5)=-X(8)*SP(1)	OUTP1200
	SP(1)= 2./(A(3,3)**2+A(2,3)**2)	OUTP1210
	DUB(7,6)=SP(1)*(X(8)*A(3,3)-X(7)*A(2,3))	OUTP1220
	DUB(8,6)=SP(1)*(X(7)*A(3,3)+X(8)*A(2,3))	OUTP1230
	DUB(9,6)=SP(1)*(X(10)*A(3,3)+X(9)*A(2,3))	OUTP1240
	DUB(10,6)=SP(1)*(X(9)*A(3,3)-X(10)*A(2,3))	OUTP1250
	GO TO 200	OUTP1260
120	SP(1)= X(1)*X(7) + ZO(1)*X(10) - X(3)*X(9)	OUTP1270
	SP(2)= X(1)*X(8) + ZO(1)*X(9) + X(3)*X(10)	OUTP1280
	SP(3)= X(1)*X(9) - ZO(1)*X(8) + X(3)*X(7)	OUTP1290
	SP(4)= X(1)*X(10) - ZO(1)*X(7) - X(3)*X(8)	OUTP1300
	SP(5)= ST(4)/(CT(4)*VO(1))	OUTP1310
	SP(6)= 2./VO(1)	OUTP1320
	DUB(1,5)= (CT(4)*A(2,1)-SP(5)*(X(1) -A(2,1)*VO(14)))/VO(1)	OUTP1330
	DUB(2,5)= (CT(4)*A(2,2)-SP(5)*(ZO(1)-A(2,2)*VO(14)))/VO(1)	OUTP1340
	DUB(3,5)= (CT(4)*A(2,3)-SP(5)*(X(3) -A(2,3)*VO(14)))/VO(1)	OUTP1350

```

DUB(4,5)=-Z0(8)*DUB(2,5)                                OUTP1360
DUB(5,5)=-DUB(4,5)*R*TPH                                  OUTP1370
DUB(7,5)=(-CT(4)*SP(4)-SP(5)*(V0(13)*SP(1)+V0(15)*SP(3)))*SP(6) OUTP1380
DUB(8,5)=(CT(4)*SP(3)-SP(5)*(V0(13)*SP(2)+V0(15)*SP(4)))*SP(6) OUTP1390
DUB(9,5)=(CT(4)*SP(2)+SP(5)*(V0(13)*SP(3)-V0(15)*SP(1)))*SP(6) OUTP1400
DUB(10,5)=(-CT(4)*SP(1)+SP(5)*(V0(13)*SP(4)-V0(15)*SP(2)))*SP(6) OUTP1410
SP(6)=Z0(3)**2                                             OUTP1420
DUB(1,6)=(V0(13)*A(3,1)-V0(15)*A(1,1))/SP(6)             OUTP1430
DUB(2,6)=(V0(13)*A(3,2)-V0(15)*A(1,2))/SP(6)             OUTP1440
DUB(3,6)=(V0(13)*A(3,3)-V0(15)*A(1,3))/SP(6)             OUTP1450
DUB(4,6)=-Z0(8)*DUB(2,6)                                  OUTP1460
DUB(5,6)=-DUB(4,6)*R*TPH                                  OUTP1470
SP(6)=2./SP(6)                                             OUTP1480
DUB(7,6)=(V0(13)*SP(3)-V0(15)*SP(1))*SP(6)               OUTP1490
DUB(8,6)=(V0(13)*SP(4)-V0(15)*SP(2))*SP(6)               OUTP1500
DUB(9,6)=(V0(13)*SP(1)+V0(15)*SP(3))*SP(6)               OUTP1510
DUB(10,6)=(V0(13)*SP(2)+V0(15)*SP(4))*SP(6)              OUTP1520
SP(1)=CT(3)*ST(4)*CT(1)+ST(3)*ST(1)*Z0(5)/CT(1)         OUTP1530
SP(2)=ST(3)*CT(1)*(A(2,2)*ST(2)+A(2,1)*CT(2))            OUTP1540
SP(3)=CT(3)*CT(4)*ST(1)                                    OUTP1550
DUB(1,4)=(SP(1)*DUB(1,2)+SP(2)*DUB(1,3)+SP(3)*DUB(1,5))/Z0(9) OUTP1560
DUB(2,4)=(SP(1)*DUB(2,2)+SP(2)*DUB(2,3)+SP(3)*DUB(2,5))/Z0(9) OUTP1570
DUB(3,4)=(SP(1)*DUB(3,2)+SP(2)*DUB(3,3)+SP(3)*DUB(3,5))/Z0(9) OUTP1580
DUB(4,4)=(SP(1)*DUB(4,2)+SP(2)*DUB(4,3)+SP(3)*DUB(4,5))/Z0(9) OUTP1590
DUB(5,4)=(SP(1)*DUB(5,2)+SP(2)*DUB(5,3)+SP(3)*DUB(5,5))/Z0(9) OUTP1600
SP(6)=ST(3)*CT(1)                                          OUTP1610
SP(5)=SP(6)*CT(2)                                          OUTP1620
SP(6)=SP(6)*ST(2)                                          OUTP1630
DUB(7,4)=(SP(3)*DUB(7,5)+2.*(CT(3)*X(8)-SP(5)*X(7)-SP(6)*X(10) OUTP1640
X))/Z0(9)                                                    OUTP1650
DUB(8,4)=(SP(3)*DUB(8,5)+2.*(CT(3)*X(7)+SP(5)*X(8)+SP(6)*X(9) OUTP1660
X))/Z0(9)                                                    OUTP1670
DUB(9,4)=(SP(3)*DUB(9,5)+2.*(CT(3)*X(10)-SP(5)*X(9)+SP(6)*X(8) OUTP1680
X))/Z0(9)                                                    OUTP1690
DUB(10,4)=(SP(3)*DUB(10,5)+2.*(CT(3)*X(9)+SP(5)*X(10)-SP(6)*X(7) OUTP1700
X))/Z0(9)                                                    OUTP1710
200 DO 205 I=1,3                                           OUTP1720
DO 205 J=1,NSTX                                             OUTP1730
DUB(J,I+6)=0.                                              OUTP1740
DUB(J,I+9)=P(I+3,J)                                       OUTP1750
DUB(J,I+12)=0.                                            OUTP1760
DO 202 K=1,5                                              OUTP1770
DUM=P(K,J)                                                 OUTP1780
IF(K-J) 202,202,201                                       OUTP1790
201 DUM=P(J,K)                                             OUTP1800
202 DUB(J,I+6)=DUB(J,I+6)+DUB(K,I)*DUM                   OUTP1810
DO 204 K=1,10                                             OUTP1820
DUM=P(K,J)                                                 OUTP1830
IF(K-J) 204,204,203                                       OUTP1840
203 DUM=P(J,K)                                             OUTP1850
204 DUB(J,I+12)=DUB(J,I+12)+DUB(K,I+3)*DUM              OUTP1860
205 CONTINUE                                              OUTP1870
DO 218 I=1,3                                              OUTP1880
DO 208 J=1,3                                              OUTP1890
P(J+1,I)=0.                                               OUTP1900
P(J+7,I)=0.                                               OUTP1910
DO 206 K=1,5                                              OUTP1920
P(J+1,I)=P(J+1,I)+DUB(K,I+6)*DUB(K,J)                   OUTP1930
DO 207 K=1,10                                             OUTP1940
207 P(J+7,I)=P(J+7,I)+DUB(K,I+6)*DUB(K,J+3)             OUTP1950

```

208 CONTINUE	OUTP1960
DO 212 J=1,3	OUTP1970
P(J+7,I+6)=0.	OUTP1980
P(J+4,I+3)=P(I+3,J+3)	OUTP1990
DO 212 K=1,10	OUTP2000
212 P(J+7,I+6)=P(J+7,I+6)+DUB(K,I+12)*DUB(K,J+3)	OUTP2010
DO 214 J=1,3	OUTP2020
P(J+4,I)= DUB(J+3,I+6)	OUTP2030
214 P(J+7,I+3)= DUB(I+3,J+12)	OUTP2040
DO 216 J=1,NSTC	OUTP2050
P(J+10,I)= DUB(J+10,I+7)	OUTP2060
P(J+10,I+6)= DUB(J+10,I+12)	OUTP2070
216 P(J+10,I+3)= P(I+3,J+10)	OUTP2080
218 CONTINUE	OUTP2090
DO 210 J=1,NSTC	OUTP2100
210 P(J+10,I+9)= P(I+10,J+10)	OUTP2110
LT=1	OUTP2120
MT=NSTX-1	OUTP2130
NT=9	OUTP2140
GO TO 34	OUTP2150
30 LT=0	OUTP2160
MT=NSTX	OUTP2170
NT=10	OUTP2180
DO 32 I=1,NSTX	OUTP2190
K=I+1	OUTP2200
DO 32 J=K,NSTX	OUTP2210
32 P(J,I)=P(I,J)	OUTP2220
34 IF(NPC(1)) 35,130,35	OUTP2230
130 IF(NPC(4)-1) 35,132,35	OUTP2240
132 IF(NPC(3)) 134,134,138	OUTP2250
134 DO 136 I=1,10	OUTP2260
136 VO(I)= DZ(I)	OUTP2270
GO TO 146	OUTP2280
138 DO 144 I=1,3	OUTP2290
VO(I)=0.	OUTP2300
VO(I+6)=0.	OUTP2310
DO 140 J=1,5	OUTP2320
140 VO(I)=VO(I)+ DUB(J,I)*DZ(J)	OUTP2330
VO(I+3)= DZ(I+3)	OUTP2340
DO 142 J=1,10	OUTP2350
142 VO(I+6)=VO(I+6)+ DUB(J,I+3)*DZ(J)	OUTP2360
144 CONTINUE	OUTP2370
146 IF(NSTC) 148,147,148	OUTP2380
147 WRITE(OUT,1028) (I,VO(I),I=1,NT)	OUTP2390
GO TO 35	OUTP2400
148 DO 150 I=1,NSTC	OUTP2410
150 VO(I+NT)= DZ(I+10)	OUTP2420
WRITE(OUT,1028) (I,VO(I),I=1,NT),(NC(I),VO(I+NT),I=1,NSTC)	OUTP2430
1028 FORMAT(6(3H Z(I3,1H)E13.6))	OUTP2440
35 DO 40 I=1,MT	OUTP2450
K=I+LT	OUTP2460
IF(P(K,I)) 36,38,38	OUTP2470
36 WRITE(OUT,1030) I,I,I,P(K,I)	OUTP2480
1030 FORMAT(26H ****NEGATIVE VARIANCE ON I3,31HRD TRANSFORMED VARIABLE,	OUTP2490
A SIGMA(I3,1H,I3,4H) = E15.8)	OUTP2500
GO TO 40	OUTP2510
38 VO(I)=SQRT(P(K,I))	OUTP2520
40 CONTINUE	OUTP2530
IF(NSTC.GT.0) GO TO 50	OUTP2540
WRITE(OUT,1032) (I,VO(I),I=1,NT)	OUTP2550

GO TO 52	OUTP2560
50 DO 39 I=1,NSTC	OUTP2570
K=I+NT	OUTP2580
39 ZO(I)=VO(K)	OUTP2590
WRITE(OUT,1032) (I,VO(I),I=1,NT),(NC(I),ZO(I) ,I=1,NSTC)	OUTP2600
1032 FORMAT(6(3H S(I3,1H)E13.6))	OUTP2610
52 IF(NPC(7).NE.ICOUNT) RETURN	OUTP2620
IF(NPC(6)-1) 99,41,42	OUTP2630
41 IF(DCOMP.GT.0) RETURN	OUTP2640
42 WRITE(OUT,1033)	OUTP2650
1033 FORMAT(41H COVARIANCE MATRIX P (UPPER TRIANGLE ONLY)	OUTP2660
DO 43 I=1,MT	OUTP2670
43 WRITE(OUT,1034) (P(I+LT,J),J=1,I)	OUTP2680
1034 FORMAT(X,12E10.3)	OUTP2690
IF(NPU) 44,44,250	OUTP2700
44 IF(NPV) 46,46,300	OUTP2710
46 CONTINUE	OUTP2720
99 RETURN	OUTP2730
250 IF(LT) 256,252,256	OUTP2740
252 DO 254 I=1,NSTX	OUTP2750
DO 254 J=1,NPU	OUTP2760
254 DUB(I,J+6)=CUZ(I,J)	OUTP2770
GO TO 266	OUTP2780
256 DO 262 I=1,3	OUTP2790
DO 262 J=1,NPU	OUTP2800
DUB(I,J+6)=0.	OUTP2810
DUB(I+6,J+6)=0.	OUTP2820
DO 258 K=1,5	OUTP2830
258 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CUZ(K,J)	OUTP2840
DO 260 K=1,10	OUTP2850
260 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CUZ(K,J)	OUTP2860
262 DUB(I+3,J+6)=CUZ(I+3,J)	OUTP2870
DO 264 I=1,NSTC	OUTP2880
DO 264 J=1,NPU	OUTP2890
264 DUB(I+9,J+6)=CUZ(I+10,J)	OUTP2900
266 WRITE(OUT,1035)	OUTP2910
1035 FORMAT(34H CORRELATION MATRIX (CUZ)TRANSP0SE)	OUTP2920
MT=NSTX-LT	OUTP2930
DO 268 J=1,NPU	OUTP2940
268 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP2950
GO TO 44	OUTP2960
300 IF(LT) 306,302,306	OUTP2970
302 DO 304 I=1,NSTX	OUTP2980
DO 304 J=1,NPV	OUTP2990
304 DUB(I,J+6)=CVZ(I,J)	OUTP3000
GO TO 316	OUTP3010
306 DO 312 I=1,3	OUTP3020
DO 312 J=1,NPV	OUTP3030
DUB(I,J+6)=0.	OUTP3040
DUB(I+6,J+6)=0.	OUTP3050
DO 308 K=1,5	OUTP3060
308 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CVZ(K,J)	OUTP3070
DO 310 K=1,10	OUTP3080
310 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CVZ(K,J)	OUTP3090
312 DUB(I+3,J+6)=CVZ(I+3,J)	OUTP3100
DO 314 I=1,NSTC	OUTP3110
DO 314 J=1,NPV	OUTP3120
314 DUB(I+9,J+6)=CVZ(I+10,J)	OUTP3130
316 WRITE(OUT,1036)	OUTP3140
1036 FORMAT(34H CORRELATION MATRIX (CVZ)TRANSP0SE)	OUTP3150

```
MT=NSTX-LT
DO 318 J=1,NPV
318 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)
GO TO 46
END
```

```
OUTP3160
OUTP3170
OUTP3180
OUTP3190
OUTP3200
```

```

SUBROUTINE PRESET
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A NB(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
NDIMT = 160
NDIMZ = 30
NDIMV = 5
NDIMU = 5
DO 12 I=1,NDIMZ
DO 4 J=1,NDIMZ
4 P(I,J)=0.
DO 6 J=1,NDIMU
6 CUZ(I,J) = 0.
DO 8 J=1,NDIMV
8 CVZ(I,J) = 0.
DO 10 J=1,10
10 PH(J,I)=0.
12 DZ(I) = 0.
DO 16 I=1,NDIMU

```

```

16 D(I)=0.
   DO 18 I=1,NDIMV
18 S(I)=0.
   DO 26 I=1,NDIMT
26 C(I) = 0.
   C(21) = 1.
   C(36) = 1.
   C(40) = 1.
   C(44) = 1.
   C(61) = 1.
   C(65) = 1.
   C(69) = 1.
   C(76) = 1.
   C(77) = 1.
   C(78) = 1.
   C(91) = 1.
   C(92) = 1.
   C(93) = 1.
   C(106) = 1.
   C(107) = 1.
   C(108) = 1.
   C(121) = 1.
   C(122) = 1.
   C(123) = 1.
   C(136) = 1.
   C(137) = 1.
   C(138) = 1.
CONRD = .0174532925
XJ2 = 1.082645E-3
XMU = 3.985992E+14
OMEGA = .7292116E-4
RPO = 6356173.
REO = 6378163.
NCOUNT = 0
ICOUNT = 1
KDATAS = -1
NST = 0
NSTX = 0
NSTC = 0
NSTA = 0
NPU = 0
NPV = 0
FIT = 1
PQR = 2
SCRACH = 3
STATE = 4
IN = 5
OUT = 6
ISV = 1
N4(1) = 0
N4(2) = 1
N4(3) = 0
N5(1) = 0
N5(2) = 1
N5(3) = 0
N6(1) = 0
N6(2) = 1
N6(3) = 0
N8(1) = 0
N8(2) = 1

```

```

PRES0160
PRES0170
PRES0180
PRES0190
PRES0200
PRES0210
PRES0220
PRES0230
PRES0240
PRES0250
PRES0260
PRES0270
PRES0280
PRES0290
PRES0300
PRES0310
PRES0320
PRES0330
PRES0340
PRES0350
PRES0360
PRES0370
PRES0380
PRES0390
PRES0400
PRES0410
PRES0420
PRES0430
PRES0440
PRES0450
PRES0460
PRES0470
PRES0480
PRES0490
PRES0500
PRES0510
PRES0520
PRES0530
PRES0540
PRES0550
PRES0560
PRES0570
PRES0580
PRES0590
PRES0600
PRES0610
PRES0620
PRES0630
PRES0640
PRES0650
PRES0660
PRES0670
PRES0680
PRES0690
PRES0700
PRES0710
PRES0720
PRES0730
PRES0740
PRES0750

```

```

N8(3) = 0
N9(1) = 0
N9(2) = 1
N9(3) = 0
N10(1) = 0
N10(2) = 1
N10(3) = 0
N11(1) = 0
N11(2) = 1
N11(3) = 0
DO 200 I=1,9
  DFIT(I) = 1.E10
  DTI(I) = 1.E10
200 NTR(I) = 0
  TIME = 1.E+10
  KG = 2
  AMO = 28.9644
  APO = 1.013250E5
  AR = 8.31432E3
  AGAM = 1.4
  ABET = 1.458E-6
  ASU= 110.4
  GO=9.80665
  CALL INDAT
  CALL SETUP
99 RETURN
END

```

```

PRES0760
PRES0770
PRES0780
PRES0790
PRES0800
PRES0810
PRES0820
PRES0830
PRES0840
PRES0850
PRES0860
PRES0870
PRES0880
PRES0890
PRES0900
PRES0910
PRES0920
PRES0930
PRES0940
PRES0950
PRES0960
PRES0970
PRES0980
PRES0990
PRES1000
PRES1010
PRES1020

```

```

SUBROUTINE PROP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,H0,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
C-----CALCULATE EQ.(55B)-----
DO 4 I=1,10
DO 4 J=1,NSTX
SUM = 0.
L = J+1
DO 2 K=1,J
2 SUM = SUM + PH(I,K)*P(K,J)
IF(L.GT.NSTX) GO TO 4
DO 3 K=L,NSTX
3 SUM = SUM + PH(I,K)*P(J,K)
4 DUB(J,I) = SUM
DO 10 I=1,10
DO 8 J=1,10
SUM = 0.
DO 6 K=1,NSTX

```

6 SUM = SUM + DUB(K,I)*PH(J,K)	PROP0160
8 P(I,J) = SUM	PROP0170
10 CONTINUE	PROP0180
IF(NSTX=10) 12,16,12	PROP0190
12 DO 14 I=11,NSTX	PROP0200
DO 14 J=1,10	PROP0210
14 P(J,I) = DUB(I,J)	PROP0220
IF(NPU) 38,38,60	PROP0230
60 DO 64 I=1,10	PROP0240
DO 64 K=11,NSTX	PROP0250
SUM = 0.	PROP0260
DO 62 J=1,NPU	PROP0270
II=J+NSTX	PROP0280
62 SUM = SUM + PH(I,II)*CUZ(K,J)	PROP0290
64 P(I,K) = P(I,K) + SUM	PROP0300
GO TO 20	PROP0310
16 IF(NPU,LE,0) GO TO 38	PROP0320
C-----CALCULATE EQ.(55C) -----	PROP0330
20 DO 25 J=1,NPU	PROP0340
DO 24 I=1,10	PROP0350
SUM = 0.	PROP0360
DO 22 K=1,NSTX	PROP0370
SUM = SUM + PH(I,K)*CUZ(K,J)	PROP0380
22 CONTINUE	PROP0390
DUB(I,J) = SUM	PROP0400
24 DUB(I,15) = SUM + PH(I,J+NSTX)*D(J)	PROP0410
DO 25 I=1,10	PROP0420
25 CUZ(I,J) = DUB(I,15)	PROP0430
26 CONTINUE	PROP0440
30 DO 34 I=1,10	PROP0450
DO 34 J=1,10	PROP0460
SUM = 0.	PROP0470
DO 32 K=1,NPU	PROP0480
32 SUM = SUM + CUZ(I,K)*PH(J,K+NSTX) + PH(I,K+NSTX)*DUB(J,K)	PROP0490
34 P(I,J) = P(I,J) + SUM	PROP0500
36 CONTINUE	PROP0510
38 IF(NPV) 99,99,40	PROP0520
C-----CALCULATE EQ.(55D) -----	PROP0530
40 DO 48 J=1,NPV	PROP0540
DO 44 I=1,10	PROP0550
SUM = 0.	PROP0560
DO 42 K=1,NSTX	PROP0570
SUM = SUM + PH(I,K)*CVZ(K,J)	PROP0580
44 DUB(I,1) = SUM	PROP0590
DO 46 I=1,10	PROP0600
46 CVZ(I,J) = DUB(I,1)	PROP0610
48 CONTINUE	PROP0620
99 IF(NPC(4).EQ.0) GO TO 75	PROP0630
IF(NPC(1).EQ.2) GO TO 75	PROP0640
C-----CALCULATE EQ.(55A) -----	PROP0650
DO 72 I=1,10	PROP0660
SUM = 0.	PROP0670
DO 70 J=1,NSTX	PROP0680
70 SUM = SUM + PH(I,J)*DZ(J)	PROP0690
72 DUB(I,1) = SUM	PROP0700
DO 74 I=1,10	PROP0710
74 DZ(I) = DUB(I,1)	PROP0720
75 CONTINUE	PROP0730
ENTRY IDENT	PROP0740
K = NSTX+NPU	PROP0750

```
DO 52 I=1,10
DO 50 J=1,K
50 PH(I,J)=0.
52 PH(I,I)=1.
RETURN
END
```

```
PROP0760
PROP0770
PROP0780
PROP0790
PROP0800
PROP0810
```



```

SUBROUTINE RKUTTA
  DIMENSION PR(3)
  DIMENSION F1(410),F2(410),F3(410),DELY(410)
  COMMON /INTGRL/ P,T,TP,Y(410),DY(410),N,L
  DATA PR /,5, .25, .5/
  GO TO (1,2,2,4),L
1 IF(IG.EQ.0) GO TO 30
  DO 10 I = 1,N
    F3(I)=Y(I)
10  L = 2
    RETURN
2 DT = P
  J = 1
  T2 = TP - T
  RT2=T2/P
  IF(RT2-.99999)22,26,29
22 IF(RT2.GT..00001) GO TO 26
20  L=3
    RETURN
26  DT=T2
29  IG=0
30  GO TO(31,32,33,34),J
31  T = T+PR(1)*DT
    DO 310 I=1,N
      F1(I)=DY(I)*DT
310  Y(I)=F3(I)+PR(1)*F1(I)
      J = J+1
      GO TO 38
33  T = T+PR(1)*DT
32  T2=DT/PR(1)
    DO 320 I=1,N
      RT2=DY(I)*T2
      F1(I)=F1(I)+RT2
320  Y(I)=F3(I)+PR(J)*RT2
35  J = J + 1
    RETURN
34  DO 340 I=1,N
340  F1(I)=F1(I)+DY(I)*DT
37 DO 39 I = 1,N
  DELY(I)=F1(I)/6.+DELY(I)
39  Y(I)=F2(I)+DELY(I)
  IG = 1
  RETURN
4 DT=P
  IG = 1
  J = 1
  DO 40 I = 1,N
    DELY(I) = 0.D0
40  F2(I)=Y(I)
38 L = 1
  RETURN
END

```

```

RKUT0010
RKUT0020
RKUT0030
RKUT0040
RKUT0050
RKUT0060
RKUT0070
RKUT0080
RKUT0090
RKUT0100
RKUT0110
RKUT0120
RKUT0130
RKUT0140
RKUT0150
RKUT0160
RKUT0170
RKUT0180
RKUT0190
RKUT0200
RKUT0210
RKUT0220
RKUT0230
RKUT0240
RKUT0250
RKUT0260
RKUT0270
RKUT0280
RKUT0290
RKUT0300
RKUT0310
RKUT0320
RKUT0330
RKUT0340
RKUT0350
RKUT0360
RKUT0370
RKUT0380
RKUT0390
RKUT0400
RKUT0410
RKUT0420
RKUT0430
RKUT0440
RKUT0450
RKUT0460
RKUT0470
RKUT0480
RKUT0490
RKUT0500
RKUT0510

```

```

SUBROUTINE SETUP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS ,BETA,CA(6),CALP ,CBET ,CETA ,
1 CF(3),JCS ,CXZI ,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH ,
2 DRDP,DWDH(2),ETA,H0,N4(3) ,N5(3) ,N6(3) ,PAXP(3,30),
3 PE ,ROE ,ROEC ,ROEM ,SALP ,SBET ,
4 SETA ,SREF ,SXZI ,TAU ,TMAS(20) ,TONE ,
5 TIWO ,TUV(20) ,TVW(20) ,UW ,VA(5) ,VB(5) ,
6 VW ,XIND1 ,XIND2 ,XLREF ,XM ,
7 XMAS(20) ,XNU ,XQ ,XQSM ,XRE ,XTEMP ,
8 XUW(20) ,XVW(20) ,XZI ,YMAS ,YMASM
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),TDUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS ,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYP ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHOT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPEN0/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON /ABET,AGAM,AMO,AP0,AR,ASU,ATM(4),HB(23),ISV,JK
A ,PB(23),RL(23),TMB(23)
COMMON /EXTRA / GO
DIMENSION DUA(10,10)
WRITE(OUT,1000)
1000 FORMAT(1H1,27H CONTROLS ARE SPECIFIED FOR)
IF(NPC(1)-1) 10,11,12
10 WRITE(OUT,1001) TO,TFINAL
1001 FORMAT(5X,28H*FILTERING RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
GO TO 13
11 WRITE(OUT,1002) TO,TFINAL
1002 FORMAT(5X,32H*DETERMINISTIC RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
1.4)
GO TO 24
12 WRITE(OUT,1003) TO,TFINAL
1003 FORMAT(5X,33H*ERROR ANALYSIS RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
19.4)
GO TO 21

```

```

13 IF(NPC(4))14,14,15 SETP0160
14 WRITE(OUT,1004) SETP0170
1004 FORMAT(SX,16H*UPDATED REFERENCE) SETP0180
GO TO 16 SETP0190
15 WRITE(OUT,1005) SETP0200
1005 FORMAT(SX,21H*NONUPDATED REFERENCE) SETP0210
16 IF(NPC(8)-1) 17,18,19 SETP0220
17 WRITE(OUT,1006) SETP0230
1006 FORMAT(SX,57H*SMOOTH DETERMINISTICALLY, NO RESIDUALS NOR LOSS FUNCSETP0240
XTION) SETP0250
GO TO 20 SETP0260
18 WRITE(OUT,1007) SETP0270
1007 FORMAT(SX,64H*SMOOTH DETERMINISTICALLY, CALCULATE RESIDUALS AND LOSETP0280
XSS FUNCTION) SETP0290
GO TO 20 SETP0300
19 IF(NPC(8)-3) 170,172,174 SETP0310
170 WRITE(OUT,1027) SETP0320
1027 FORMAT(SX,49H*SMOOTH COVARIANCE,NO RESIDUALS NOR LOSS FUNCTION) SETP0330
GO TO 20 SETP0340
172 WRITE(OUT,1028) SETP0350
1028 FORMAT(SX,56H*SMOOTH COVARIANCE,CALCULATE RESIDUALS AND LOSS FUNCTSETP0360
XION) SETP0370
GO TO 20 SETP0380
174 WRITE(OUT,1029) SETP0390
1029 FORMAT(SX,13H*NO SMOOTHING) SETP0400
20 WRITE(OUT,1009) NPC(7) SETP0410
1009 FORMAT(SX,12H*FILTER FOR I2,11H ITERATIONS) SETP0420
21 IF(NPC(9).EQ.0) GO TO 23 SETP0430
22 WRITE(OUT,1010) SETP0440
1010 FORMAT(SX,28H*SCALAR PROCESS FITTING DATA) SETP0450
GO TO 24 SETP0460
23 WRITE(OUT,1011) SETP0470
1011 FORMAT(SX,36H*VECTOR PROCESS FITTING DATA TRIPLES) SETP0480
24 IF(NPC(2)) 25,25,26 SETP0490
25 WRITE(OUT,1012) SETP0500
1012 FORMAT(SX,52H*INPUT AND OUTPUT IN METRIC UNITS(M,M/SEC,M/SEC2,KG))SETP0510
GO TO 27 SETP0520
26 WRITE(OUT,1013) SETP0530
1013 FORMAT(SX,62H*INPUT AND OUTPUT IN ENGLISH UNITS (FT,FT/SEC,FT/SEC2SETP0540
X,LB,SLUG)) SETP0550
27 WRITE(OUT,1014) REO,RPO,OMEGA,XMU,XJ2,GO SETP0560
1014 FORMAT(SX,18H*PLANET PARAMETERS/20X,11HEQUIT,RAD.=E15.8,13H POLARSETP0570
1 RAD.=E15.8,13H ROTATION =E15.8/20X,11HMU(GRAV.) =E15.8,13H J2(GSETP0580
2RAV. ) =E15.8,7X,6HG(0) =E15.8) SETP0590
IF(NPC(14)-1) 280,282,284 SETP0600
280 WRITE(OUT,1040) SETP0610
1040 FORMAT(SX,32H*ATMOSPHERE IS 1962 U.S.STANDARD) SETP0620
NPTS=22 SETP0630
HB( 1) = 0. SETP0640
HB( 2) = 11000. SETP0650
HB( 3) = 20000. SETP0660
HB( 4) = 32000. SETP0670
HB( 5) = 47000. SETP0680
HB( 6) = 52000. SETP0690
HB( 7) = 61000. SETP0700
HB( 8) = 79000. SETP0710
HB( 9) = 88743. SETP0720
HB(10) = 98451.235 SETP0730
HB(11) = 108128.89 SETP0740
HB(12) = 117776.67 SETP0750

```

HB(13) = 146542.06
 HB(14) = 156071.67
 HB(15) = 165572.08
 HB(16) = 184485.82
 HB(17) = 221968.74
 HB(18) = 286479.92
 HB(19) = 376320.01
 HB(20) = 463539.66
 HB(21) = 548251.81
 HB(22) = 630563.08
 TMB(1) = 288.15
 TMB(2) = 216.65
 TMB(3) = 216.65
 TMB(4) = 228.65
 TMB(5) = 270.65
 TMB(6) = 270.65
 TMB(7) = 252.65
 TMB(8) = 180.65
 TMB(9) = 180.65
 TMB(10) = 210.65
 TMB(11) = 260.65
 TMB(12) = 360.65
 TMB(13) = 960.65
 TMB(14) = 1110.65
 TMB(15) = 1210.65
 TMB(16) = 1350.65
 TMB(17) = 1550.65
 TMB(18) = 1830.65
 TMB(19) = 2160.65
 TMB(20) = 2420.65
 TMB(21) = 2590.65
 TMB(22) = 2700.65
 GO TO 286

282 WRITE(OUT,1041)
 1041 FORMAT(5X,24H*ATMOSPHERE IS 1959 ARDC)

NPTS= 12
 HB(1)= 0.
 HB(2)= 11000.
 HB(3)= 25000.
 HB(4)= 47000.
 HB(5)= 53000.
 HB(6)= 79000.
 HB(7)= 90000.
 HB(8)= 105000.
 HB(9)= 160000.
 HB(10)= 170000.
 HB(11)= 200000.
 HB(12)= 700000.
 TMB(1)= 288.16
 TMB(2)= 216.66
 TMB(3)= 216.66
 TMB(4)= 282.66
 TMB(5)= 282.66
 TMB(6)= 165.66
 TMB(7)= 165.66
 TMB(8)= 225.66
 TMB(9)= 1325.66
 TMB(10)= 1425.66
 TMB(11)= 1575.66
 TMB(12)= 3325.66

SETP0760
 SETP0770
 SETP0780
 SETP0790
 SETP0800
 SETP0810
 SETP0820
 SETP0830
 SETP0840
 SETP0850
 SETP0860
 SETP0870
 SETP0880
 SETP0890
 SETP0900
 SETP0910
 SETP0920
 SETP0930
 SETP0940
 SETP0950
 SETP0960
 SETP0970
 SETP0980
 SETP0990
 SETP1000
 SETP1010
 SETP1020
 SETP1030
 SETP1040
 SETP1050
 SETP1060
 SETP1070
 SETP1080
 SETP1090
 SETP1100
 SETP1110
 SETP1120
 SETP1130
 SETP1140
 SETP1150
 SETP1160
 SETP1170
 SETP1180
 SETP1190
 SETP1200
 SETP1210
 SETP1220
 SETP1230
 SETP1240
 SETP1250
 SETP1260
 SETP1270
 SETP1280
 SETP1290
 SETP1300
 SETP1310
 SETP1320
 SETP1330
 SETP1340
 SETP1350

```

      GO TO 286
284 WRITE(OUT,1042)
1042 FORMAT(5X,29H*ATMOSPHERE SPECIFIED BY USER)
      NPTS=K1
      GO TO 292
286 IF(NPC(2)) 288,292,288
288 AR= AR/.167225472
      APO = APO/47.880258
      ABET= ABET*.01556708573
      ASU = ASU*1.8
      DO 290 I=1,NPTS
      HB(I)=HB(I)/.3048
290 TMB(I)=TMB(I)*1.8
292 JK=3
      ATM(1)= 60*AMC/AR
      ATM(2)= AMO/AR
      ATM(3)= SQRT(AGAM*AR/AMO)
      PB(1)=APO
      ISV=1
      DO 294 K=2,NPTS
      RL(K-1)=(TMB(K)-TMB(K-1))/(HB(K)-HB(K-1))
      SP(1)= HB(K)-.0001
      CALL ATMDAT(SP(1),PE,ROE,AS,TM,VMU,H)
294 PB(K)=PE
      JK=NPC(14)
      RL(NPTS)=0
      HB(NPTS+1)=1.E15
      WRITE(OUT,1043) AMO,AR,AGAM,APO,ABET,ASU,(HB(I),I=1,NPTS)
1043 FORMAT(26X,5H MO =E15.8,13H R(STAR) =E15.8,13H CP/CV =E15.8,13H
      18/25X,6HP(0) =E15.8,7X,6HBETA =E15.8,10X,3HS =E15.8/8X,4HHB =6E18,
      28/(12X,6E18.8))
      WRITE(OUT,1044) (TMB(I),I=1,NPTS)
1044 FORMAT(7X,5HTMB =E15.8/(12X,6E18.8))
      WRITE(OUT,1046) (PB(I),I=1,NPTS)
1046 FORMAT(8X,4HPB =6E18.8/(12X,6E18.8))
      WRITE(OUT,1047)
1047 FORMAT(5X,26H*INITIAL STATE ESTIMATE IS)
      IF(NPC(3)-1) 28,29,30
      28 WRITE(OUT,1015) (ZO(I),I=1,10)
1015 FORMAT(20X,1HU,9X,1H=E15.8,3H V,9X,1H=E15.8,3H W,9X,1H=E15.8/20X,2HE0,8X,1H=E15.8,4H
      1,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/20X,2HE0,8X,1H=E15.8,4H
      20X,2HE0,8X,1H=E15.8,4H E1,8X,1H=E15.8,4H E2,8X,1H=E15.8/20X,2HE3,8X,1H=E15.8)
      GO TO 31
      29 WRITE(OUT,1016) (ZO(I),I=1,9)
1016 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA =E15.8/20X,11HALTITUDE =E15.8,13H
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/20X,11HPSI(BAR) =E15.8,13H
      2UDE =E15.8/20X,11HPSI(BAR) =E15.8,13H THETA(BAR)=E15.8,13H PHI(BAR) =E15.8)
      GO TO 31
      30 WRITE(OUT,1017) (ZO(I),I=1,9)
1017 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA =E15.8/20X,11HALTITUDE =E15.8,13H
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/20X,11HSIGMA =E15.8,13H
      2UDE =E15.8/20X,11HSIGMA =E15.8,13H BETA =E15.8,13H ALPHA =E15.8)
      3A =E15.8)
      31 RERP2=(REO/RPO)**2
      XMUJ = 3.*XMU*XJ2*REO**2
      ATM(4)= REO/SQRT(1.-(RERP2-1.)*SIN(.79486646)**2)
      IF(NPC(1)-1)32,40,32
      32 WRITE(OUT,1018) NSTA

```

1018	FORMAT(5X,22H*FITTING DATA IS FROM 12.8H SOURCES)	SETP1960
	KSS=0	SETP1970
	DO 42 I=1,NSTA	SETP1980
	IF(NS(I)-6) 33,44,45	SETP1990
33	MT=NS(I)	SETP2000
	N = 73 +15*MT	SETP2010
	WRITE(OUT,1019) I,MT,C(N),C(N+1),C(N+2)	SETP2020
1019	FORMAT(10X,I1,19H. TRACKING STATION I1,12H, GEOD.LAT.=F11.6,12H L	SETP2030
	XONGITUDE=F11.6,12H ALTITUDE =F11.4,19H ABOVE REF. SURFACE)	SETP2040
	C(N)=C(N)*CONRD	SETP2050
	C(N+1)=C(N+1)*CONRD	SETP2060
	C(N) = ATAN2(SIN(C(N)),RERP2*COS(C(N)))	SETP2070
	NT=N+2	SETP2080
	MTYP = MT	SETP2090
	CALL STAT	SETP2100
	DO 36 J=1,NSTC	SETP2110
	IF(NC(J)-N) 36,35,35	SETP2120
35	IF(NC(J)-NT)37,37,36	SETP2130
36	CONTINUE	SETP2140
	GO TO 38	SETP2150
37	KSS=KSS+1	SETP2160
	NSS(KSS) = MT	SETP2170
38	MO(MT) = 0	SETP2180
	DO 39 J=1,NSTC	SETP2190
	IF(NC(J).LT.N-6) GO TO 39	SETP2200
	IF(NC(J).LE.N-4) GO TO 40	SETP2210
39	CONTINUE	SETP2220
	IF(C(N-6).NE.0.) GO TO 40	SETP2230
	IF(C(N-5).NE.0.) GO TO 40	SETP2240
	IF(C(N-4).NE.0.) GO TO 40	SETP2250
	GO TO 42	SETP2260
44	WRITE(OUT,1020) I,C(151),C(152)	SETP2270
1020	FORMAT(10X,I1,27H. AIRBORNE RADAR, DELTA(P)=F11.6,11H DELTA(Y)=F1	SETP2280
	X1.6)	SETP2290
	GO TO 42	SETP2300
45	IF(NS(I)-8) 43,41,47	SETP2310
47	WRITE(OUT,1032) I	SETP2320
1032	FORMAT(10X,I1,20H. ACCELEROMETER DATA)	SETP2330
	GO TO 42	SETP2340
41	WRITE(OUT,1030) I	SETP2350
1030	FORMAT(I11,15H. POSITION DATA)	SETP2360
	GO TO 42	SETP2370
43	WRITE(OUT,1031) I	SETP2380
1031	FORMAT(I11,15H. VELOCITY DATA)	SETP2390
	GO TO 42	SETP2400
40	MO(MT) = 1	SETP2410
42	CONTINUE	SETP2420
46	ZO(5) = ZO(5)*CONRD	SETP2430
	ZO(6)=ZO(6)*CCNRD	SETP2440
	NSTX = NSTC + 10	SETP2450
	ZO(5) = ATAN2(SIN(ZO(5)),RERP2*COS(ZO(5)))	SETP2460
	CPH=COS(ZO(5))	SETP2470
	SPH=SIN(ZO(5))	SETP2480
	RO =REO/SQRT(1.+(RERP2-1.)*SPH**2)	SETP2490
	R= ZO(4)+RO	SETP2500
	ZO(4)=R-REO	SETP2510
	DO 48 I=1,10	SETP2520
48	X(I)=ZO(I)	SETP2530
	IF(NPC(3).EQ.0) GO TO 100	SETP2540
50	DO 51 I=7,9	SETP2550

51	ZO(I)=ZO(I)*CONRD	SETP2560
	DO 52 I=1,2	SETP2570
	ZO(I+1) = ZO(I+1)*CONRD	SETP2580
	ST(I)=SIN(ZO(I+1))	SETP2590
52	CT(I)=COS(ZO(I+1))	SETP2600
	DO 53 I=3,5	SETP2610
	ST(I)=SIN(ZO(I+4)/2.)	SETP2620
53	CT(I)=COS(ZO(I+4)/2.)	SETP2630
	X(3)=ZO(1)*CT(1)	SETP2640
	X(1)=X(3)*CT(2)	SETP2650
	X(2)=X(3)*ST(2)+R*OMEGA*CPH	SETP2660
	X(3)=-ZO(1)*ST(1)	SETP2670
	UW = TAB(ZO(4),N5(1),TUV(1),XUW(1))	SETP2680
	VW = TAB(ZO(4),N6(1),TVW(1),XVW(1))	SETP2690
	X(1) = X(1)-UW	SETP2700
	X(2) = X(2)-VW	SETP2710
	DO 54 I=1,10	SETP2720
	DO 54 J=1,9	SETP2730
54	DUB(I,J)=0.	SETP2740
	DUB(1,1)= CT(1)*CT(2)	SETP2750
	DUB(2,1)= CT(1)*ST(2)	SETP2760
	DUB(3,1)=-ST(1)	SETP2770
	SP(1)= ZO(1)*ST(1)	SETP2780
	DUB(1,2)=-SP(1)*CT(2)	SETP2790
	DUB(2,2)=-SP(1)*ST(2)	SETP2800
	SP(1)= ZO(1)*CT(1)	SETP2810
	DUB(3,2)=-SP(1)	SETP2820
	DUB(1,3)=-SP(1)*ST(2)	SETP2830
	DUB(2,3)= SP(1)*CT(2)	SETP2840
	DUB(2,4)= OMEGA*CPH	SETP2850
	DUB(2,5)=-R*OMEGA*SPH	SETP2860
	DUB(4,4)=1.	SETP2870
	DUB(5,5)=1.	SETP2880
	DUB(6,6)=1.	SETP2890
	IF(NPC(3)-1) 100, 50, 60	SETP2900
56	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP2910
	DUA(2,1)= CT(3)*CT(4)*ST(5)	SETP2920
	DUA(3,1)= CT(3)*ST(4)*CT(5)	SETP2930
	DUA(4,1)= ST(3)*CT(4)*CT(5)	SETP2940
	DUA(1,2)= ST(3)*ST(4)*CT(5)	SETP2950
	DUA(2,2)= ST(3)*ST(4)*CT(5)	SETP2960
	DUA(3,2)= ST(3)*CT(4)*ST(5)	SETP2970
	DUA(4,2)= CT(3)*ST(4)*ST(5)	SETP2980
	X(7) = DUA(1,1)+DUA(1,2)	SETP2990
	X(8) = DUA(2,1)-DUA(2,2)	SETP3000
	X(9) = DUA(3,1)+DUA(3,2)	SETP3010
	X(10)= DUA(4,1)-DUA(4,2)	SETP3020
	IF(NPC(1).EQ.1) GO TO 100	SETP3030
	DUB(7,7) = -X(10)/2.	SETP3040
	DUB(8,7) =-X(9)/2.	SETP3050
	DUB(9,7) = X(8)/2.	SETP3060
	DUB(10,7) = X(7)/2.	SETP3070
	DUB(7,8) =-(DUA(3,1) - DUA(3,2))/2.	SETP3080
	DUB(8,8) =-(DUA(4,1) + DUA(4,2))/2.	SETP3090
	DUB(9,8) = (DUA(1,1) - DUA(1,2))/2.	SETP3100
	DUB(10,8)=- (DUA(2,1) + DUA(2,2))/2.	SETP3110
	DUB(7,9) =-X(8)/2.	SETP3120
	DUB(8,9) = X(7)/2.	SETP3130
	DUB(9,9) = X(10)/2.	SETP3140
	DUB(10,9)=-X(9)/2.	SETP3150

GO TO 70	SETP3160
60 ST(1) = SIN(.5*Z0(2))	SETP3170
CT(1) = COS(.5*Z0(2))	SETP3180
ST(2) = SIN(.5*Z0(3))	SETP3190
CT(2) = COS(.5*Z0(3))	SETP3200
DUE(1)= CT(1)*CT(2)	SETP3210
DUE(2)=-ST(1)*ST(2)	SETP3220
DUE(3)= ST(1)*CT(2)	SETP3230
DUE(4)= CT(1)*ST(2)	SETP3240
DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP3250
DUA(2,1)= ST(3)*CT(4)*CT(5)	SETP3260
DUA(3,1)= CT(3)*CT(4)*ST(5)	SETP3270
DUA(4,1)= ST(3)*CT(4)*ST(5)	SETP3280
DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP3290
DUA(2,2)= CT(3)*ST(4)*ST(5)	SETP3300
DUA(3,2)= ST(3)*ST(4)*CT(5)	SETP3310
DUA(4,2)= CT(3)*ST(4)*CT(5)	SETP3320
DUF(1)= DUA(1,1)-DUA(1,2)	SETP3330
DUF(2)= DUA(2,1)+DUA(2,2)	SETP3340
DUF(3)= DUA(3,1)+DUA(3,2)	SETP3350
DUF(4)= DUA(4,1)-DUA(4,2)	SETP3360
X(7) = DUE(1)*DUF(1)-DUE(2)*DUF(2)-DUE(3)*DUF(3)-DUE(4)*DUF(4)	SETP3370
X(8) = DUE(1)*DUF(2)+DUE(2)*DUF(1)+DUE(3)*DUF(4)-DUE(4)*DUF(3)	SETP3380
X(9) = DUE(1)*DUF(3)-DUE(2)*DUF(4)+DUE(3)*DUF(1)+DUE(4)*DUF(2)	SETP3390
X(10)= DUE(1)*DUF(4)+DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(1)	SETP3400
IF(NPC(1).EQ.1) GO TO 100	SETP3410
DUB(7,2) = -X(9)/2. - DUE(2)*DUF(4) + DUE(4)*DUF(2)	SETP3420
DUB(8,2) = X(10)/2.- DUE(2)*DUF(3) - DUE(4)*DUF(1)	SETP3430
DUB(9,2) = X(7)/2. + DUE(2)*DUF(2) + DUE(4)*DUF(4)	SETP3440
DUB(10,2)= -X(8)/2. + DUE(2)*DUF(1) - DUE(4)*DUF(3)	SETP3450
DUB(7,3) = -X(10)/2.	SETP3460
DUB(8,3) = -X(9)/2.	SETP3470
DUB(9,3) = X(8)/2.	SETP3480
DUB(10,3)= X(7)/2.	SETP3490
DUB(7,7) = -X(8)/2. + DUE(3)*DUF(4) - DUE(4)*DUF(3)	SETP3500
DUB(8,7) = X(7)/2. + DUE(3)*DUF(3) + DUE(4)*DUF(4)	SETP3510
DUB(9,7) = -X(10)/2.- DUE(3)*DUF(2) + DUE(4)*DUF(1)	SETP3520
DUB(10,7)= X(9)/2. - DUE(3)*DUF(1) - DUE(4)*DUF(2)	SETP3530
DUF(1) = DUA(1,1)+DUA(1,2)	SETP3540
DUF(2) = DUA(2,1)-DUA(2,2)	SETP3550
DUF(3) = DUA(3,1)-DUA(3,2)	SETP3560
DUF(4) = DUA(4,1)+DUA(4,2)	SETP3570
DUB(7,8) = (-DUE(1)*DUF(4)-DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(SETP3580
X1))/2.	SETP3590
DUB(8,8) = (DUE(1)*DUF(3)-DUE(2)*DUF(4)-DUE(3)*DUF(1)-DUE(4)*DUF(SETP3600
X2))/2.	SETP3610
DUB(9,8) = (DUE(1)*DUF(2)+DUE(2)*DUF(1)-DUE(3)*DUF(4)+DUE(4)*DUF(SETP3620
X3))/2.	SETP3630
DUB(10,8)= (-DUE(1)*DUF(1)+DUE(2)*DUF(2)-DUE(3)*DUF(3)-DUE(4)*DUF(SETP3640
X4))/2.	SETP3650
DUB(7,9) = -X(9)/2.	SETP3660
DUB(8,9) = -X(10)/2.	SETP3670
DUB(9,9) = X(7)/2.	SETP3680
DUB(10,9)= X(8)/2.	SETP3690
70 DO 74 I=1,10	SETP3700
DO 74 J=1,NSTX	SETP3710
SUM = 0.	SETP3720
DO 72 K=1,9	SETP3730
72 SUM = SUM + DUB(I,K)*P(K,J)	SETP3740
74 PH(I,J) = SUM	SETP3750

DO 80 I=1,10	SETP3760
DO 78 J=1,10	SETP3770
SUM = 0.	SETP3780
DO 76 K=1,10	SETP3790
76 SUM = SUM + PH(I,K)*DUB(J,K)	SETP3800
78 P(I,J) = SUM	SETP3810
DO 80 J=1,NSTX	SETP3820
80 P(I,J) = PH(I,J)	SETP3830
IF(NPU.EQ.0) GO TO 88	SETP3840
DO 84 I=1,10	SETP3850
DO 84 J=1,NPU	SETP3860
SUM = 0.	SETP3870
DO 82 K=1,9	SETP3880
82 SUM = SUM + DUB(I,K)*CUZ(K,J)	SETP3890
84 PH(I,J) = SUM	SETP3900
DO 86 I=1,10	SETP3910
DO 86 J=1,NPU	SETP3920
86 CUZ(I,J) = PH(I,J)	SETP3930
88 IF(NPV.EQ.0) GO TO 100	SETP3940
DO 92 I=1,10	SETP3950
DO 92 J=1,NPV	SETP3960
SUM = 0.	SETP3970
DO 90 K=1,9	SETP3980
90 SUM = SUM + DUB(I,K)*CVZ(K,J)	SETP3990
92 PH(I,J) = SUM	SETP4000
DO 94 I=1,10	SETP4010
DO 94 J=1,NPV	SETP4020
94 CVZ(I,J) = PH(I,J)	SETP4030
100 WRITE(OUT,3021)	SETP4040
WRITE(OUT,1021) (I,I,X(I),P(I,I),I=1,10)	SETP4050
3021 FORMAT(//,24H STATE VECTOR COMPONENTS/43H COMP. ID.NO.	EST,SETP4060
*VALUE VARIANCE)	SETP4070
1021 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP4080
IF(NSTC) 102,104,102	SETP4090
102 WRITE(OUT,1022)	SETP4100
1022 FORMAT(42H MODEL PARAMETERS IN EXPANDED STATE VECTOR)	SETP4110
DO 103 I=1,NSTC	SETP4120
LT=NC(I)	SETP4130
MT=I+10	SETP4140
103 WRITE(OUT,1023) MT,LT,C(LT),P(MT,MT)	SETP4150
1023 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP4160
104 IF(NPU) 106,108,106	SETP4170
106 WRITE(OUT,1024)	SETP4180
1024 FORMAT(55H RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR))	SETP4190
DO 107 I=1,NPU	SETP4200
LT=MC(I)	SETP4210
107 WRITE(OUT,1023) I,LT,C(LT),D(I)	SETP4220
108 IF(NPV) 110,112,110	SETP4230
110 WRITE(OUT,1025)	SETP4240
1025 FORMAT(61H RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V-VESETP4250	
ACTOR))	SETP4260
DO 111 I=1,NPV	SETP4270
LT=MCC(I)	SETP4280
111 WRITE(OUT,1023) I,LT,C(LT),S(I)	SETP4290
112 LT=9	SETP4300
IF(NPC(3).EQ.0) LT = 10	SETP4310
IF(NST-LT) 114,120,114	SETP4320
114 WRITE(OUT,1026)	SETP4330
1026 FORMAT(48H IMPROPER NUMBER OF STATE VARIABLES ARE INPUTTED)	SETP4340
CALL EXIT	SETP4350

120 IF(NPC(1)-1) 124,122,124	SETP4360
122 NALL=10	SETP4370
GO TO 128	SETP4380
124 NALL = 10*(NSTX+NPU+1)	SETP4390
K = NSTX + NPU	SETP4400
DO 126 I =1,10	SETP4410
DO 125 J=1,K	SETP4420
125 PH(I,J) = 0.	SETP4430
126 PH(I,I) = 1.	SETP4440
128 IF(NPC(1)-2) 144,130,144	SETP4450
130 IF(NSTA-1) 144,144,132	SETP4460
132 DO 142 I=2,NSTA	SETP4470
MT=NS(I-1)	SETP4480
TT=DTF(MT)	SETP4490
DO 136 J=1,NSTA	SETP4510
K=NS(J)	SETP4520
IF(TT-DTF(K)) 135,135,136	SETP4530
135 TT=DTF(K)	SETP4540
LT=J	SETP4550
136 CONTINUE	SETP4560
137 IP=NS(I-1)	SETP4570
138 NS(I-1)=NS(LT)	SETP4580
139 NS(LT)=IP	SETP4590
142 CONTINUE	SETP4600
144 KDATA=-1	SETP4760
WRITE(SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SETP4770
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SETP4780
ET = TO	SETP4790
TZERO = TC	SETP4800
TIMES=TZERO-10.	SETP4810
T = TO	SETP4820
KDAP = 1	SETP4830
KPROP=-1	SETP4840
KDATAS =-1	SETP4850
C(151) = C(151)*CONRD	SETP4860
C(152) = C(152)*CONRD	SETP4870
RETURN	SETP4880
END	SETP4890

```

SUBROUTINE SMOOTH
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUV(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRS,JST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSS,L,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYPS,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GO
CALL IDENT
FLOS = 0.
TIME = TZERO - 10.
NALLSV=NALL
MOPTSV=NPC(1)
DCOMP=-DCOMP
IF(NPC(1)-1) 4,6,2
2 IF(NPC(8)-4) 12,6,12
4 IF(NPC(7).GT.ICOUNT) IF(NPC(8)-4) 16,6,16
IF(NPC(8).LE.1) GO TO 8
IF(NPC(8).LE.3) GO TO 14
6 TZERO = TO
NPC(7) = ICOUNT
GO TO 62
8 NPC(1) = 1

```

NALL=10	SMTH0160
9 IF(NPC(8).EQ.0) GO TO 12	SMTH0170
IF(NPC(8).EQ.2) GO TO 12	SMTH0180
10 KSM = 1	SMTH0190
GO TO 18	SMTH0200
12 KSM = 0	SMTH0210
GO TO 18	SMTH0220
14 IF(NPC(8)-2) 12,12,10	SMTH0230
16 NPC(1) = 1	SMTH0240
NALL=10	SMTH0250
GO TO 9	SMTH0260
18 T2 = TO	SMTH0270
WRITE(OUT,1004)	SMTH0280
20 CALL INTAG	SMTH0290
TO=T2	SMTH0300
IF(ET.LE.TIME) GO TO 150	SMTH0310
IF(NPC(1).NE.1) CALL PROP	SMTH0320
24 CALL OUTPUT	SMTH0330
L1=1	SMTH0340
28 IF(T2-TZERO) 60,60,30	SMTH0350
30 ET=ET-DET	SMTH0360
IF(KSM.LE.0) GO TO 38	SMTH0370
36 TIME = TYM(KG)	SMTH0380
37 IF(TIME.LE.ET) GO TO 38	SMTH0390
T2 = TIME	SMTH0400
GO TO 20	SMTH0410
38 T2 = ET	SMTH0420
GO TO 20	SMTH0430
60 NALL=NALLSV	SMTH0440
NPC(1)=MOPTSV	SMTH0450
DCOMP=-DCOMP	SMTH0460
IF(ICOUNT-NPC(7)) 64,62,62	SMTH0470
62 ET=TFINAL	SMTH0480
NPC(1)=1	SMTH0490
L1=0	SMTH0500
GO TO 99	SMTH0510
64 ICOUNT=ICOUNT+1	SMTH0520
DO 66 I=1,9	SMTH0530
66 NTR(I) = 0	SMTH0540
REWIND FIT	SMTH0550
REWIND PQR	SMTH0560
KDATAS=-1	SMTH0570
KDATA=-1	SMTH0580
KPROP=-1	SMTH0590
NCOUNT=0	SMTH0600
L1=1	SMTH0610
BACKSPACE SCRACH	SMTH0620
BACKSPACE SCRACH	SMTH0630
READ (SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SMTH0640
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SMTH0650
CALL IDENT	SMTH0660
99 RETURN	SMTH0670
150 MTYP=MTP(KG)	SMTH0680
IF(KG.EQ.0) GO TO 158	SMTH0690
CALL OBSERV	SMTH0700
DO 156 I=1,3	SMTH0710
IF(MR(I,MTYP)) 152,154,152	SMTH0720
152 RES(I)=DFM(I)-DAT(I,KG)	SMTH0730
IF(MTYP.GT.5) GO TO 153	SMTH0740
IF(I.EQ.1) GO TO 153	SMTH0750

IF (ABS (RES (I)).LT.3.1416) GO TO 153	SMTH0760
RES (I)=RES (I)-SIGN (6.283185307179586,RES (I))	SMTH0770
153 CONTINUE	SMTH0780
RES (I+3)= RES (I)/SP (I)	SMTH0790
FLOS= FLOS + RES (I+3)**2	SMTH0800
KD (I)=NCOUNT	SMTH0810
NCOUNT=NCOUNT-1	SMTH0820
GO TO 156	SMTH0830
154 RES (I)=0.	SMTH0840
RES (I+3)=0.	SMTH0850
KD (I) = 0	SMTH0860
156 CONTINUE	SMTH0870
IF (L1.NE.0) WRITE (OUT,1000)	SMTH0880
L1=0	SMTH0890
WRITE (OUT,1002) (KD (I),I=1,3),MTYP,TO,(RES (I),I=1,6),FLOS	SMTH0900
KG=KG-1	SMTH0910
IF (KG.GT.0) GO TO 36	SMTH0920
158 TIME=TZERO-10.	SMTH0930
GO TO 37	SMTH0940
1000 FORMAT (//5X6HPPOINTS4X,4HTYPE,3X,4HTIME,6X,4HRES1,9X,4HRES2,9X,4HRES3,9X,8HWGT.RES1,5X,8HWGT.RES2,5X,8HWGT.RES3,5X,9HLOSS FCTN)	SMTH0950
1002 FORMAT (1X,I4,1H,I4,1H,I4,1X,I2,1X,F10.3,7(1X,E12.5))	SMTH0960
1004 FORMAT (///20(1H*),25HBEGIN BACKWARDS SMOOTHING,75(1H*))	SMTH0970
END	SMTH0980
	SMTH0990

```

SUBROUTINE STAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /MOD1/ ALPH,AS,BETA,CA(6),CALP,CBET,CETA,
1 CF(3),JCS,CXZI,DADX(2,10),DCDY(3,4),DERIV(3,10),DRDH,
2 DRDP,DWDH(2),ETA,HO,N4(3),N5(3),N6(3),PAXP(3,30),
3 PE,ROE,ROEC,ROEM,SALP,SBET,
4 SETA,SREF,SXZI,TAU,TMAS(20),TONE,
5 TTWO,TUW(20),TVW(20),UW,VA(5),VB(5),
6 VW,XIND1,XIND2,XLREF,XM,
7 XMAS(20),XNU,XQ,XQSM,XRE,XTEMP,
8 XUW(20),XVW(20),XZI,YMAS,YMASM
COMMON /TWICE/ A(3,3),CPH,CT(5),SP(10),ST(5)
1 TPH,VO(20),ZO(20),AG(3),AMDOT(3),APDOT(4)
2 B(8),CGM(3),DFM(3),DTRAN(3,3),DUD(10,1),DUE(4)
3 DUF(4),F1(3,40),F2(3,5),F3(4,40),GG(3),HI(2)
4 IDN,II,IP,IPC,JJ,JN,KA,KD(3),KDUM,KG2
5 K1,NNN,NPTS,PAR(6),PDOT(3),PMDOT(3),RES(6)
6 RO,SPD(5),SPH,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3),AM(3),AP(4),AX(40),AY(40)
1 AZ(40),C(160),CCAPH(5),CONRD,CPHDT(5),CUZ(30,5)
2 CVZ(30,5),D(5),DAT(3,40),DATA(3),DATAS(3),DATC(3)
3 DET,DFIT(9),DTF(9),DTI(9),DZ(30),ET
4 FLOS,G(3,30),H(3,5),I,ICOUNT,J,JNBR,JNBRJ,JUST
5 K,KAR,KC(3),KDAP,KDATA,KDATAS,KG,KI,KK
6 KN,KOB,KPROP,KS,KSM,KSSL,LC(3),LCS(3),LS,LT
7 L1,M,MC(5),MCC(5),MO(5),MR(3,9),MT
8 MTP(40),MTYP,MTYP5,N,NC(30),NCOUNT,NPC(15)
9 NPU,NPV,NS(9),NSS(5),NST,NSTA,NSTC,NSTX,NT,NTR(9)
A N8(3),N9(3),N10(3),N11(3),OMEGA,P(30,30)
B PA(3),PM(3),R,REO,RERP2
C RPO,ROT(5),S(5),SCAPH(5),SI(3),SIG(3,40)
D SIGM(3),SIGMS(3),SPHDT(5),SUM,SUM2,SYG(3,9),TFINAL
E TFIT(9),TIME,TIMES,TO,TP(40),TQ(40)
F TR(40),TT(40),TXCG(20),TYCG(20),TYM(40),TZCG(20)
G TZERO,XJ2,XMU,XMUJ,XP(3),XXCG(20)
H XYCG(20),XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
COMMON /ATMCON/ ABET,AGAM,AMO,APO,AR,ASU,ATM(4),HB(23),ISV,JK
A PB(23),RL(23),TMB(23)
COMMON /EXTRA/ GC
EQUIVALENCE (SP(3),PHIDT),(SP(4),CAPHI)
IF(MTYP.GT.5) RETURN
N = 60 + 15*MTYP
SP(1) = COS(C(N+13))
SP(2) = SIN(C(N+13))
PHIDT = ATAN2(RERP2*SP(2),SP(1))
CAPHI = PHIDT - C(N+13)
SPHDT(MTYP) = SIN(PHIDT)
CPHDT(MTYP) = COS(PHIDT)
CCAPH(MTYP) = COS(CAPHI)
SCAPH(MTYP) = SIN(CAPHI)
ROT(MTYP) = REC/SQRT(1.+(RERP2-1.)*SP(2)**2)
99 RETURN
END

```

FUNCTION TAB(TARG,N,T,Y)	
DIMENSION N(1),T(1),Y(1)	
IF(N(1))111,14,111	TABT0010
111 CONTINUE	TABT0020
I = N(2)	TABT0030
6 IF(TARG - T(I))3,2,1	TABT0040
1 IF(N(3))9,5,9	TABT0050
5 I = I+1	TABT0060
IF(I-N(1)) 6,4,4	TABT0070
4 I = I - 1	TABT0080
8 TAB = (Y(I+1)*(TARG - T(I)) - Y(I)*(TARG - T(I+1)))/(T(I+1)-T(I))	TABT0090
7 N(2) = I	TABT0100
99 RETURN	TABT0110
11 I = I - 1	TABT0120
2 TAB = Y(I)	TABT0130
GO TO 7	TABT0140
9 IF(TARG - T(I-1)) 4,11,12	TABT0150
3 IF(N(3))5,10,5	TABT0160
10 IF(TARG - T(I-1))12,11,4	TABT0170
12 I = I - 1	TABT0180
IF(I-1)18,8,6	TABT0190
18 I=1	TABT0200
GO TO 8	TABT0210
14 TAB = 0.	TABT0220
RETURN	TABT0230
END	TABT0240
	TABT0250

B. STEP2 Listing

The STEP2 source listing is presented in the following subsection. The following listing indicates the pages on which the STEP2 subroutine listings appear:

MAIN	217
DATAB	221
FXXU	224
INDAT	229
INTAG	233
MINVAR	235
MOTION	239
OBSERV	242
OUTPUT	250
PRESET	256
PROP	258
RKUTTA	260
SETUP	261
SMOOTH	268
STAT	271
TAB	272


```

PROGRAM MAIN(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,
2 TAPE7, TAPE1,TAPE2,TAPE3,TAPE4)
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBR5 ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROPC,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MQ(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
C-----STATISTICAL TRAJECTORY ESTIMATION PROGRAM, STEP2
C DEVELOPED BY W.E.WAGNER AND A.C.SEROLD
C MARTIN MARIETTA CORPORATION
C DENVER, COLORADO
2 CONTINUE
CALL PRESET
4 WRITE(OUT,1001)
IF(NPC(1).EQ.0) WRITE(OUT,1000) ICOUNT
1000 FORMAT(19H ITERATION NUMBER I2//)
1001 FORMAT(1H1)
10 IF(KDATA) 12,42,202
12 T2=TO
CALL INTAG
GO TO 44
24 T2=TIME
IF(T2-ET)260,260,42
30 IF(TO-ET) 34,32,32
32 IF(JST.EQ.1) GO TO 44
34 IF(KLATA) 36,36,36
36 IF(KPROPC.EQ.1) GO TO 24
IF(KDATA) 10,40,10
38 IF(NPC(1)-1) 200,40,100
40 TIME=TFINAL+100.
GO TO 24
42 T2=ET
C-----PROPAGATION LOOP, TO EFN 44

```

CALL INTAG	STP20280
KPROP=1	STP20290
TO=T2	STP20300
CALL PROP	STP20310
44 CALL OUTPUT	STP20320
LI=2	STP20340
IF(ET-TFINAL) 46,50,50	STP20350
46 ET=ET+DET	STP20360
GO TO 34	STP20370
50 WRITE(SCRACH) KDATA	STP20380
IF(NPC(1).EQ.1) GO TO 2	STP20390
56 IF(NPC(4)) 300,58,300	STP20400
58 CALL SMOOTH	STP20410
IF(LI-1) 2,4,2	STP20420
C-----DETERMINE MEASUREMENT TIME FOR ERROR	STP20430
C ANALYSIS PROBLEMS, THRU EFN 118--	STP20440
100 IF(KPROP.GT.0) GO TO 24	STP10432
JUST=1	STP10434
IF(NSTA-1) 40,102,104	STP10440
102 II=NS(1)	STP20460
GO TO 112	STP20470
104 II = NS(1)	STP20480
SP(1) = DTI(II)	STP20490
DO 110 I=2,NSTA	STP20510
J=NS(1)	STP20520
IF(SP(1)-DTI(J)) 110,106,107	STP20530
106 JUST=JUST+1	STP20540
GO TO 108	STP20550
107 JUST=1	STP20560
108 SP(1) = DTI(J)	STP20570
II=J	STP20580
110 CONTINUE	STP20590
112 IF(DTI(II)-DTF(II)) 116,116,114	STP20600
114 NSTA=NSTA-1	STP20610
GO TO 100	STP20620
116 JNBR=0	STP20630
TIME=DTI(II)	STP20640
DTI(II)=DTI(II)+DFIT(II)	STP20650
DO 118 I=1,3	STP20660
IF(MR(I,II).EQ.0) GO TO 118	STP20670
JNBR=JNBR+1	STP20680
LC(JNBR)=I	STP20690
118 CONTINUE	STP20700
IF(JNBR.EQ.0) GO TO 100	STP20710
MTYP=II	STP20720
GO TO 24	STP20730
C-----DATA EDITING LOGIC FOR FILTER PROBLEMS, THRU EFN 250-----	STP20740
200 KG = 1	STP20750
KS = 1	STP20760
TYM(1) = TZERO - 10.	STP20770
GO TO 211	STP20780
202 KG=KG+1	STP20790
MTP(KG)=MTYPS	STP20800
TYM(KG)=TIMES	STP20810
DAT(1,KG)=DATAS(1)	STP20820
DAT(2,KG)=DATAS(2)	STP20830
DAT(3,KG)=DATAS(3)	STP20840
SIG(1,KG)=SIGMS(1)	STP20850
SIG(2,KG)=SIGMS(2)	STP20860
SIG(3,KG)=SIGMS(3)	STP20870

MTYP=MTYPS	STP20890
TIME=TIMES	STP20900
DATA(1)=DATAS(1)	STP20910
DATA(2)=DATAS(2)	STP20920
DATA(3)=DATAS(3)	STP20930
SIGM(1)=SIGMS(1)	STP20940
SIGM(2)=SIGMS(2)	STP20950
SIGM(3)=SIGMS(3)	STP20960
LC(1)=LCS(1)	STP20970
LC(2)=LCS(2)	STP20980
LC(3)=LCS(3)	STP20990
JNBR=JNBRS	STP21000
204 IF(KI-KS) 206,208,208	STP21010
206 KI=KI+1	STP21020
GO TO 216	STP21030
208 KS=KG	STP21040
210 CONTINUE	STP21050
211 IF(KDATAS.EQ.0) GO TO 212	STP21060
READ(FIT) KDATAS,(MTP(KS+I),TYM(KS+I),(DAT(J,KS+I),J=1,3),(SIG(J	STP21070
X,KS+I),J=1,3),I=1,KDATAS)	STP21080
KS=KS+KDATAS	STP21090
IF(KS-20) 210,215,215	STP21100
212 IF(KG+1-KS) 215,213,213	STP21110
213 KDATA=0	STP21120
GO TO 248	STP21130
215 KI=KG+1	STP21140
216 MTYPS=MTP(KI)	STP21150
TIMES=TYM(KI)	STP21160
IF(TIMES.GT.TFINAL) GO TO 213	STP21170
IF(NTR(MTYPS)) 220,218,220	STP21180
218 IF(TIMES.LT.DTI(MTYPS)) GO TO 204	STP21190
TFIT(MTYPS)=TIMES	STP21200
NTR(MTYPS)=1	STP21210
220 CONTINUE	STP21220
222 IF(TIMES-DTF(MTYPS)) 224,224,204	STP21230
224 IF(TIMES-TFIT(MTYPS)) 226,234,228	STP21240
226 NTR(MTYPS)=3	STP21250
GO TO 204	STP21260
228 IF(NTR(MTYPS)-3) 230,232,230	STP21270
230 TFIT(MTYPS)=TFIT(MTYPS)+DFIT(MTYPS)	STP21280
NTR(MTYPS)=3	STP21290
GO TO 224	STP21300
232 TFIT(MTYPS)=TIMES	STP21310
234 NTR(MTYPS)=2	STP21320
JNBR=0	STP21330
DO 238 I=1,3	STP21340
IF(MR(I,MTYPS)) 236,238,236	STP21350
236 JNBR=JNBR+1	STP21360
LCS(JNBR)=I	STP21370
238 CONTINUE	STP21380
IF(JNBR) 240,204,240	STP21390
240 DATAS(1)=DAT(1,KI)	STP21400
DATAS(2)=DAT(2,KI)	STP21410
DATAS(3)=DAT(3,KI)	STP21420
SIGMS(1)=SIG(1,KI)	STP21430
SIGMS(2)=SIG(2,KI)	STP21440
SIGMS(3)=SIG(3,KI)	STP21450
IF(KDATA) 242,244,244	STP21460
242 KDATA=2	STP21465
IF(TIMES-TZERO) 204,202,202	STP21465

244 IF(TIMES-TIME) 248,246,248	STP21480
246 JST=2	STP21490
GO TO 250	STP21500
248 JST=1	STP21510
250 GO TO 24	STP21520
C-----PROCESSING LOOP, THRU EFN 278-----	STP21530
260 CALL INTAG	STP21540
TO=T2	STP21550
KPROP=0	STP21560
KN=0	STP21570
KK = 1	STP21580
IF(JNBR-1) 270,270,262	STP21590
262 IF(NPC(9)) 268,264,268	STP21600
264 KN=1	STP21610
GO TO 270	STP21620
268 KK=JNBR	STP21630
IF(NPC(4)) 264,270,264	STP21640
270 KAR=1	STP21650
272 CALL OBSERV	STP21660
273 IF(T-TSAV) 274,276,274	STP21670
274 CALL PROP	STP21680
TSAV=T	STP21690
276 IF(NPC(9),NE.0) KOB = KAR	STP21700
CALL MINVAR	STP21710
IF(KAR-KK) 278,30,30	STP21720
278 KAR=KAR+1	STP21730
IF(KN,NE.0) GO TO 276	STP21740
CALL MOTION	STP21750
GO TO 272	STP21760
C-----UPDATE STATE, EQ.(55A), THRU EFN 312-----	STP21770
300 DO 306 I=1,10	STP21780
SUM=0.	STP21790
DO 304 K=1,10	STP21800
304 SUM=SUM+PH(I,K)*DZ(K)	STP21810
306 UUD(I)=SUM	STP21820
DO 312 I=1,NSTX	STP21830
IF(I-10) 308,308,310	STP21840
308 DZ(I)=UUD(I)	STP21850
X(I)=X(I)+DZ(I)	STP21860
GO TO 312	STP21870
310 K=NC(I-10)	STP21880
C(K)=C(K)+DZ(I)	STP21890
VO(I-10)=C(K)	STP21900
312 CONTINUE	STP21910
C-----NORMALIZE QUATERNION-----	STP21920
DATC(1)= SQRT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	STP21930
X(7) = X(7)/DATC(1)	STP21940
X(8) = X(8)/DATC(1)	STP21950
X(9) = X(9)/DATC(1)	STP21960
X(10)=X(10)/DATC(1)	STP21970
C-----UPDATE TRACKING STATION LOCATIONS-----	STP21980
IF(KSS,LE.0) GO TO 316	STP21990
DO 314 I=1,KSS	STP22000
Mtyp=NSS(I)	STP22010
314 CALL STAT	STP22020
316 WRITE(OUT,1003)	STP22030
1003 FORMAT(39H UPDATED MODEL PARAMETERS AT FINAL TIME)	STP22040
WRITE(OUT,1002) (NC(I),VO(I),I=1,NSTC)	STP22050
1002 FORMAT(62H C,I3,E15.8))	STP22060
GO TO 58	STP22070
END	STP22080

```

SUBROUTINE DATAB
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENC/ IN,OUT,FIT,STATE,SCRACH,PQR
IF(DCOMP.LT.0.) GO TO 20
IF(KPROP.GE.0) GO TO 10
2 CONTINUE
4 LS = 0
6 IF(KDAP.EQ.0) GO TO 14
READ(PQR) KDAP,(TT(LS+1),TP(LS+1),TQ(LS+1),TR(LS+1),AX(LS+1),
* AY(LS+1),AZ(LS+1),I=1,KDAP)
LS = LS+KDAP
IF(LS.EQ.1) GO TO 6
IF(T.GT.TT(LS)) GO TO 11
IF(LS.LE.20) GO TO 6
N11(2)=3
10 IF(T.LT.TT(LS-1)) GO TO 14
IF(KDAP.EQ.0) GO TO 14
KG2 = KG-2
WRITE(SCRACH) LS,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),
* I=1,LS),KG2,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KG2)
IF(KG2.LE.0) GO TO 11
KG = 2
DO 13 I=1,2
LT = KG2 + I
MTP(I) = MTP(LT)
TYM(I) = TYM(LT)
DAT(1,I) = DAT(1,LT)
DAT(2,I) = DAT(2,LT)

```

DAT(3,I) = DAT(3,LT)	DATB0270
SIG(1,I) = SIG(1,LT)	DATB0280
SIG(2,I) = SIG(2,LT)	DATB0290
SIG(3,I) = SIG(3,LT)	DATB0300
13 CONTINUE	DATB0310
11 CONTINUE	DATB0320
DO 12 I=1,2	DATB0330
MT = LS + I - 2	DATB0340
TT(I) = TT(MT)	DATB0350
TP(I) = TP(MT)	DATB0360
TQ(I) = TQ(MT)	DATB0370
TR(I) = TR(MT)	DATB0380
AX(I) = AX(MT)	DATB0390
AY(I) = AY(MT)	DATB0400
AZ(I) = AZ(MT)	DATB0410
12 CONTINUE	DATB0420
LS = 2	DATB0430
GO TO 6	DATB0440
14 N11(1) = LS	DATB0450
IF(KPROP.LT.0) TRCD=TT(1)	DATB0460
KPROP = 1	DATB0470
PM(1) = TAB(T,N11(1),TT(1),TP(1))	DATB0480
PM(2)=TAB(T,N11(1),TT(1),TQ(1))	DATB0490
PM(3)=TAB(T,N11(1),TT(1),TR(1))	DATB0500
AM(1)= TAB(T,N11(1),TT(1),AX(1))	DATB0510
AM(2)= TAB(T,N11(1),TT(1),AY(1))	DATB0520
AM(3)= TAB(T,N11(1),TT(1),AZ(1))	DATB0530
CGM(1) = TAB(T,N8(1) ,TXCG(1),XXCG(1))	DATB0540
CGM(2) = TAB(T,N9(1) ,TYCG(1),XYCG(1))	DATB0550
CGM(3) = TAB(T,N10(1),TZCG(1),XZCG(1))	DATB0560
99 RETURN	DATB0570
20 IF(T.GT.TT(2)) GO TO 14	DATB0580
IF(TT(1).EQ.TRCD) GO TO 14	DATB0590
BACKSPACE SCRACH	DATB0600
BACKSPACE SCRACH	DATB0610
LT = 40-KG	DATB0620
DO 22 I=1,KG	DATB0630
MT = LT+I	DATB0640
MTP(MT) = MTP(I)	DATB0650
TYM(MT) = TYM(I)	DATB0660
DAT(1,MT) = DAT(1,I)	DATB0670
DAT(2,MT) = DAT(2,I)	DATB0680
DAT(3,MT) = DAT(3,I)	DATB0690
SIG(1,MT) = SIG(1,I)	DATB0700
SIG(2,MT) = SIG(2,I)	DATB0710
22 SIG(3,MT) = SIG(3,I)	DATB0720
READ(SCRACH) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),	DATB0730
* I=1,KDAP),KDATA,(MTP(I),TYM(I),DAT(1,I),DAT(2,I),DAT(3,I),	DATB0740
* SIG(1,I),SIG(2,I),SIG(3,I),I=1,KDATA)	DATB0750
LS=KDAP	DATB0760
N11(2)=LS-2	DATB0770
IF(KDATA.LT.0) GO TO 26	DAT20780
LT = LT - KDATA	DATB0790
I = KDATA+1	DATB0800
J = KDATA+KG	DATB0810
DO 24 I=I,J	DATB0820
MT = LT + I	DATB0830
MTP(I) = MTP(MT)	DATB0840
TYM(I) = TYM(MT)	DATB0850
DAT(1,I) = DAT(1,MT)	DATB0860

DAT(2,I) = DAT(2,MT)
 DAT(3,I) = DAT(3,MT)
 SIG(1,I) = SIG(1,MT)
 SIG(2,I) = SIG(2,MT)
 24 SIG(3,I) = SIG(3,MT)
 KG = KG + KDATA
 GO TO 14
 26 KG = 1
 GO TO 14
 END

DAT80870
 DAT80880
 DAT80890
 DAT80900
 DAT80910
 DAT80920
 DAT80930
 DAT80940
 DAT80950
 DAT80960

```

SUBROUTINE FXXU
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DIMENSION CX(3,4)
EQUIVALENCE (C(48),CX(1,1))
C-----CALCULATE EGS. IN TABLE 4 -----
SP(1) = PAR(4)*X(2)/CPH**2
F2(2,1) = 1./R
F1(1,3) = F2(2,1)*X(1)
F1(3,1) = -F1(1,3)-F1(1,3)
F1(3,2) = -F1(2,3)-F1(2,3)
F1(1,1) = F2(2,1)*X(3)
F1(1,2) = -F1(2,1)-F1(2,1)
F1(1,4) = (-PAR(5)*F2(2,1)+4.*PAR(3)*SPH*CPH)*F2(2,1)
F1(1,5) = SP(1)*F1(3,2)*R - PAR(3)*(CPH+SPH)*(CPH-SPH)
F1(2,4) = -F1(2,2)*F1(2,3)
F1(2,5) = -SP(1)*F1(3,1)*R
F1(3,4) = (PAR(1)*F2(2,1)-PAR(2)-PAR(2) + 4.*PAR(3)*PAR(6))*
* F2(2,1)
F1(3,5) = -3.*PAR(3)*SPH*CPH
F2(2,4) = -F1(1,3)*F2(2,1)
F2(3,2) = F2(2,1)/CPH
F2(3,4) = -F1(2,3)*F2(3,2)
F2(3,5) = F1(2,1)/CPH
F3(1,1) = -X( 9)*PAR(4)
F3(2,1) = X(10)*PAR(4)
F3(3,1) = X( 7)*PAR(4)
F3(4,1) = -X( 8)*PAR(4)
F3(1,2) = (X( 8)-X(10)*TPH)*PAR(4)
F3(2,2) = -(X( 7)+X( 9)*TPH)*PAR(4)

```


F3(3,2) = (X(10)+X(8)*TPH)*PAR(4)	FXXU0280
F3(4,2) =-(X(9)-X(7)*TPH)*PAR(4)	FXXU0290
F3(1,4) =-F1(1,3)*F3(1,1) - F1(2,3)*F3(1,2)	FXXU0300
F3(2,4) =-F1(1,3)*F3(2,1) - F1(2,3)*F3(2,2)	FXXU0310
F3(3,4) =-F1(1,3)*F3(3,1) - F1(2,3)*F3(3,2)	FXXU0320
F3(4,4) =-F1(1,3)*F3(4,1) - F1(2,3)*F3(4,2)	FXXU0330
F3(1,5) =-X(10)*SP(1)	FXXU0340
F3(2,5) =-X(9)*SP(1)	FXXU0350
F3(3,5) = X(8)*SP(1)	FXXU0360
F3(4,5) = X(7)*SP(1)	FXXU0370
F1(1,7) = 2.*(X(7)*AB(1)-X(10)*AB(2)+X(9)*AB(3))	FXXU0380
F1(1,8) = 2.*(X(8)*AB(1)+X(9)*AB(2)+X(10)*AB(3))	FXXU0390
F1(1,9) = 2.*(-X(9)*AB(1)+X(8)*AB(2)+X(7)*AB(3))	FXXU0400
F1(1,10)=-2.*(X(10)*AB(1)+X(7)*AB(2)-X(8)*AB(3))	FXXU0410
F1(2,7) =-F1(1,10)	FXXU0420
F1(2,8) =-F1(1, 9)	FXXU0430
F1(2,9) = F1(1, 8)	FXXU0440
F1(2,10)= F1(1, 7)	FXXU0450
F1(3,7) = F1(1, 9)	FXXU0460
F1(3,8) =-F1(1,10)	FXXU0470
F1(3,9) =-F1(1, 7)	FXXU0480
F1(3,10)= F1(1, 8)	FXXU0490
F3(2,7) =-F3(1,8)	FXXU0500
F3(3,7) =-F3(1, 9)	FXXU0510
F3(3,8) =-F3(2, 9)	FXXU0520
F3(4,7) =-F3(1,10)	FXXU0530
F3(4,8) =-F3(2,10)	FXXU0540
F3(4,9) =-F3(3,10)	FXXU0550
F2(1,3) = -1.	FXXU0560
F1(1,6) = 0.	FXXU0570
F1(2,6) = 0.	FXXU0580
F1(3,6) = 0.	FXXU0590
F1(3,3) = 0.	FXXU0600
F2(1,1) = 0.	FXXU0610
F2(1,2) = 0.	FXXU0620
F2(1,4) = 0.	FXXU0630
F2(1,5) = 0.	FXXU0640
F2(2,2) = 0.	FXXU0650
F2(2,3) = 0.	FXXU0660
F2(2,5) = 0.	FXXU0670
F2(3,1) = 0.	FXXU0680
F2(3,3) = 0.	FXXU0690
F3(1,3) = 0.	FXXU0700
F3(2,3) = 0.	FXXU0710
F3(3,3) = 0.	FXXU0720
F3(4,3) = 0.	FXXU0730
F3(1,6) = 0.	FXXU0740
F3(2,6) = 0.	FXXU0750
F3(3,6) = 0.	FXXU0760
F3(4,6) = 0.	FXXU0770
F3(1,7)=0.	FXXU0780
F3(2,8)=0.	FXXU0790
F3(3,9)=0.	FXXU0800
F3(4,10)=0.	FXXU0810
LT= 0	FXXU0820
MT=0	FXXU0830
NT = 0	FXXU0840
IF(NSTC) 1,1,6	FXXU0850
1 IF(NPU) 2,99,2	FXXU0860
2 N = NSTX	FXXU0870

NT = 1	FXXU0880
II = 1	FXXU0890
3 NNN = MC(II)	FXXU0900
GO TO 18	FXXU0910
6 N = 10	FXXU0920
II = 1	FXXU0930
9 NNN = NC(II)	FXXU0940
GO TO 18	FXXU0950
12 II = II+1	FXXU0960
IF(NT) 13,13,15	FXXU0970
13 IF(II-NSTC) 9,9,1	FXXU0980
15 IF(II-NPU) 3,3,99	FXXU0990
18 CONTINUE	FXXU1000
IF(NNN.GT.72) GO TO 25	FXXU1010
19 IF(NNN-33) 100,100,20	FXXU1020
20 IF(MT) 21,24,21	FXXU1030
21 CONTINUE	FXXU1040
SP(1) = 0.	FXXU1050
SP(2) = 0.	FXXU1060
SP(3) = 0.	FXXU1070
IF(NNN-59) 150,150,300	FXXU1080
25 DO 26 I=1,3	FXXU1090
F1(I,II+N) = 0.	FXXU1100
F3(I,II+N) = 0.	FXXU1110
26 CONTINUE	FXXU1120
F3(4,II+N) = 0.	FXXU1130
GO TO 12	FXXU1140
24 CONTINUE	FXXU1150
MT=1	FXXU1160
K = 0	FXXU1170
DO 27 I=1,3	FXXU1180
DO 27 J=1,3	FXXU1190
K = K+1	FXXU1200
27 SP(K) = PA(I)*XP(J)	FXXU1210
DTRAN(1,1) = SP(5) + SP(9)	FXXU1220
DTRAN(1,2) = -2.*SP(4) + SP(2)	FXXU1230
DTRAN(1,3) = -2.*SP(7) + SP(3)	FXXU1240
DTRAN(2,1) = SP(4) -2.*SP(2)	FXXU1250
DTRAN(2,2) = SP(1) + SP(9)	FXXU1260
DTRAN(2,3) = -2.*SP(8) + SP(6)	FXXU1270
DTRAN(3,1) = SP(7) -2.*SP(3)	FXXU1280
DTRAN(3,2) = SP(6) - 2.*SP(6)	FXXU1290
DTRAN(3,3) = SP(1) + SP(5)	FXXU1300
GO TO 21	FXXU1310
30 CONTINUE	FXXU1320
SP(1) = SP(1)-XP(3)*DUD(2)+XP(2)*DUD(3)	FXXU1330
SP(2) = SP(2)+XP(3)*DUD(1)-XP(1)*DUD(3)	FXXU1340
SP(3) = SP(3)-XP(2)*DUD(1)+XP(1)*DUD(2)	FXXU1350
33 CONTINUE	FXXU1360
C-----CALCULATE EQ.(172) -----	FXXU1370
SP(1) = SP(1)-DTRAN(1,1)*SP(4)-DTRAN(1,2)*SP(5)-DTRAN(1,3)*SP(6)	FXXU1380
SP(2) = SP(2)-DTRAN(2,1)*SP(4)-DTRAN(2,2)*SP(5)-DTRAN(2,3)*SP(6)	FXXU1390
SP(3) = SP(3)-DTRAN(3,1)*SP(4)-DTRAN(3,2)*SP(5)-DTRAN(3,3)*SP(6)	FXXU1400
36 I = N + II	FXXU1410
IF(L) 39,42,39	FXXU1420
C-----CALCULATE EQ.(169) -----	FXXU1430
39 F3(1,I) = .5*(-X(8)*SP(4)-X(9)*SP(5)-X(10)*SP(6))	FXXU1440
F3(2,I) = .5*(X(7)*SP(4)-X(10)*SP(5)+X(9)*SP(6))	FXXU1450
F3(3,I) = .5*(X(10)*SP(4)+X(7)*SP(5)-X(8)*SP(6))	FXXU1460
F3(4,I) = .5*(-X(9)*SP(4)+X(8)*SP(5)+X(7)*SP(6))	FXXU1470

GO TO 45	FXXU1480
42 F3(1,I) = 0.	FXXU1490
F3(2,I) = 0.	FXXU1500
F3(3,I) = 0.	FXXU1510
F3(4,I) = 0.	FXXU1520
C-----CALCULATE EQ.(167) -----	FXXU1530
45 F1(1,I) = SP(1)*A(1,1) + SP(2)*A(2,1) + SP(3)*A(3,1)	FXXU1540
F1(2,I) = SP(1)*A(1,2) + SP(2)*A(2,2) + SP(3)*A(3,2)	FXXU1550
F1(3,I) = SP(1)*A(1,3) + SP(2)*A(2,3) + SP(3)*A(3,3)	FXXU1560
GO TO 12	FXXU1570
100 CONTINUE	FXXU1580
C-----CALCULATE EQ.(170) -----	FXXU1590
L = 0	FXXU1600
I = NNN - 30	FXXU1610
SP(1) = -TRAN(1,I)	FXXU1620
SP(2) = -TRAN(2,I)	FXXU1630
SP(3) = -TRAN(3,I)	FXXU1640
GO TO 36	FXXU1650
C-----CALCULATE EQ.(173) -----	FXXU1660
C-----CALCULATE EQ.(174) -----	FXXU1670
150 L = 1	FXXU1680
DUD(1) = 0.	FXXU1690
DUD(2) = 0.	FXXU1700
DUD(3) = 0.	FXXU1710
SP(4) = 0.	FXXU1720
SP(5) = 0.	FXXU1730
SP(6) = 0.	FXXU1740
IF(NNN.GE.48) GO TO 250	FXXU1750
IF(NNN.GE.45) GO TO 200	FXXU1760
J = (NNN-33)/3	FXXU1770
K = NNN - 3*J - 32	FXXU1780
DUD(J) = PMDOT(K)	FXXU1790
SP(J+3) = PM(K)	FXXU1800
GO TO 30	FXXU1810
200 CONTINUE	FXXU1820
SP(NNN-41) = 1.	FXXU1830
GO TO 33	FXXU1840
250 J = (NNN-45)/3	FXXU1850
K = NNN - 3*J - 41	FXXU1860
SP(K) = AP(J)	FXXU1870
DUD(K-3) = APDOT(J)	FXXU1880
GO TO 30	FXXU1890
C-----CALCULATE EQ.(176) -----	FXXU1900
300 CONTINUE	FXXU1910
C-----CALCULATE EQ.(175) -----	FXXU1920
DUD(5) = 0.	FXXU1930
DUD(6) = 0.	FXXU1940
DUD(7) = 0.	FXXU1950
J = (NNN-58)/3	FXXU1960
K = NNN - 3*J - 57	FXXU1970
IF(J-3) 301,301,302	FXXU1980
301 SP(J) = AM(K)	FXXU1990
DUD(J+4) = AMDOT(K)	FXXU2000
GO TO 304	FXXU2010
302 SP(K) = 1.	FXXU2020
J = K	FXXU2030
304 CONTINUE	FXXU2040
IF(J-2) 306,308,310	FXXU2050
306 CONTINUE	FXXU2060
I = 3	FXXU2070

GO TO 312	FXXU2080
308 DUD(4) = 0.	FXXU2090
DUD(8) = 0.	FXXU2100
GO TO 316	FXXU2110
310 CONTINUE	FXXU2120
I = 1	FXXU2130
312 CONTINUE	FXXU2140
SP(5) = AP(I)*DUD(J+4) + APDOT(I)*SP(J)	FXXU2150
SP(6) = AP(J)*SP(J)	FXXU2160
SP(7) = AP(J)*DUD(J+4) + APDOT(J)*SP(J)	FXXU2170
DUD(4) = (AP(4)/AP(J))**3*SP(J)*.25	FXXU2180
IF(LT) 314,313,314	FXXU2190
313 CONTINUE	FXXU2200
LT=1	FXXU2210
SP(9) = AP(1)**2 + AP(3)**2	FXXU2220
SPD(5) = SQRT(SP(9))	FXXU2230
SPD(1) = 2./SPD(5)	FXXU2240
SPD(2) = -(AP(1)*APDOT(3)+AP(3)*APDOT(1))*SPD(1)/SP(9)	FXXU2250
SPD(3) = -AP(4)/SP(9)	FXXU2260
SPD(4) = -(AP(1)*APDOT(1)+AP(3)*APDOT(3))/SP(9)	FXXU2270
SPD(5) = 2.*SPD(4)*SPD(3)	FXXU2280
C-----CALCULATE EQ.(181) -----	FXXU2290
314 DUD(8) = SPD(1)*SP(5) + (SPD(2)+SPD(5))*SP(6) + SPD(3)*SP(7) +	FXXU2300
* SPD(4)*DUD(4)	FXXU2310
316 CONTINUE	FXXU2320
DO 320 I=1,3	FXXU2330
SP(7) = CX(I,4)*DUD(4)	FXXU2340
SP(8) = CX(I,4)*DUD(8)	FXXU2350
DO 318 J=1,3	FXXU2360
SP(7) = SP(7)+CX(I,J)*SP(J)	FXXU2370
318 SP(8) = SP(8)+CX(I,J)*DUD(J+4)	FXXU2380
SP(I+3) = SP(7)	FXXU2390
320 DUD(I) = SP(8)	FXXU2400
L = 1	FXXU2410
GO TO 30	FXXU2420
99 RETURN	FXXU2430
END	FXXU2440

```

SUBROUTINE INDAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TG(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DATA CONV /.3648/
REWIND FIT
REWIND PQR
REWIND SCRACH
REWIND STATE
WRITE(OUT,1030)
1030 FORMAT(1H1,22H DATA ANALYSIS PROGRAM//11H INPUT DATA//)
8 READ(IN,1000) KDUM,(B(I),I=1,8)
1000 FORMAT(I2,7A10,A8)
WRITE(OUT,1001) KDUM,(B(I),I=1,8)
1001 FORMAT(5X,I2,5X,7A10,5X,A8)
IF(KDUM) 7,8,9
7 CALL EXIT
9 GO TO ( 8,20,30,40,50,60,70,80,90,100,110,120,130,140,150,160,170,
X180,190,200),KDUM
20 DECODE(40,1002,B) (NPC(1),I=1,10)
1002 FORMAT(10I4)
IF(NPC(2).EQ.0) GO TO 8
XMU = XMU/CONV**3
REO = REO/CONV
RPO = RPO/CONV
GO TO 8
30 DECODE(30,1003,B) IPC,IDN,SP(1),SP(2)
1003 FORMAT(I2,I4,E12.4,E12.4)
GO TO (32,34,36,38,39),IPC
32 NST=NST+1
ZO(IDN)=SP(1)

```

P(IDN,IDN)=SP(2)**2	INDT0280
GO TO 8	INDT0290
34 NSTC = NSTC + 1	INDT0300
NC(NSTC) = IDN	INDT0310
C(IDN)=SP(1)	INDT0320
P(NSTC+10,NSTC+10) = SP(2)**2	INDT0330
GO TO 8	INDT0340
36 NPU=NPU+1	INDT0350
MC(NPU)=IDN	INDT0360
C(IDN)=SP(1)	INDT0370
D(NPU)=SP(2)**2	INDT0380
GO TO 8	INDT0390
38 NPV=NPV+1	INDT0400
MCC(NPV)=IDN	INDT0410
C(IDN)=SP(1)	INDT0420
S(NPV)=SP(2)**2	INDT0430
GO TO 8	INDT0440
39 C(IDN) = SP(1)	INDT0450
GO TO 8	INDT0460
40 DECODE(54,1004,B) TO,DET,DCOMP,TFINAL	INDT0470
1004 FORMAT(6X,4E12.4)	INDT0480
GO TO 8	INDT0490
50 DECODE(42,1005,B) IPC,SP(1),SP(2),SP(3)	INDT0500
1005 FORMAT(12,4X,3E12.4)	INDT0510
IF(IPC.EQ.2) GO TO 54	INDT0520
52 XMU=SP(2)	INDT0530
XJ2 = SP(3)	INDT0540
GO TO 8	INDT0550
54 RPO = SP(1)	INDT0560
REO = SP(2)	INDT0570
OMEGA=SP(3)	INDT0580
GO TO 8	INDT0590
60 DECODE(6,1006,B) IPC,NPTS	INDT0600
1006 FORMAT(12,I4)	INDT0610
GO TO(62,64,66),IPC	INDT0620
62 READ(IN,1031) (TXCG(I),XXCG(I),I=1,NPTS)	INDT0630
WRITE(OUT,1031)(TXCG(I),XXCG(I),I=1,NPTS)	INDT0640
1031 FORMAT(6E12.4)	INDT0650
N8(1)=NPTS	INDT0660
GO TO 8	INDT0670
64 READ(IN,1031) (TYCG(I),XYCG(I),I=1,NPTS)	INDT0680
WRITE(OUT,1031)(TYCG(I),XYCG(I),I=1,NPTS)	INDT0690
N9(1)=NPTS	INDT0700
GO TO 8	INDT0710
66 READ(IN,1031) (TZCG(I),XZCG(I),I=1,NPTS)	INDT0720
WRITE(OUT,1031)(TZCG(I),XZCG(I),I=1,NPTS)	INDT0730
N10(1)=NPTS	INDT0740
GO TO 8	INDT0750
70 DECODE(68,1007,B) IDN,SP(1),SP(2),SP(3),LT,MT,NT,SP(4),SP(5),SP(6)	INDT0760
1007 FORMAT(12,3E10.4,3I2,3E10.4)	INDT0770
NSTA=NSTA+1	INDT0780
NS(NSTA) = IDN	INDT0790
DTI(NSTA)=SP(1)	INDT0800
DTF(NSTA)=SP(2)	INDT0810
DFIT(NSTA)=SP(3)	INDT0820
MR(1,NSTA)=LT	INDT0830
MR(2,NSTA)=MT	INDT0840
MR(3,NSTA)=NT	INDT0850
SYG(1,NSTA)=SP(4)	INDT0860
SYG(2,NSTA)=SP(5)	INDT0870

SYG(3,NSTA)=SP(6)	INDT0880
GO TO 8	INDT0890
80 DECODE(6,1006,B) IPC,IDN	INDT0900
IF(IDN) 81,83,81	INDT0910
81 READ(IN,1032) KDATA	INDT0920
IF(KDATA.LE.0) GO TO 82	INDT0930
READ(IN,1032) (K,MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,3),	INDT0940
* I=1,KDATA)	INDT0950
WRITE(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT0960
X3),I=1,KDATA)	INDT0970
GO TO 81	INDT0980
1032 FORMAT(2I2,7E10.2)	INDT0990
82 CONTINUE	INDT1000
K = 0	INDT1010
WRITE(FIT)KDATA,K,K,K,K,K,K,K,K	INDT1020
REWIND FIT	INDT1030
83 IF(IPC) 84,8,84	INDT1040
84 READ(FIT) KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1,	INDT1050
X3),I=1,KDATA)	INDT1060
WRITE(OUT,1033)KDATA,(MTP(I),TYM(I), (DAT(J,I),J=1,3), (SIG(J,I),J=1	INDT1070
X,3),I=1,KDATA)	INDT1080
1033 FORMAT(2I4,7E16.7/(4X,I4,7E16.7))	INDT1090
IF(KDATA) 84,85,84	INDT1100
85 REWIND FIT	INDT1110
GO TO 8	INDT1120
90 DECODE(6,1006,B) IPC,IDN	INDT1130
IF(IDN) 91,93,91	INDT1140
91 READ(IN,1034) KDAP	INDT1150
IF(KDAP.LE.0) GO TO 92	INDT1160
READ(IN,1034) (K,TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1170
* KDAP)	INDT1180
WRITE(PQR)KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,	INDT1190
* KDAP)	INDT1200
GO TO 91	INDT1210
1034 FORMAT(I2,7E10.2)	INDT1220
92 CONTINUE	INDT1230
K = 0	INDT1240
WRITE(PQR) KDAP,K,K,K,K,K,K,K,K	INDT1250
REWIND PQR	INDT1260
93 IF(IPC) 94,8,94	INDT1270
94 READ(PQR) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=1,KDAP	INDT1280
X)	INDT1290
WRITE(OUT,1035) KDAP,(TT(I),TP(I),TQ(I),TR(I),AX(I),AY(I),AZ(I),I=	INDT1300
X1,KDAP)	INDT1310
1035 FORMAT(I4,7E16.7/(4X,7E16.7))	INDT1320
IF(KDAP) 94,95,94	INDT1330
95 REWIND PQR	INDT1340
GO TO 8	INDT1350
100 DECODE(6,1006,B) IPC,NPTS	INDT1360
NSTX = NST+NSTC	INDT1370
GO TO (101,102,103,104,106,108),IPC	INDT1380
101 READ(IN,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1390
WRITE(OUT,1031) ((P(I,J),J=1,NSTX),I=1,NSTX)	INDT1400
GO TO 8	INDT1410
102 READ(IN,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1420
WRITE(OUT,1031) ((CUZ(I,J),J=1,NPU),I=1,NSTX)	INDT1430
GO TO 8	INDT1440
103 READ(IN,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1450
WRITE(OUT,1031) ((CVZ(I,J),J=1,NPV),I=1,NSTX)	INDT1460
GO TO 8	INDT1470

104 DO 105 I=1,NPTS	INDT1480
READ(IN,1036) LT,MT,P(LT,MT)	INDT1490
P(MT,LT)=P(LT,MT)	INDT1500
1036 FORMAT(4X,2I4,E12.4)	INDT1510
105 WRITE(OUT,1037) LT,MT,P(LT,MT)	INDT1520
1037 FORMAT(10X,2HP(,I3,1H,I3,3H) =E15.8)	INDT1530
GO TO 8	INDT1540
106 DO 107 I=1,NPTS	INDT1550
READ(IN,1036) LT,MT,CUZ(LT,MT)	INDT1560
107 WRITE(OUT,1038) LT,MT,CUZ(LT,MT)	INDT1570
1038 FORMAT(8X,4HCUZ(,I3,1H,I3,3H) =E15.8)	INDT1580
GO TO 8	INDT1590
108 DO 109 I=1,NPTS	INDT1600
READ(IN,1036) LT,MT,CVZ(LT,MT)	INDT1610
109 WRITE(OUT,1039) LT,MT,CVZ(LT,MT)	INDT1620
1039 FORMAT(8X,4HCVZ(,I3,1H,I3,3H) =E15.8)	INDT1630
GO TO 8	INDT1640
110 GO TO 8	INDT1650
120 GO TO 8	INDT1660
130 GO TO 8	INDT1670
140 GO TO 8	INDT1680
150 GO TO 8	INDT1690
160 GO TO 8	INDT1700
170 GO TO 8	INDT1710
180 GO TO 8	INDT1720
190 GO TO 8	INDT1730
200 RETURN	INDT1740
END	INDT1750


```

SUBROUTINE INTAG
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDOUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5) ,D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBR5 ,JUST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROF ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
2 LRK = 4
6 CALL RKUTTA
IF(LRK-2) 8,10,99
8 CALL DATAB
CALL MOTION
IF(NPC(1)-1) 12,6,12
10 IF(DCOMP.GE.0..OR.NPC(10).EQ.0.OR.T.EQ.TSAV) GO TO 6
WRITE(STATE) T,X
TSAV=T
GO TO 6
12 CALL FXXU
DO 22 I=1,4
N = NSTX+NPU
DO 22 J=1,N
IF(J-10) 13,13,14
13 CONTINUE
SUM = 0.
SUM2= 0.
GO TO 15
14 SUM = F1(I,J)
SUM2= F3(I,J)
15 DO 16 K=1,10
16 SUM2 = SUM2 + F3(I,K)*PH(K,J)
DPH(I+6,J) = SUM2
IF(I.EQ.4) GO TO 22
DO 18 K=1,10
18 SUM = SUM + F1(I,K)*PH(K,J)

```

```
DPH(I,J) = SUM
SUM = 0.
DO 20 K=1,5
20 SUM = SUM + F2(I,K)*PH(K,J)
DPH(I+3,J) = SUM
22 CONTINUE
GO TO 6
99 RETURN
END
```

```
INT60280
INT60290
INT60300
INT60310
INT60320
INT60330
INT60340
INT60350
INT60360
```

```

SUBROUTINE MINVAR
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
G(1,10) = 0.
G(2,10) = 0.
G(3,10) = 0.
NT = 0
LT = 1
MT = NSTX
DO 1 I=1,NSTX
P(I,10) = 0.
1 P(10,I) = 0.
2 DO 12 J=KAR,KOB
DO 6 I=LT,MT
L = I+1
SUM = 0.
DO 3 K=LT,I
3 SUM = SUM + P(K,I)*G(J,K)
IF(L.GT.MT) GO TO 6
DO 4 K=L,MT
4 SUM = SUM+P(I,K)*G(J,K)
6 DUB(I,J) = SUM
C-----CALCULATE EQ.(54F) -----
DO 10 I=KAR,KOB
SUM = 0.
DO 8 K=LT,MT
8 SUM = SUM+G(I,K)*DUB(K,J)
10 DUB(I,J+6) = SUM
12 DUB(J,J+6) = DUB(J,J+6)+SI(J)**2
IF(NPV) 36,36,14

```

14 CONTINUE	MINV0280
DO 15 I=1,NPV	MINV0290
15 CVZ(10,I) = 0.	MINV0300
DO 20 J=KAR,KOB	MINV0310
DO 17 I=1,NSTX	MINV0320
SUM= 0.	MINV0330
DO 16 K=1,NPV	MINV0340
16 SUM= SUM+CVZ(I,K)*H(J,K)	MINV0350
DUB(I,J+3) = SUM	MINV0360
17 DUB(I,J) = DUB(I,J)+SUM	MINV0370
DO 18 I=1,NPV	MINV0380
18 DUB(I+12,J+6) = S(I)*H(J,I)	MINV0390
20 CONTINUE	MINV0400
DO 26 J=KAR,KOB	MINV0410
DO 24 I=KAR,KOB	MINV0420
SUM = 0.	MINV0430
SUM2= 0.	MINV0440
DO 22 K=LT,MT	MINV0450
22 SUM = SUM + DUB(K,J+3)*G(I,K)	MINV0460
DO 23 K=1,NPV	MINV0470
23 SUM2= SUM2+ H(I,K)*DUB(K+12,J+6)	MINV0480
DUB(J+3,I+6) = SUM	MINV0490
24 DUB(I+6,J+6) = SUM + SUM2	MINV0500
26 CONTINUE	MINV0510
DO 34 J=KAR,KOB	MINV0520
DO 28 I=KAR,KOB	MINV0530
28 DUB(I,J+6) = DUB(I,J+6) + DUB(I+3,J+6) + DUB(I+6,J+6)	MINV0540
DO 32 I=1,NPV	MINV0550
SUM = 0.	MINV0560
DO 30 K=LT,MT	MINV0570
30 SUM = SUM + G(J,K)*CVZ(K,I)	MINV0580
32 DUB(I,J+9) = SUM	MINV0590
34 CONTINUE	MINV0600
36 CONTINUE	MINV0610
IF(KAR-KOB) 37,46,37	MINV0620
37 CONTINUE	MINV0630
DO 39 J=KAR,KOB	MINV0640
DO 38 I=KAR,KOB	MINV0650
38 DUB(I+9,J+6) = 0.	MINV0660
39 DUB(J+9,J+6) = 1.	MINV0670
L = KOB-1	MINV0680
DO 42 I=KAR,L	MINV0690
M = I+1	MINV0700
SUM = DUB(I,I+6)	MINV0710
DO 42 J=KAR,KOB	MINV0720
DUB(I ,J+6) = DUB(I ,J+6)/SUM	MINV0730
DUB(I+9,J+6) = DUB(I+9,J+6)/SUM	MINV0740
DO 42 K=M,KOB	MINV0750
IF(I-J) 40,41,40	MINV0760
40 DUB(K ,J+6) = DUB(K ,J+6)-DUB(K,I+6)*DUB(I ,J+6)	MINV0770
41 DUB(K+9,J+6) = DUB(K+9,J+6)-DUB(K,I+6)*DUB(I+9,J+6)	MINV0780
42 CONTINUE	MINV0790
DO 44 I=KAR,KOB	MINV0800
44 DUB(KOB+9,I+6) = DUB(KOB+9,I+6)/DUB(KOB,KOB+6)	MINV0810
DO 45 I=KAR,L	MINV0820
M = KOB+KAR+6-I	MINV0830
DO 45 J=I,L	MINV0840
N = KOB+KAR+8-J	MINV0850
DO 45 K=KAR,KOB	MINV0860
45 DUB(N,K+6) = DUB(N,K+6)-DUB(N-9 ,M)*DUB(M+3,K+6)	MINV0870

GO TO 48	MINV0880
46 DUB(KAR+9,KAR+6) = 1./DUB(KAR,KAR+6)	MINV0890
48 CONTINUE	MINV0900
C-----CALCULATE EQ.(54E) -----	MINV0910
DO 54 I=1,NSTX	MINV0920
DO 51 J=KAR,KOB	MINV0930
SUM = 0.	MINV0940
DO 50 K=KAR,KOB	MINV0950
50 SUM = SUM + DUB(I,K)*DUB(K+9,J+6)	MINV0960
51 DUB(I,J+12) = SUM	MINV0970
DO 54 L=I,NSTX	MINV0980
SUM = 0.	MINV0990
C-----CALCULATE EQ.(54B) -----	MINV1000
DO 52 K=KAR,KOB	MINV1010
52 SUM = SUM + DUB(I,K+12)*DUB(L,K)	MINV1020
P(I,L) = P(I,L) - SUM	MINV1030
54 CONTINUE	MINV1040
IF(NPU) 66,66,56	MINV1050
C-----CALCULATE EQ.(54C) -----	MINV1060
56 CONTINUE	MINV1070
DO 57 I=1,NPU	MINV1080
57 CUZ(10,I) = 0.	MINV1090
DO 64 J=1,NPU	MINV1100
DO 60 I=KAR,KOB	MINV1110
SUM = 0.	MINV1120
DO 58 K=1,NSTX	MINV1130
58 SUM = SUM + G(I,K)*CUZ(K,J)	MINV1140
60 DUB(I,1) = SUM	MINV1150
DO 64 I=1,NSTX	MINV1160
SUM = 0.	MINV1170
DO 62 K=KAR,KOB	MINV1180
62 SUM = SUM + DUB(I,K+12)*DUB(K,1)	MINV1190
64 CUZ(I,J) = CUZ(I,J)-SUM	MINV1200
66 IF(NPV) 72,72,67	MINV1210
C-----CALCULATE EQ.(54D) -----	MINV1220
67 DO 70 I=1,NSTX	MINV1230
DO 70 J=1,NPV	MINV1240
SUM = 0.	MINV1250
DO 68 K=KAR,KOB	MINV1260
68 SUM = SUM + DUB(I,K+12)*(DUB(J,K+9)+DUB(J+12,K+6))	MINV1270
70 CVZ(I,J) = CVZ(I,J) - SUM	MINV1280
72 IF(NPC(1)-2) 74,108,74	MINV1290
74 IF(NPC(4)) 75,88,75	MINV1300
75 DO 82 I=1,NSTX	MINV1310
80 DUB(I,1) = DZ(I)	MINV1320
82 CONTINUE	MINV1330
C-----CALCULATE EQ.(54A) -----	MINV1340
DO 86 I=KAR,KOB	MINV1350
SUM = 0.	MINV1360
DO 84 J=1,NSTX	MINV1370
84 SUM = SUM + G(I,J)*DUB(J,1)	MINV1380
86 DATC(1) = DATC(1)+SUM	MINV1390
88 DO 90 I=KAR,KOB	MINV1400
J = LC(I)	MINV1410
DUB(I,2) = DATA(J)-DATC(I)	MINV1420
IF(MTYP.GT.5) GO TO 90	MINV1430
IF(J.EQ.1) GO TO 90	MINV1440
IF(ABS(DUB(I,2)).LT.3.1416) GO TO 90	MINV1450
DUB(I,2) = DUB(I,2)-SIGN(6.283185307179586,DUB(I,2))	MINV1460
90 CONTINUE	MINV1470

DO 92 I=1,NSTX	MINV1480
DZ(I) = 0.	MINV1490
DO 92 J=KAR,KCB	MINV1500
92 DZ(I) = DZ(I)+DUB(I,J+12)*DUB(J,2)	MINV1510
IF(NPC(4)) 294,298,294	MINV1520
294 DO 296 I=1,4	MINV1530
296 V0(I) = X(I+6) + DUB(I+6,1)	MINV1540
DZ(10) = -(V0(1)*DZ(7)+V0(2)*DZ(8)+V0(3)*DZ(9))/V0(4)	MINV1550
94 DO 96 I=1,NSTX	MINV1560
96 DZ(I) = DZ(I)+DUB(I,1)	MINV1570
GO TO 108	MINV1580
298 DZ(10) = -(X(7)*DZ(7)+X(8)*DZ(8)+X(9)*DZ(9))/X(10)	MINV1590
98 DO 100 I=1,10	MINV1600
100 X(I) = X(I)+DZ(I)	MINV1610
DATC(1)= SQRT(X(7)**2 + X(8)**2 + X(9)**2 + X(10)**2)	MINV1620
X(7) = X(7)/DATC(1)	MINV1630
X(8) = X(8)/DATC(1)	MINV1640
X(9) = X(9)/DATC(1)	MINV1650
X(10)=X(10)/DATC(1)	MINV1660
IF(NSTC.EQ.0) GO TO 103	MINV1670
DO 102 I=1,NSTC	MINV1680
J = NC(I)	MINV1690
102 C(J) = C(J)+DZ(I+10)	MINV1700
103 CONTINUE	MINV1710
IF(KSS) 108,108,104	MINV1720
104 DO 106 I=1,KSS	MINV1730
MTYP = NSS(I)	MINV1740
106 CALL STAT	MINV1750
108 P(8,7) = P(7,8)	MINV1760
P(9,7) = P(7,9)	MINV1770
P(9,8) = P(8,9)	MINV1780
DO 110 I=1,9	MINV1790
SUM = P(I,7)*X(7) + P(I,8)*X(8) + P(I,9)*X(9)	MINV1800
110 P(I,10) =-SUM/X(10)	MINV1810
P(10,10) = -(X(7)*P(7,10)+X(8)*P(8,10)+X(9)*P(9,10))/X(10)	MINV1820
DO 114 I=11,NSTX	MINV1830
SUM = P(7,I)*X(7) + P(8,I)*X(8) + P(9,I)*X(9)	MINV1840
114 P(10,I) =-SUM/X(10)	MINV1850
IF(NPU.EQ.0) GO TO 117	MINV1860
115 DO 116 I=1,NPU	MINV1870
SUM = CUZ(7,I)*X(7) + CUZ(8,I)*X(8) + CUZ(9,I)*X(9)	MINV1880
116 CUZ(10,I) =-SUM/X(10)	MINV1890
117 IF(NPV.EQ.0) GO TO 99	MINV1900
DO 118 I=1,NPV	MINV1910
SUM = CVZ(7,I)*X(7) + CVZ(8,I)*X(8) + CVZ(9,I)*X(9)	MINV1920
118 CVZ(10,I) =-SUM/X(10)	MINV1930
99 CONTINUE	MINV1940
RETURN	MINV1950
END	MINV1960

```

SUBROUTINE MOTION
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,I1 ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
LT = 0
1 CONTINUE
CPH = COS(X(5))
SPH = SIN(X(5))
TPH = SPH/CPH
R = REO + X(4)
C-----CALCULATE EQ.(159) -----
AP(1) = C(61)*AM(1)+C(62)*AM(2)+C(63)*AM(3)+C(70)
AP(2) = C(64)*AM(1)+C(65)*AM(2)+C(66)*AM(3)+C(71)
AP(3) = C(67)*AM(1)+C(68)*AM(2)+C(69)*AM(3)+C(72)
C-----CALCULATE EQ.(155) -----
AP(4) = SQRT(AP(1)**2+ AP(3)**2)
IF(AP(4)) 9,9,7
7 CONTINUE
AP(4) = 2.*AP(1)*AP(3)/AP(4)
9 CONTINUE
C-----CALCULATE EQ.(154) -----
DO 11 I=1,3
J = 3*I
PA(I)=C(J+33)*PM(1)+C(J+34)*PM(2)+C(J+35)*PM(3)+C(I+44)+C(I+47)*
X AP(1) + C(I+50)*AP(2) + C(I+53)*AP(3) + C(I+56)*AP(4)
11 CONTINUE
C-----CALCULATE EQ.(153) -----
XP(1) = CGM(1) + C(31)
XP(2) = CGM(2) + C(32)
XP(3) = CGM(3) + C(33)
I=N11(2)

```

```

IF(N11(2)-1)10,10,12
10 I = 2
12 CONTINUE
SP(1)= TT(I+1)-TT(I-1)
HI(2)= .5*SP(1)
HI(1)= T + HI(2)
HI(2)= T - HI(2)
PMDOT(1)= (TAB(HI(1),N11(1),TT(1),TP(1))-TAB(HI(2),N11(1),TT(1),TP(1)))/SP(1)
PMDOT(2)= (TAB(HI(1),N11(1),TT(1),TQ(1))-TAB(HI(2),N11(1),TT(1),TQ(1)))/SP(1)
PMDOT(3)= (TAB(HI(1),N11(1),TT(1),TR(1))-TAB(HI(2),N11(1),TT(1),TR(1)))/SP(1)
AMDOT(1)= (TAB(HI(1),N11(1),TT(1),AX(1))-TAB(HI(2),N11(1),TT(1),AX(1)))/SP(1)
AMDOT(2)= (TAB(HI(1),N11(1),TT(1),AY(1))-TAB(HI(2),N11(1),TT(1),AY(1)))/SP(1)
AMDOT(3)= (TAB(HI(1),N11(1),TT(1),AZ(1))-TAB(HI(2),N11(1),TT(1),AZ(1)))/SP(1)
C-----CALCULATE EQ.(158) -----
APDOT(1)= C(61)*AMDOT(1) + C(62)*AMDOT(2) + C(63)*AMDOT(3)
APDOT(2)= C(64)*AMDOT(1) + C(65)*AMDOT(2) + C(66)*AMDOT(3)
APDOT(3)= C(67)*AMDOT(1) + C(68)*AMDOT(2) + C(69)*AMDOT(3)
C-----CALCULATE EQ.(157) -----
APDOT(4)= (APDOT(1)*((1.-(AP(4)/(2.*AP(3)))**2)/AP(1))
X + APDOT(3)*((1.-(AP(4)/(2.*AP(1)))**2)/AP(3)))*AP(4)
C-----CALCULATE EQ.(156) -----
13 DO 14 I=1,3
J = 3*I
PDOT(I) = C(J+33)*PMDOT(1) + C(J+34)*PMDOT(2) + C(J+35)*PMDOT(3)
X + C(I+47)*APDOT(1) + C(I+50)*APDOT(2) + C(I+53)*APDOT(3)
Y + C(I+56)*APDOT(4)
14 CONTINUE
C-----CALCULATE EQ.(146) -----
SP(1) = PA(1)**2
SP(2) = PA(2)**2
SP(3) = PA(3)**2
TRAN(1,1)=-SP(2)-SP(3)
TRAN(1,2)= PA(1)*PA(2)-PDOT(3)
TRAN(1,3)= PA(1)*PA(3)+PDOT(2)
TRAN(2,1)= PA(1)*PA(2)+PDOT(3)
TRAN(2,2)=-SP(1)-SP(3)
TRAN(2,3)= PA(2)*PA(3)-PDOT(1)
TRAN(3,1)= PA(1)*PA(3)-PDOT(2)
TRAN(3,2)= PA(2)*PA(3)+PDOT(1)
TRAN(3,3)=-SP(1)-SP(2)
AB(1) = AP(1)-TRAN(1,1)*XP(1)-TRAN(1,2)*XP(2)-TRAN(1,3)*XP(3)
AB(2) = AP(2)-TRAN(2,1)*XP(1)-TRAN(2,2)*XP(2)-TRAN(2,3)*XP(3)
AB(3) = AP(3)-TRAN(3,1)*XP(1)-TRAN(3,2)*XP(2)-TRAN(3,3)*XP(3)
C-----CALCULATE EQ.(133) -----
SP(1) = (X( 7)-X( 8))*(X( 7)+X( 8))
SP(2) = (X( 9)-X(10))*(X( 9)+X(10))
A(1,1) = (X( 7)-X( 9))*(X( 7)+X( 9)) + (X( 8)-X(10))*(X( 8)+X(10))
A(2,2) = SP(1) + SP(2)
A(3,3) = SP(1) - SP(2)
A(1,2) = 2.*(X( 8)*X( 9)+X( 7)*X(10))
A(2,1) = 2.*(X( 8)*X( 9)-X( 7)*X(10))
A(1,3) = 2.*(X( 8)*X(10)-X( 7)*X( 9))
A(3,1) = 2.*(X( 8)*X(10)+X( 7)*X( 9))
A(3,2) = 2.*(X(10)*X( 9)-X( 7)*X( 8))

```


A(2,3) = 2.*(X(10)*X(9)+X(7)*X(8))	MOTN0880
IF(LT) 15,15,99	MOTN0890
15 CONTINUE	MOTN0900
C-----CALCULATE EQ.(132) -----	MOTN0910
AG(1) = AB(1)*A(1,1)+AB(2)*A(2,1)+AB(3)*A(3,1)	MOTN0920
AG(2) = AB(1)*A(1,2)+AB(2)*A(2,2)+AB(3)*A(3,2)	MOTN0930
AG(3) = AB(1)*A(1,3)+AB(2)*A(2,3)+AB(3)*A(3,3)	MOTN0940
C PARAMETERS USED FREQUENTLY IN REMAINING SUBROUTINES	MOTN0950
PAR(1) = X(1)*X(1) + X(2)*X(2)	MOTN0960
PAR(2)=XMU/R**2	MOTN0970
PAR(3)=XMUJ/R**4	MOTN0980
PAR(4) = 1./(2.*R)	MOTN0990
PAR(5) = X(1)*X(3)-X(2)*X(2)*TPH	MOTN1000
PAR(6) = 1. - 1.5*CPH*CPH	MOTN1010
F1(2,2)= (X(1)*TPH+X(3))/R	MOTN1020
F1(2,3)= X(2)/R	MOTN1030
F1(2,1)= F1(2,3)*TPH	MOTN1040
DX(5) = X(1)/R	MOTN1050
F3(1,8) =-.5*(PA(1)-F1(2,3))	MOTN1060
F3(1,9) =-.5*(PA(2)+DX(5))	MOTN1070
F3(1,10)=-.5*(PA(3)+F1(2,1))	MOTN1080
F3(2,9) = F3(1,10) + PA(3)	MOTN1090
F3(2,10)= F3(1,9) + DX(5)	MOTN1100
F3(3,10)= F3(1,8) + PA(1)	MOTN1110
C-----CALCULATE EQ.(127) -----	MOTN1120
DX(1) = AG(1) + PAR(5)/R - PAR(3)*SPH*CPH	MOTN1130
DX(2) = AG(2) + X(2)*F1(2,2)	MOTN1140
DX(3) = AG(3) + PAR(2) - PAR(1)/R - PAR(3)*PAR(6)	MOTN1150
C-----CALCULATE EQ.(128) -----	MOTN1160
DX(4) = -X(3)	MOTN1170
DX(6) = F1(2,3)/CPH - OMEGA	MOTN1180
C-----CALCULATE EQ.(129) -----	MOTN1190
DX(7) = X(8)*F3(1, 8) + X(9)*F3(1, 9) + X(10)*F3(1,10)	MOTN1200
DX(8) =-X(7)*F3(1, 8) + X(9)*F3(2, 9) + X(10)*F3(2,10)	MOTN1210
DX(9) =-X(7)*F3(1, 9) - X(8)*F3(2, 9) + X(10)*F3(3,10)	MOTN1220
DX(10) =-X(7)*F3(1,10) - X(8)*F3(2,10) - X(9)*F3(3,10)	MOTN1230
99 RETURN	MOTN1240
ENTRY AUXIL	MOTN1250
LT = 1	MOTN1260
GO TO 1	MOTN1270
END	MOTN1280

```

SUBROUTINE OBSERV
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KG ,KI ,KK
6 ,KN ,KOB ,KPROP ,KS ,KSM ,KSS ,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
DIMENSION CTM(6) ,RCC(3) ,RCDC(3) ,RCDX(3,6),RCX(3,6) ,
A XA(5) ,XAX(5,7) ,XC(3) ,XCX(3,7) ,XLB(3) ,XLG(3) ,
B XLGE(3,4),XLGX(2,4),XS(3) ,XSC(3) ,XSD(3) ,XSDC(3) ,
C XSDX(3,6),XSX(3,3) ,CI(3,3) ,CJ(3,3)
EQUIVALENCE (DPH(1,1) ,CTM(1) ) , (DPH(7,1) ,RCC(1) ) ,
N (DPH(10,1),RCDC(1) ) , (DPH(3,2) ,RCDX(1,1)) ,
O (DPH(1,4) ,RCX(1,1) ) , (DPH(9,5) ,XA(1) ) ,
P (DPH(4,6) ,XAX(1,1) ) , (DPH(9,9) ,XC(1) ) ,
Q (DPH(2,10),XCX(1,1) ) , (DPH(3,12),XLB(1) ) ,
R (DPH(6,12),XLG(1) ) , (DPH(9,12),XLGE(1,1)) ,
S (DPH(1,14),XLGX(1,1)) , (DPH(9,14),XS(1) ) ,
T (DPH(2,15),XSC(1) ) , (DPH(5,15),XSD(1) ) ,
U (DPH(8,15),XSDC(1) ) , (DPH(1,16),XSDX(1,1)) ,
V (DPH(9,17),XSX(1,1) ) , (DPH(8,18),CI(1,1) ) ,
W (DPH(7,19),CJ(1,1) ) , (DPH(6,20),CAZC ) ,
X (DPH(7,20),CDP ) , (DPH(8,20),COY ) ,
Y (DPH(9,20),CELC ) , (DPH(10,20),CGR ) ,
Z (DPH(1,21),CLR ) , (DPH(2,21),CTH ) ,
1 (DPH(3,21),SAZC ) , (DPH(4,21),SDP ) ,
2 (DPH(5,21),SDY ) , (DPH(6,21),SELC ) ,
3 (DPH(7,21),SGR ) , (DPH(8,21),SLR ) ,
4 (DPH(9,21),STH ) , (DPH(10,21),THETA )
IF(L1-2) 14,10,14
10 IF(NPC(5)) 14,12,14
12 WRITE(OUT,1000)
1000 FORMAT(5X,6HPOINTS,5X,4HTYPE,4X,4HTIME,8X,5HCOMP1,10X,5HCOMP2,10X,5HCOMP3,10X,4HSIG1,11X,4HSIG2,11X,4HSIG3)

```

L1=1	OBSV0280
14 IF(MTYP-6) 16,150,15	OBSV0290
15 IF(MTYP-8) 115,120,125	OBSV0300
16 N = 60+MTYP*15	OBSV0310
C-----CALCULATE EQ.(236) -----	OBSV0320
100 THETA=X(6)-C(N+14)	OBSV0330
STH=SIN(THETA)	OBSV0340
CTH=COS(THETA)	OBSV0350
VO(1)= CPH*CPHDT(MTYP)	OBSV0360
VO(2)= CPH*SPHDT(MTYP)	OBSV0370
VO(3)= SPH*CPHDT(MTYP)	OBSV0380
VO(4)= SPH*SPHDT(MTYP)	OBSV0390
SP(1) = ROT(MTYP) + C(N+15)	OBSV0400
VO(5) = SP(1)*CCAPH(MTYP)	OBSV0410
VO(6) = SP(1)*SCAPH(MTYP)	OBSV0420
C-----CALCULATE EQ.(235) -----	OBSV0430
102 XS(1)= R*(CTH*VO(1)+VO(4))-VO(5)	OBSV0440
XS(2)= R*STH*CPH	OBSV0450
XS(3)= -R*(CTH*VO(2)-VO(3))+VO(6)	OBSV0460
VO(8)= SQRT(XS(2)**2+XS(3)**2)	OBSV0470
VO(9)= VO(8)**2	OBSV0480
C-----CALCULATE EQ.(238A)-----	OBSV0490
CTM(1)= SQRT(XS(1)**2+VO(9))	OBSV0500
C-----CALCULATE EQ.(238B)-----	OBSV0510
SAZC= XS(2)/VO(8)	OBSV0520
CAZC= XS(3)/VO(8)	OBSV0530
C-----CALCULATE EQ.(238C)-----	OBSV0540
SELC= XS(1)/CTM(1)	OBSV0550
CELC= VO(8)/CTM(1)	OBSV0560
CTM(2)= ATAN2(XS(2),XS(3))	OBSV0570
CTM(3)= ATAN2(XS(1),VO(8))	OBSV0580
C-----CALCULATE EQ.(239) -----	OBSV0590
DFM(1)= C(N+1)*CTM(1)+C(N+4)+C(N+10)/SELC	OBSV0600
DFM(2)= C(N+2)*CTM(2)+C(N+5)	OBSV0610
DFM(3)= C(N+3)*CTM(3)+C(N+6)+C(N+11)*CELC/SELC	OBSV0620
IF(MO(MTYP)) 106,104,106	OBSV0630
104 IF(NPC(1)-1) 106,18,106	OBSV0640
C-----CALCULATE EQ.(246) -----	OBSV0650
106 XSX(1,1)= (XS(1)+VO(5))/R	OBSV0660
XSX(1,2)= R*(VO(2)-CTH*VO(3))	OBSV0670
XSX(1,3)= -XS(2)*CPHDT(MTYP)	OBSV0680
XSX(2,1)= XS(2)/R	OBSV0690
XSX(2,2)= -R*STH*SPH	OBSV0700
XSX(2,3)= R*CTH*CPH	OBSV0710
XSX(3,1)= (XS(3)-VO(6))/R	OBSV0720
XSX(3,2)= R*(CTH*VO(4)+VO(1))	OBSV0730
XSX(3,3)= XS(2)*SPHDT(MTYP)	OBSV0740
IF(MO(MTYP)) 108,18,108	OBSV0750
C-----CALCULATE EQ.(241) -----	OBSV0760
108 DO 112 I=1,3	OBSV0770
SUM=0.	OBSV0780
DO 110 J=1,3	OBSV0790
110 SUM=SUM+XSX(I,J)*DX(J+3)	OBSV0800
112 XSD(I)=SUM	OBSV0810
C-----CALCULATE EQ.(240) -----	OBSV0820
CTM(4)= (XS(1)*XSD(1)+XS(2)*XSD(2)+XS(3)*XSD(3))/CTM(1)	OBSV0830
CTM(5)= (XS(3)*XSD(2)-XS(2)*XSD(3))/VO(9)	OBSV0840
CTM(6)= (CTM(1)*XSD(1)-XS(1)*CTM(4))/(CTM(1)*VO(8))	OBSV0850
DFM(1)= DFM(1)+C(N+7)*CTM(4)	OBSV0860
DFM(2)= DFM(2)+C(N+8)*CTM(5)	OBSV0870

DFM(3)= DFM(3)+C(N+9)*CTM(6)	OBSV0880
GO TO 18	OBSV0890
115 DFM(1)= X(1)	OBSV0900
DFM(2)= X(2)	OBSV0910
DFM(3)= X(3)	OBSV0920
GO TO 18	OBSV0930
120 DFM(1)= X(4)	OBSV0940
DFM(2)= X(5)	OBSV0950
DFM(3)= X(6)	OBSV0960
GO TO 18	OBSV0970
125 WRITE(OUT,5000) MTYP	OBSV0980
5000 FORMAT(35H ILLIGITIMATE MTYP IN OBSERV, MTYP=I3)	OBSV0990
CALL EXIT	OBSV1000
C 150 CALCULATE AMR	OBSV1010
150 SDP= SIN(C(151))	OBSV1020
CDP= COS(C(151))	OBSV1030
SDY= SIN(C(152))	OBSV1040
CDY= COS(C(152))	OBSV1050
C-----CALCULATE EQ.(269) -----	OBSV1060
XLB(1)= CDY*CDP	OBSV1070
XLB(2)= SDY	OBSV1080
XLB(3)= CDY*SDP	OBSV1090
C-----CALCULATE EQ.(270) -----	OBSV1100
DO 152 I=1,3	OBSV1110
XLG(I)=0.	OBSV1120
DO 152 J=1,3	OBSV1130
152 XLG(I)=XLG(I)+A(J,I)*XLB(J)	OBSV1140
VO(1)= REO**2	OBSV1150
C-----CALCULATE EQ.(271A)-----	OBSV1160
VO(2)= ATAN2(XLG(2),XLG(1))	OBSV1170
C-----CALCULATE EQ.(271B)-----	OBSV1180
SP(1)= SQRT(XLG(1)**2+XLG(2)**2)	OBSV1190
VO(3)=-ATAN2(XLG(3),SP(1))	OBSV1200
SLR= SIN(VO(2))	OBSV1210
CLR= COS(VO(2))	OBSV1220
SGR= SIN(VO(3))	OBSV1230
CGR= COS(VO(3))	OBSV1240
C-----CALCULATE EQ.(277) -----	OBSV1250
XA(1)= SLR*CGR	OBSV1260
XA(2)= R*CPH	OBSV1270
XA(3)= CPH*SGR-SPH*CLR*CGR	OBSV1280
XA(4)= R*SPH	OBSV1290
XA(5)= SPH*SGR+CPH*CLR*CGR	OBSV1300
C-----CALCULATE EQ.(276) -----	OBSV1310
XC(1)= XA(1)**2 + XA(3)**2 + RERP2*XA(5)**2	OBSV1320
XC(2)= 2.*(XA(2)*XA(3)+ RERP2*XA(4)*XA(5))	OBSV1330
XC(3)= XA(2)**2 + RERP2*XA(4)**2 - VO(1)	OBSV1340
SP(2)= XC(2)**2 - 4.*XC(1)*XC(3)	OBSV1350
IF(SP(2)) 154,156,156	OBSV1360
154 WRITE(OUT,5022)	OBSV1370
5022 FORMAT(49H IMAGINARY OR NEGATIVE SOLUTION ON AIRBORNE RADAR)	OBSV1380
DO 160 I=1,3	OBSV1390
DFM(I)= 0.	OBSV1400
DO 158 J=1,NSTX	OBSV1410
158 G(I,J)= 0.	OBSV1420
DO 160 J=1,NPV	OBSV1430
H(I,J)= 0.	OBSV1440
160 CONTINUE	OBSV1450
SI(1)=1.E20	OBSV1460
GO TO 99	OBSV1470

C-----CALCULATE EQ.(273) -----		
156	DFM(1) = -.5*(XC(2)+SQRT(SP(2)))/XC(1)	OBSV1480
	IF(DFM(1).LT.0.) GO TO 154	OBSV1490
	DFM(2) = 0.	OBSV1500
	DFM(3) = 0.	OBSV1510
18	IF(DCOMP.LT.0.) GO TO 80	OBSV1520
	DO 20 I=1,3	OBSV1530
	SP(I) = SYG(I,MTYP)	OBSV1540
	IF(NPC(1).EQ.0) SP(I) = SP(I)+SIGM(I)	OBSV1550
20	KC(I)=0	OBSV1560
	IF(KN) 22,22,24	OBSV1570
22	KOB=KAR	OBSV1580
	GO TO 26	OBSV1590
24	KOB=JNBR	OBSV1600
26	DO 28 I=KAR,KOB	OBSV1610
	J=LC(I)	OBSV1620
	DATC(I)=DFM(J)	OBSV1630
	SI(I)=SP(J)	OBSV1640
	NCOUNT=NCOUNT+1	OBSV1650
28	KC(J) = NCOUNT	OBSV1660
30	IF(NPC(5)) 34,32,34	OBSV1670
32	CONTINUE	OBSV1680
	WRITE(OUT,1002) (KC(I),I=1,3),MTYP,TO:(DFM(I),I=1,3),(SP(I),I=1,3)	OBSV1690
1002	FORMAT(1X,I4,1H,I4,1H,I4,2X,I2,1X,F10.4,F15.2,5F15.6)	OBSV1700
34	DO 36 I=1,NSTX	OBSV1710
	DO 36 J=KAR,KOB	OBSV1720
36	G(J,I)=0.	OBSV1730
	IF(MTYP-6) 200,250,270	OBSV1740
C 200	CALCULATE G(1-10) FOR R,A,E	OBSV1750
C-----	CALCULATE EQ.(244) -----	OBSV1760
200	DO 202 I=1,3	OBSV1770
	RCX(1,I) = (XSX(1,I)*XS(1)+XSX(2,I)*XS(2)+XSX(3,I)*XS(3))/CTM(1)	OBSV1780
	RCX(2,I) = (XSX(2,I)*XS(3)-XSX(3,I)*XS(2))/VO(9)	OBSV1790
202	RCX(3,I) = (XSX(1,I)-RCX(1,I)*SELC)/VO(8)	OBSV1800
	IF(MO(MTYP)) 204,218,204	OBSV1810
204	SP(1) = R*CPH	OBSV1820
	SP(2) = DX(5)/R	OBSV1830
	SP(3) = X(2)/(R*SP(1))	OBSV1840
	SP(4) = X(2)*TPH/SP(1)	OBSV1850
C-----	CALCULATE EQ.(247) -----	OBSV1860
	DO 206 I=1,3	OBSV1870
	XSDX(I,1) = XSX(I,2)/R	OBSV1880
	XSDX(I,2) = XSX(I,3)/SP(1)	OBSV1890
	XSDX(I,3) = -XSX(I,1)	OBSV1900
	XSDX(I,4) = -XSX(I,2)*SP(2)-XSX(I,3)*SP(3)	OBSV1910
206	XSDX(I,5) = XSX(I,3)*SP(4)	OBSV1920
	VO(10) = -X(3)/R	OBSV1930
	SP(4) = DX(6)/R	OBSV1940
	SP(5) = DX(5)/R	OBSV1950
	SP(6) = -TPH*DX(6)	OBSV1960
	SP(7) = -R*DX(5)	OBSV1970
	SP(1) = CTH*DX(6)/STH - TPH*DX(5)	OBSV1980
	SP(3) = SP(1)	OBSV1990
	SP(2) = -STH*DX(6)/CTH - TPH*DX(5)	OBSV2000
	DO 208 I=1,3	OBSV2010
	XSDX(I,4) = XSDX(I,4)+XSX(I,3)*SP(4)+XSX(I,2)*SP(5)	OBSV2020
	XSDX(I,5) = XSDX(I,5)+XSX(I,2)*VO(10)+XSX(I,3)*SP(6)+XSX(I,1)*SP(7)	OBSV2030
208	XSDX(I,6) = XSX(I,3)*VO(10)+XSX(I,3)*SP(1)	OBSV2040
	VO(11) = -(XSD(3)+2.*CTM(5)*XS(2))	OBSV2050
	VO(12) = XSD(2)-2.*CTM(5)*XS(3)	OBSV2060
		OBSV2070

SP(1)= -CTM(6)*XS(2)/CELC	OBSV2080
SP(2)= -CTM(6)*XS(3)/CELC	OBSV2090
SP(3)= XSD(1)-CTM(6)*VO(8)	OBSV2100
C-----CALCULATE EQ.(245) -----	OBSV2110
DO 216 I=1,6	OBSV2120
IF(I-3) 210,210,212	OBSV2130
210 RCDX(1,I)=0.	OBSV2140
RCDX(2,I)=0.	OBSV2150
RCDX(3,I)=0.	OBSV2160
GO TO 214	OBSV2170
212 RCDX(1,I)=XSX(1,I-3)*XSD(1)+XSX(2,I-3)*XSD(2)+XSX(3,I-3)*XSD(3)	OBSV2180
X -RCX(1,I-3)*CTM(4)	OBSV2190
RCDX(2,I)=XSX(3,I-3)*VO(12)+XSX(2,I-3)*VO(11)	OBSV2200
RCDX(3,I)=-XSX(1,I-3)*CTM(4)+XSX(2,I-3)*SP(1)+XSX(3,I-3)*SP(2)	OBSV2210
X +RCX(1,I-3)*SP(3)	OBSV2220
214 RCDX(1,I)=(RCDX(1,I)+XSDX(1,I)*XS(1)+XSDX(2,I)*XS(2)	OBSV2230
X +XSDX(3,I)*XS(3))/CTM(1)	OBSV2240
RCDX(2,I)=(RCDX(2,I)+XSDX(2,I)*XS(3)-XSDX(3,I)*XS(2))/VO(9)	OBSV2250
216 RCDX(3,I)=((RCDX(3,I)-RCDX(1,I)*XS(1))/CTM(1)+XSDX(1,I))/VO(8)	OBSV2260
218 VO(13)= C(N+10)*CELC/SELC**2	OBSV2270
VO(14)= C(N+3)-C(N+11)/SELC**2	OBSV2280
DO 230 I=1,6	OBSV2290
IF(I-3) 220,220,222	OBSV2300
220 GG(1)=0.	OBSV2310
GG(2)=0.	OBSV2320
GG(3)=0.	OBSV2330
GO TO 224	OBSV2340
C-----CALCULATE EQ.(243) -----	OBSV2350
222 GG(1)= C(N+1)*RCX(1,I-3)-VO(13)*RCX(3,I-3)	OBSV2360
GG(2)= C(N+2)*RCX(2,I-3)	OBSV2370
GG(3)= VO(14)*RCX(3,I-3)	OBSV2380
224 IF(MO(MTYP)) 226,228,226	OBSV2390
226 GG(1)= GG(1)+ C(N+7)*RCDX(1,I)	OBSV2400
GG(2)= GG(2)+ C(N+8)*RCDX(2,I)	OBSV2410
GG(3)= GG(3)+ C(N+9)*RCDX(3,I)	OBSV2420
228 DO 230 K=KAR,KOB	OBSV2430
J=LC(K)	OBSV2440
230 G(K,I)=GG(J)	OBSV2450
232 CONTINUE	OBSV2460
GO TO 36	OBSV2470
C-----CALCULATE EQ.(286) -----	OBSV2480
250 XLGE(1,1)= 2.*(X(7)*XLB(1)-X(10)*XLB(2)+X(9)*XLB(3))	OBSV2490
XLGE(1,2)= 2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2500
XLGE(1,3)= 2.*(-X(9)*XLB(1)+X(8)*XLB(2)+X(7)*XLB(3))	OBSV2510
XLGE(1,4)= 2.*(-X(10)*XLB(1)-X(7)*XLB(2)+X(8)*XLB(3))	OBSV2520
XLGE(2,1)= 2.*(X(10)*XLB(1)+X(7)*XLB(2)-X(8)*XLB(3))	OBSV2530
XLGE(2,2)= 2.*(X(9)*XLB(1)-X(8)*XLB(2)-X(7)*XLB(3))	OBSV2540
XLGE(2,3)= 2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2550
XLGE(2,4)= 2.*(X(7)*XLB(1)-X(10)*XLB(2)+X(9)*XLB(3))	OBSV2560
XLGE(3,1)= 2.*(-X(9)*XLB(1)+X(8)*XLB(2)+X(7)*XLB(3))	OBSV2570
XLGE(3,2)= 2.*(X(10)*XLB(1)+X(7)*XLB(2)-X(8)*XLB(3))	OBSV2580
XLGE(3,3)= 2.*(-X(7)*XLB(1)+X(10)*XLB(2)-X(9)*XLB(3))	OBSV2590
XLGE(3,4)= 2.*(X(8)*XLB(1)+X(9)*XLB(2)+X(10)*XLB(3))	OBSV2600
SP(4)= SGR/CGR	OBSV2610
SP(3)= XLG(1)**2 + XLG(2)**2	OBSV2620
SP(1)= SQRT(SP(3))	OBSV2630
DO 258 I=1,4	OBSV2640
C-----CALCULATE EQ.(284) -----	OBSV2650
XLGX(1,I) = (XLG(1)*XLGE(2,I)-XLG(2)*XLGE(1,I))/SP(3)	OBSV2660
C-----CALCULATE EQ.(285) -----	OBSV2670

```

258 XLGX(2,I) =-SP(1)*XLGE(3,I)-SP(4)*(XLG(1)*XLGE(1,I)+XLG(2)*XLGE(2, OBSV2680
1I)) OBSV2690
VO(4)= -SLR*SGR OBSV2700
VO(5)= CLR*CGR OBSV2710
VO(6)= CPH*CGR+SPH*CLR*SGR OBSV2720
VO(7)= SPH*XA(1) OBSV2730
VO(9)= SPH*CGR-CPH*CLR*SGR OBSV2740
VO(10)= CPH*XA(1) OBSV2750
C-----CALCULATE EQ.(283)----- OBSV2760
DO 260 I=1,5 OBSV2770
DO 260 J=1,7 OBSV2780
260 XAX(I,J)= 0. OBSV2790
DO 262 I=1,4 OBSV2800
XAX(1,I+3) = VO(4)*XLGX(2,I) + VO(5)*XLGX(1,I) OBSV2810
XAX(3,I+3) = VO(6)*XLGX(2,I) + VO(7)*XLGX(1,I) OBSV2820
262 XAX(5,I+3) = VO(9)*XLGX(2,I) - VO(10)*XLGX(1,I) OBSV2830
XAX(2,1) = CPH OBSV2840
XAX(2,2) =-XA(4) OBSV2850
XAX(3,2) =-XA(5) OBSV2860
XAX(4,1) = SPH OBSV2870
XAX(4,2) = XA(2) OBSV2880
XAX(5,2) = XA(3) OBSV2890
C-----CALCULATE EQ.(282) ----- OBSV2900
DO 264 I=1,7 OBSV2910
XCX(1,I)= 2.*(XA(1)*XAX(1,I)+XA(3)*XAX(3,I)+RERP2*XA(5)*XAX(5,I)) OBSV2920
XCX(2,I)= 2.*(XA(2)*XAX(3,I)+XA(3)*XAX(2,I)+RERP2*(XA(4)*XAX(5,I) OBSV2930
1 + XA(5)*XAX(4,I))) OBSV2940
264 XCX(3,I)= 2.*(XA(2)*XAX(2,I)+RERP2*XA(4)*XAX(4,I)) OBSV2950
G(1,1)= 0. OBSV2960
G(1,2)= 0. OBSV2970
G(1,3)= 0. OBSV2980
VO(11)= 2.*XC(1)*DFM(1)+XC(2) OBSV2990
VO(12)= (DFM(1)+ XC(3)/VO(11))/XC(1) OBSV3000
VO(13)= (.5-.5*XC(2)/VO(11))/XC(1) OBSV3010
VO(14)= 1./VO(11) OBSV3020
C-----CALCULATE EQ.(281) ----- OBSV3030
DO 266 I=1,7 OBSV3040
266 G(1,I+3)= -VO(12)*XCX(1,I)-VO(13)*XCX(2,I)-VO(14)*XCX(3,I) OBSV3050
GO TO 38 OBSV3060
270 IF(MTYP-8) 272,274,375 OBSV3070
272 LT=0 OBSV3080
GO TO 276 OBSV3090
274 LT=3 OBSV3100
276 DO 284 I=KAR,KOB OBSV3110
J=LC(I) OBSV3120
284 G(I,LT+J)=1. OBSV3130
38 CONTINUE OBSV3140
IF(NSTC) 40,40,46 OBSV3150
40 IF(NPV) 99,99,42 OBSV3160
42 II=1 OBSV3170
IP=1 OBSV3180
44 JJ=MCC(II) OBSV3190
GO TO 50 OBSV3200
46 II=1 OBSV3210
IP=0 OBSV3220
48 JJ=NC(II) OBSV3230
50 GG(1)=0. OBSV3240
GG(2)=0. OBSV3250
GG(3)=0. OBSV3260
IF(MTYP.GE.6) GO TO 375 OBSV3270

```

IF(JJ-N) 60,60,54	OBSV3280
54 IF(JJ-N-15) 56,56,60	OBSV3290
56 JN=JJ-N	OBSV3300
IF(JN-12) 58,58,350	OBSV3310
58 GO TO(300,301,302,303,304,305,306,307,308,309,310,311),JN	OBSV3320
60 II=II+1	OBSV3330
DO 66 I=KAR,KOB	OBSV3340
J=LC(I)	OBSV3350
IF(IP) 62,62,64	OBSV3360
62 G(I,II+ 9) = GG(J)	OBSV3370
GO TO 66	OBSV3380
64 H(I,II-1) = GG(J)	OBSV3390
66 CONTINUE	OBSV3400
IF(IP) 68,68,70	OBSV3410
68 IF(II-NSTC) 48,48,40	OBSV3420
70 IF(II-NPV) 44,44,99	OBSV3430
C-----CALCULATE EQ.(248) -----	OBSV3440
300 GG(1) = CTM(1)	OBSV3450
GO TO 60	OBSV3460
301 GG(2) = CTM(2)	OBSV3470
GO TO 60	OBSV3480
302 GG(3) = CTM(3)	OBSV3490
GO TO 60	OBSV3500
303 GG(1) = 1.	OBSV3510
GO TO 60	OBSV3520
304 GG(2) = 1.	OBSV3530
GO TO 60	OBSV3540
305 GG(3) = 1.	OBSV3550
GO TO 60	OBSV3560
306 GG(1) = CTM(4)	OBSV3570
GO TO 60	OBSV3580
307 GG(2) = CTM(5)	OBSV3590
GO TO 60	OBSV3600
308 GG(3) = CTM(6)	OBSV3610
GO TO 60	OBSV3620
309 GG(1) = 1./SELC	OBSV3630
GO TO 60	OBSV3640
310 GG(3) = CELC/SELC	OBSV3650
311 GO TO 60	OBSV3660
350 SP(1)= SIN(C(N+13))	OBSV3670
SP(2)= COS(C(N+13))	OBSV3680
IF(JN-14) 352,354,356	OBSV3690
352 VO(15)=RERP2*(CPHDT(MTYP)/SP(2))*2	OBSV3700
VO(16)=-{ROT(MTYP)/REO)**2*(RERP2-1.)*SP(1)*SP(2)*ROT(MTYP)	OBSV3710
C-----CALCULATE EQ.(252) -----	OBSV3720
XSC(1)= XS(3)*VO(15)-VO(6)-VO(16)*CCAPH(MTYP)	OBSV3730
XSC(2)= 0.	OBSV3740
XSC(3)=-XS(1)*VO(15)-VO(5)+ VO(16)*SCAPH(MTYP)	OBSV3750
GO TO 358	OBSV3760
354 XSC(1)=-XSX(1,3)	OBSV3770
XSC(2)=-XSX(2,3)	OBSV3780
XSC(3)=-XSX(3,3)	OBSV3790
GO TO 358	OBSV3800
356 XSC(1)=-CCAPH(MTYP)	OBSV3810
XSC(2)= 0.	OBSV3820
XSC(3)= SCAPH(MTYP)	OBSV3830
C-----CALCULATE EQ.(250) -----	OBSV3840
358 RCC(1)=(XSC(1)*XS(1)+XSC(2)*XS(2)+XSC(3)*XS(3))/CTM(1)	OBSV3850
RCC(2)=(XSC(2)*XS(3)-XSC(3)*XS(2))/VO(9)	OBSV3860
RCC(3)=(XSC(1)-RCC(1)*SELC)/VO(8)	OBSV3870

C-----CALCULATE EQ.(249)-----	OBSV3880
GG(1)= C(N+1)*RCC(1)-VO(13)*RCC(3)	OBSV3890
GG(2)= C(N+2)*RCC(2)	OBSV3900
GG(3)= VO(14)*RCC(3)	OBSV3910
IF(MO(MTYP)) 360,60,360	OBSV3920
360 IF(JN-14) 362,364,366	OBSV3930
362 SP(3)= VO(15)-1.	OBSV3940
SP(5)= XS(2)*DX(6)	OBSV3950
C-----CALCULATE EQ.(253A)-----	OBSV3960
XSDC(1)= VO(10)*(XSC(1)+VO(16)*CCAPH(MTYP)-VO(6)*SP(3))	OBSV3970
X +VO(15)*(XSX(3,2)*DX(5)+SP(5)*SPHDT(MTYP))	OBSV3980
XSDC(2)= 0.	OBSV3990
XSDC(3)= VO(10)*(XSC(3)-VO(16)*SCAPH(MTYP)-VO(5)*SP(3))	OBSV4000
X +VO(15)*(-XSX(1,2)*DX(5)+SP(5)*CPHDT(MTYP))	OBSV4010
GO TO 368	OBSV4020
364 SP(1)= XSX(2,3)*DX(6)+XSX(2,2)*DX(5)	OBSV4030
C-----CALCULATE EQ.(253B)-----	OBSV4040
XSDC(1)= VO(10)*XSC(1)+ SP(1)*CPHDT(MTYP)	OBSV4050
XSDC(2)= VO(10)*XSC(2)+ XS(2)*DX(6)+R*CTH*SPH*DX(5)	OBSV4060
XSDC(3)= VO(10)*XSC(3)- SP(1)*SPHDT(MTYP)	OBSV4070
GO TO 368	OBSV4080
366 RCDC(1)= 0.	OBSV4090
RCDC(2)= 0.	OBSV4100
RCDC(3)= 0.	OBSV4110
GO TO 370	OBSV4120
C-----CALCULATE EQ.(251)-----	OBSV4130
368 RCDC(1)= XSDC(1)*XS(1)+XSDC(2)*XS(2)+XSDC(3)*XS(3)	OBSV4140
RCDC(2)= XSDC(2)*XS(3)-XSDC(3)*XS(2)	OBSV4150
RCDC(3)= XSDC(1)*CTM(1)	OBSV4160
370 SP(1)= CTM(6)*XS(2)/CELC	OBSV4170
SP(2)= CTM(6)*XS(3)/CELC	OBSV4180
SP(3)= XSD(1)-CTM(6)*VO(8)	OBSV4190
SP(4)= CTM(1)*VO(8)	OBSV4200
RCDC(1)=(RCDC(1)+XSC(1)*XSD(1)+XSC(2)*XSD(2)+XSC(3)*XSD(3)	OBSV4210
X -RCC(1)*CTM(4))/CTM(1)	OBSV4220
RCDC(2)=(RCDC(2)+XSC(2)*VO(11)+XSC(3)*VO(12))/VO(9)	OBSV4230
RCDC(3)=(RCDC(3)-RCDC(1)*XS(1)-XSC(1)*CTM(4)-XSC(2)*SP(1)	OBSV4240
X -XSC(3)*SP(2)+RCC(1)*SP(3))/SP(4)	OBSV4250
GG(1)= GG(1) + C(N+7)*RCDC(1)	OBSV4260
GG(2)= GG(2) + C(N+8)*RCDC(2)	OBSV4270
GG(3)= GG(3) + C(N+9)*RCDC(3)	OBSV4280
GO TO 60	OBSV4290
375 DO 390 I=1,3	OBSV4300
DO 385 J=1,NSTC	OBSV4310
385 G(I,J+10)= 0.	OBSV4320
DO 390 J=1,NPV	OBSV4330
390 H(I,J)= 0.	OBSV4340
RETURN	OBSV4350
80 DO 82 I=1,3	OBSV4360
SP(I)=SYG(I,MTYP)	OBSV4370
IF(NPC(1).NE.2) SP(I)=SP(I)+SIG(I,KG)	OBSV4380
82 CONTINUE	OBSV4390
99 CONTINUE	OBSV4400
RETURN	OBSV4410
END	OBSV4420

```

SUBROUTINE OUTPUT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
2 CALL AUXIL
4 ZO(1)=X(2)-R*OMEGA*CPH
ZO(2)=SQRT(X(1)**2+ZO(1)**2)
VO(1)=SQRT(ZO(2)**2+X(3)**2)
IF(VO(1).EQ.0.) VO(1)=.00001
ST(1)=-X(3)/VO(1)
CT(1)= ZO(2)/VO(1)
VO(2)=ATAN2(ST(1),CT(1))/CONRD
IF(ZO(2).EQ.0.) ZO(2)=.00001
ST(2)= ZO(1)/ZO(2)
CT(2)= X(1)/ZO(2)
VO(3)=ATAN2(ST(2),CT(2))/CONRD
RO=RO/SQRT(1.-(1.-RERP2)*SPH**2)
VO(4)= X(4)+RO-RO
VO(5)=ATAN2(RERP2*SPH,CPH)/CONRD
VO(6)= X(6)/CONRD
SP(1)=SQRT(X(1)**2+X(2)**2)
VO(10)=ATAN2(A(1,2),A(1,1))/CONRD
SP(1) =SQRT(1.-A(1,3)**2)
VO(11)=-ATAN2(A(1,3),SP(1))/CONRD
VO(12)=ATAN2(A(2,3),A(3,3))/CONRD
SP(1)=X(1)
SP(2)=ZO(1)
SP(3)=X(3)
DO 10 I=1,3
VO(I+12)=0.
DO 10 J=1,3

```

```

OUTP0000
OUTP0010
OUTP0020
OUTP0030
OUTP0040
OUTP0050
OUTP0060
OUTP0070
OUTP0080
OUTP0090
OUTP0100
OUTP0110
OUTP0120
OUTP0130
OUTP0140
OUTP0150
OUTP0160
OUTP0170
OUTP0180
OUTP0190
OUTP0200
OUTP0210
OUTP0220
OUTP0230
OUTP0240
OUTP0250
OUTP0260
OUTP0270
OUTP0280
OUTP0290
OUTP0300
OUTP0310
OUTP0320
OUTP0330
OUTP0340
OUTP0350
OUTP0360
OUTP0370
OUTP0380
OUTP0390
OUTP0400
OUTP0410
OUTP0420
OUTP0430
OUTP0440
OUTP0450
OUTP0460
OUTP0470
OUTP0480
OUTP0490
OUTP0500
OUTP0510
OUTP0520
OUTP0530
OUTP0540
OUTP0550
OUTP0560
OUTP0570
OUTP0580

```

```

10 VO(I+12)=VO(I+12)+A(I,J)*SP(J)
ZO(3)=SQRT(VO(13)**2+VO(15)**2)
SP(1)=SQRT(ZO(3)**2+VO(14)**2)
IF(SP(1).EQ.0.) SP(1)=.00001
ST(4)=VO(14)/SP(1)
CT(4)=ZO(3)/SP(1)
VO(17)=ATAN2(ST(4),CT(4))/CONRD
IF(ZO(3).EQ.0.) ZO(3)=.00001
ST(5)= VO(15)/ZO(3)
CT(5)= VO(13)/ZO(3)
VO(18)=ATAN2(ST(5),CT(5))/CONRD
ZO(4)=A(2,3)+ST(4)*ST(1)
ZO(5)=(A(2,2)*CT(2)-A(2,1)*ST(2))*CT(1)
ZO(9)=SQRT(ZO(4)**2+ZO(5)**2)
IF(ZO(9).EQ.0.) ZO(9)=.000001
ST(3)=ZO(4)/ZO(9)
CT(3)=ZO(5)/ZO(9)
VO(16)=ATAN2(ST(3),CT(3))/CONRD
SP(1)=SQRT(VO(14)**2+VO(15)**2)
SP(3)=ATAN2(SP(1),VO(1))/CONRD
SP(2)=ATAN2(VO(14),VO(15))/CONRD
SP(1) = SQRT(X(1)**2+X(2)**2+X(3)**2)
VO(7) = SP(1)
VO(19)=X(5)/CONRD
VO(20)=SQRT(AG(1)**2+AG(2)**2+AG(3)**2)
WRITE(OUT,1001)
1001 FORMAT(//)
WRITE(OUT,1000) TO
WRITE(OUT,1002) (VO(I),I=1,6)
WRITE(OUT,1004) X(1),X(2),X(3),VO(10),VO(11),VO(12)
WRITE(OUT,1006) (VO(I),I=13,18)
WRITE(OUT,1008) (XP(I),I=1,3),(SP(I),I=1,3)
WRITE(OUT,1010) (PA(I),I=1,3),(AB(I),I=1,3)
WRITE(OUT,1012) (PM(I),I=1,3),(AM(I),I=1,3)
WRITE(OUT,1014) (X(I),I=7,10),VO(19),VO(20)
1000 FORMAT(5H TIME,E15.8)
1002 FORMAT(5H V(A),E15.8,5H G(A)E15.8,5H L(A)E15.8,5H ALT E15.8,5H LATOUTP0590
10E15.8,5H LON E15.8)
1004 FORMAT(5H U(I),E15.8,5H V(I)E15.8,5H W(I)E15.8,5H PSI E15.8,5H THEOUTP0600
2 E15.8,5H PHI E15.8)
1006 FORMAT(5H U(B),E15.8,5H V(B)E15.8,5H W(B)E15.8,5H SIG E15.8,5H BETOUTP0610
3 E15.8,5H ALF E15.8)
1008 FORMAT(5H XP ,E15.8,5H YP E15.8,5H ZP E15.8,5H V(T)E15.8,5H XZIOUTP0620
4 E15.8,5H ETA E15.8)
1010 FORMAT(5H P ,E15.8,5H Q E15.8,5H R E15.8,5H AX E15.8,5H AY OUTP0630
5 E15.8,5H AZ E15.8)
1012 FORMAT(5H PM ,E15.8,5H QM E15.8,5H RM E15.8,5H AXM E15.8,5H AYMOUTP0640
6 E15.8,5H AZM E15.8)
1014 FORMAT(5H E0 ,E15.8,5H E1 E15.8,5H E2 E15.8,5H E3 E15.8,5H LATOUTP0650
7E15.8,5H A(T)E15.8)
IF(NPC(1)-1) 20,99,28
20 IF(DCOMP) 28,22,22
22 IF(NSTC) 28,26,24
24 DO 26 I=1,NSTC
K=NC(I)
26 AG(I) = C(K)
WRITE(OUT,1016) (NC(I),AG(I),I=1,NSTC)
1016 FORMAT(6(2H C,I3,E15.8))
28 IF(NPC(3)-1) 30,100,100
100 DO 102 I=1,6

```

```

DO 102 K=1,10
102 DUB(K,1)=0.
Z0(6)=V0(1)**2
Z0(7)=Z0(6)*Z0(2)
Z0(8)=OMEGA*CPH
DUB(1,1)= X(1)/V0(1)
DUB(2,1)= Z0(1)/V0(1)
DUB(3,1)= X(3)/V0(1)
DUB(4,1)= - DUB(2,1)*Z0(8)
DUB(5,1)= -DUB(4,1)*R*TPH
SP(1)= X(3)/(V0(1)*Z0(2))
DUB(1,2)= SP(1)*DUB(1,1)
DUB(2,2)= SP(1)*DUB(2,1)
DUB(3,2)=-Z0(2)/Z0(6)
DUB(4,2)= SP(1)*DUB(4,1)
DUB(5,2)= SP(1)*DUB(5,1)
SP(1)=Z0(2)**2
DUB(1,3)=-Z0(1)/SP(1)
DUB(2,3)= X(1)/SP(1)
DUB(4,3)=-X(1)*Z0(8)/SP(1)
DUB(5,3)=-DUB(4,3)*R*TPH
IF(NPC(3)-1) 120,110,120
110 SP(1)= 2./(A(1,1)**2+A(1,2)**2)
DUB(7,4)=SP(1)*(X(10)*A(1,1)-X(7)*A(1,2))
DUB(8,4)=SP(1)*(X(9)*A(1,1)-X(8)*A(1,2))
DUB(9,4)=SP(1)*(X(8)*A(1,1)+X(9)*A(1,2))
DUB(10,4)=SP(1)*(X(7)*A(1,1)+X(10)*A(1,2))
SP(1)= 2./SQRT(1.-A(1,3)**2)
DUB(7,5)= X(9)*SP(1)
DUB(8,5)=-X(10)*SP(1)
DUB(9,5)= X(7)*SP(1)
DUB(10,5)=-X(8)*SP(1)
SP(1)= 2./(A(3,3)**2+A(2,3)**2)
DUB(7,6)=SP(1)*(X(8)*A(3,3)-X(7)*A(2,3))
DUB(8,6)=SP(1)*(X(7)*A(3,3)+X(8)*A(2,3))
DUB(9,6)=SP(1)*(X(10)*A(3,3)+X(9)*A(2,3))
DUB(10,6)=SP(1)*(X(9)*A(3,3)-X(10)*A(2,3))
GO TO 200
120 SP(1)= X(1)*X(7) + Z0(1)*X(10) - X(3)*X(9)
SP(2)= X(1)*X(8) + Z0(1)*X(9) + X(3)*X(10)
SP(3)= X(1)*X(9) - Z0(1)*X(8) + X(3)*X(7)
SP(4)= X(1)*X(10) - Z0(1)*X(7) - X(3)*X(8)
SP(5)= ST(4)/(CT(4)*V0(1))
SP(6)= 2./V0(1)
DUB(1,5)= (CT(4)*A(2,1)-SP(5)*(X(1) -A(2,1)*V0(14)))/V0(1)
DUB(2,5)= (CT(4)*A(2,2)-SP(5)*(Z0(1)-A(2,2)*V0(14)))/V0(1)
DUB(3,5)= (CT(4)*A(2,3)-SP(5)*(X(3) -A(2,3)*V0(14)))/V0(1)
DUB(4,5)= -Z0(8)*DUB(2,5)
DUB(5,5)= -DUB(4,5)*R*TPH
DUB(7,5)=(-CT(4)*SP(4)-SP(5)*(V0(13)*SP(1)+V0(15)*SP(3)))*SP(6)
DUB(8,5)= (CT(4)*SP(3)-SP(5)*(V0(13)*SP(2)+V0(15)*SP(4)))*SP(6)
DUB(9,5)= (CT(4)*SP(2)+SP(5)*(V0(13)*SP(3)-V0(15)*SP(1)))*SP(6)
DUB(10,5)=(-CT(4)*SP(1)+SP(5)*(V0(13)*SP(4)-V0(15)*SP(2)))*SP(6)
SP(6)= Z0(3)**2
DUB(1,6)= (V0(13)*A(3,1)-V0(15)*A(1,1))/SP(6)
DUB(2,6)= (V0(13)*A(3,2)-V0(15)*A(1,2))/SP(6)
DUB(3,6)= (V0(13)*A(3,3)-V0(15)*A(1,3))/SP(6)
DUB(4,6)= -Z0(8)*DUB(2,6)
DUB(5,6)= -DUB(4,6)*R*TPH
SP(6)= 2./SP(6)

```

```

OUTPUT1190
OUTPUT1200
OUTPUT1210
OUTPUT1220
OUTPUT1230
OUTPUT1240
OUTPUT1250
OUTPUT1260
OUTPUT1270
OUTPUT1280
OUTPUT1290
OUTPUT1300
OUTPUT1310
OUTPUT1320
OUTPUT1330
OUTPUT1340
OUTPUT1350
OUTPUT1360
OUTPUT1370
OUTPUT1380
OUTPUT1390
OUTPUT1400
OUTPUT1410
OUTPUT1420
OUTPUT1430
OUTPUT1440
OUTPUT1450
OUTPUT1460
OUTPUT1470
OUTPUT1480
OUTPUT1490
OUTPUT1500
OUTPUT1510
OUTPUT1520
OUTPUT1530
OUTPUT1540
OUTPUT1550
OUTPUT1560
OUTPUT1570
OUTPUT1580
OUTPUT1590
OUTPUT1600
OUTPUT1610
OUTPUT1620
OUTPUT1630
OUTPUT1640
OUTPUT1650
OUTPUT1660
OUTPUT1670
OUTPUT1680
OUTPUT1690
OUTPUT1700
OUTPUT1710
OUTPUT1720
OUTPUT1730
OUTPUT1740
OUTPUT1750
OUTPUT1760
OUTPUT1770
OUTPUT1780

```

```

DUB(7,6) = (V0(13)*SP(3)-V0(15)*SP(1))*SP(6)      OUTP1790
DUB(8,6) = (V0(13)*SP(4)-V0(15)*SP(2))*SP(6)      OUTP1800
DUB(9,6) = (V0(13)*SP(1)+V0(15)*SP(3))*SP(6)      OUTP1810
DUB(10,6) = (V0(13)*SP(2)+V0(15)*SP(4))*SP(6)     OUTP1820
SP(1)= CT(3)*ST(4)*CT(1)+ST(3)*ST(1)*Z0(5)/CT(1)  OUTP1830
SP(2)= ST(3)*CT(1)*(A(2,2)*ST(2)+A(2,1)*CT(2))    OUTP1840
SP(3)= CT(3)*CT(4)*ST(1)                          OUTP1850
DUB(1,4) = (SP(1)*DUB(1,2)+SP(2)*DUB(1,3)+SP(3)*DUB(1,5))/Z0(9) OUTP1860
DUB(2,4) = (SP(1)*DUB(2,2)+SP(2)*DUB(2,3)+SP(3)*DUB(2,5))/Z0(9) OUTP1870
DUB(3,4) = (SP(1)*DUB(3,2)+SP(2)*DUB(3,3)+SP(3)*DUB(3,5))/Z0(9) OUTP1880
DUB(4,4) = (SP(1)*DUB(4,2)+SP(2)*DUB(4,3)+SP(3)*DUB(4,5))/Z0(9) OUTP1890
DUB(5,4) = (SP(1)*DUB(5,2)+SP(2)*DUB(5,3)+SP(3)*DUB(5,5))/Z0(9) OUTP1900
SP(6)= ST(3)*CT(1)                                OUTP1910
SP(5)= SP(6)*CT(2)                                OUTP1920
SP(6)= SP(6)*ST(2)                                OUTP1930
DUB(7,4) = (SP(3)*DUB(7,5)+2.*(CT(3)*X( 8)-SP(5)*X( 7)-SP(6)*X(10) OUTP1940
X))/Z0(9)                                           OUTP1950
DUB(8,4) = (SP(3)*DUB(8,5)+2.*(CT(3)*X( 7)+SP(5)*X( 8)+SP(6)*X( 9) OUTP1960
X))/Z0(9)                                           OUTP1970
DUB(9,4) = (SP(3)*DUB(9,5)+2.*(CT(3)*X(10)-SP(5)*X( 9)+SP(6)*X( 8) OUTP1980
X))/Z0(9)                                           OUTP1990
DUB(10,4) = (SP(3)*DUB(10,5)+2.*(CT(3)*X( 9)+SP(5)*X(10)-SP(6)*X( 7) OUTP2000
X))/Z0(9)                                           OUTP2010
200 DO 205 I=1,3                                     OUTP2020
    DO 205 J=1,NSTX                                   OUTP2030
        DUB(J,I+6)=0.                                OUTP2040
        DUB(J,I+9)=P(I+3,J)                          OUTP2050
        DUB(J,I+12)=0.                                OUTP2060
        DO 202 K=1,5                                  OUTP2070
            SUM=P(K,J)                                OUTP2080
            IF(K-J) 202,202,201                        OUTP2090
201 SUM=P(J,K)                                         OUTP2100
202 DUB(J,I+6)=DUB(J,I+6)+DUB(K,I)*SUM               OUTP2110
    DO 204 K=1,10                                     OUTP2120
        SUM=P(K,J)                                    OUTP2130
        IF(K-J) 204,204,203                           OUTP2140
203 SUM=P(J,K)                                         OUTP2150
204 DUB(J,I+12)=DUB(J,I+12)+DUB(K,I+3)*SUM           OUTP2160
205 CONTINUE                                           OUTP2170
    DO 218 I=1,3                                     OUTP2180
        DO 208 J=1,3                                  OUTP2190
            P(J+1,I)=0.                                OUTP2200
            P(J+7,I)=0.                                OUTP2210
            DO 206 K=1,5                                OUTP2220
206 P(J+1,I)=P(J+1,I)+DUB(K,I+6)*DUB(K,J)           OUTP2230
        DO 207 K=1,10                                  OUTP2240
207 P(J+7,I)=P(J+7,I)+DUB(K,I+6)*DUB(K,J+3)         OUTP2250
208 CONTINUE                                           OUTP2260
    DO 212 J=1,3                                     OUTP2270
        P(J+7,I+6)=0.                                OUTP2280
        P(J+4,I+3)=P(I+3,J+3)                        OUTP2290
        DO 212 K=1,10                                  OUTP2300
212 P(J+7,I+6)=P(J+7,I+6)+DUB(K,I+12)*DUB(K,J+3)   OUTP2310
    DO 214 J=1,3                                     OUTP2320
        P(J+4,I)= DUB(J+3,I+6)                        OUTP2330
214 P(J+7,I+3)= DUB(I+3,J+12)                        OUTP2340
    DO 216 J=1,NSTC                                   OUTP2350
        P(J+10,I)= DUB(J+10,I+7)                     OUTP2360
        P(J+10,I+6)= DUB(J+10,I+12)                  OUTP2370
216 P(J+10,I+3)= P(I+3,J+10)                        OUTP2380

```

218 CONTINUE	OUTP2390
DO 210 I=1,NSTC	OUTP2400
DO 210 J=1,NSTC	OUTP2410
210 P(J+10,I+9)= P(I+10,J+10)	OUTP2420
LT=1	OUTP2430
MT=NSTX-1	OUTP2440
NT=9	OUTP2450
GO TO 34	OUTP2460
30 LT=0	OUTP2470
MT=NSTX	OUTP2480
NT=10	OUTP2490
DO 32 I=1,NSTX	OUTP2500
K=I+1	OUTP2510
DO 32 J=K,NSTX	OUTP2520
32 P(J,I)=P(I,J)	OUTP2530
34 IF(NPC(1)) 35,130,35	OUTP2540
130 IF(NPC(4)-1) 35,132,35	OUTP2550
132 IF(NPC(3)) 134,134,138	OUTP2560
134 DO 136 I=1,10	OUTP2570
136 VO(I)= DZ(I)	OUTP2580
GO TO 146	OUTP2590
138 DO 144 I=1,3	OUTP2600
VO(I)=0.	OUTP2610
VO(I+6)=0.	OUTP2620
DO 140 J=1,5	OUTP2630
140 VO(I)=VO(I)+ DUB(J,I)*DZ(J)	OUTP2640
VO(I+3)= DZ(I+3)	OUTP2650
DO 142 J=1,10	OUTP2660
142 VO(I+6)=VO(I+6)+ DUB(J,I+3)*DZ(J)	OUTP2670
144 CONTINUE	OUTP2680
146 IF(NSTC) 148,147,148	OUTP2690
147 WRITE(OUT,1028) (I,VO(I),I=1,NT)	OUTP2700
GO TO 35	OUTP2710
148 DO 150 I=1,NSTC	OUTP2720
150 VO(I+NT)= DZ(I+10)	OUTP2730
WRITE(OUT,1028) (I,VO(I),I=1,NT),(NC(I),VO(I+NT),I=1,NSTC)	OUTP2740
1028 FORMAT(6(3H Z(I3,1H)E13.6))	OUTP2750
35 DO 40 I=1,MT	OUTP2760
K=I+LT	OUTP2770
IF(P(K,I)) 36,38,38	OUTP2780
36 WRITE(OUT,1030) I,I,I,P(K,I)	OUTP2790
VO(I) = P(K,I)	OUTP2800
1030 FORMAT(26H ****NEGATIVE VARIANCE ON I3,31HRD TRANSFORMED VARIABLE,	OUTP2810
A SIGMA(I3,1H,I3,4H) = E15.8)	OUTP2820
GO TO 40	OUTP2830
38 VO(I)=SQRT(P(K,I))	OUTP2840
40 CONTINUE	OUTP2850
IF(NSTC.GT.0) GO TO 50	OUTP2860
WRITE(OUT,1032) (I,VO(I),I=1,NT)	OUTP2870
GO TO 52	OUTP2880
50 DO 39 I=1,NSTC	OUTP2890
K=I+NT	OUTP2900
39 ZO(I)=VO(K)	OUTP2910
WRITE(OUT,1032) (I,VO(I),I=1,NT),(NC(I),ZO(I) ,I=1,NSTC)	OUTP2920
1032 FORMAT(6(3H S(I3,1H)E13.6))	OUTP2930
52 IF(NPC(7).NE.ICOUNT) RETURN	OUTP2940
IF(NPC(6)-1) 99,41,42	OUTP2950
41 IF(DCOMP.GT.0) RETURN	OUTP2960
42 WRITE(OUT,1033)	OUTP2970
1033 FORMAT(42H COVARIANCE MATRIX P (LOWER TRIANGLE ONLY))	OUTP2980

DO 43 I=1,MT	OUTP2990
43 WRITE(OUT,1034) (P(I+LT,J),J=1,I)	OUTP3000
1034 FORMAT(X,12E10,3)	OUTP3010
IF(NPU) 44,44,250	OUTP3020
44 IF(NPV) 46,46,300	OUTP3030
46 CONTINUE	OUTP3040
99 RETURN	OUTP3050
250 IF(LT) 256,252,256	OUTP3060
252 DO 254 I=1,NSTX	OUTP3070
DO 254 J=1,NPU	OUTP3080
254 DUB(I,J+6)=CUZ(I,J)	OUTP3090
GO TO 266	OUTP3100
256 DO 262 I=1,3	OUTP3110
DO 262 J=1,NPU	OUTP3120
DUB(I,J+6)=0.	OUTP3130
DUB(I+6,J+6)=0.	OUTP3140
DO 258 K=1,5	OUTP3150
258 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CUZ(K,J)	OUTP3160
DO 260 K=1,10	OUTP3170
260 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CUZ(K,J)	OUTP3180
262 DUB(I+3,J+6)=CUZ(I+3,J)	OUTP3190
DO 264 I=1,NSTC	OUTP3200
DO 264 J=1,NPU	OUTP3210
264 DUB(I+9,J+6)=CUZ(I+10,J)	OUTP3220
266 WRITE(OUT,1035)	OUTP3230
1035 FORMAT(34H CORRELATION MATRIX (CUZ)TRANPOSE)	OUTP3240
MT=NSTX-LT	OUTP3250
DO 268 J=1,NPU	OUTP3260
268 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP3270
GO TO 44	OUTP3280
300 IF(LT) 306,302,306	OUTP3290
302 DO 304 I=1,NSTX	OUTP3300
DO 304 J=1,NPV	OUTP3310
304 DUB(I,J+6)=CVZ(I,J)	OUTP3320
GO TO 316	OUTP3330
306 DO 312 I=1,3	OUTP3340
DO 312 J=1,NPV	OUTP3350
DUB(I,J+6)=0.	OUTP3360
DUB(I+6,J+6)=0.	OUTP3370
DO 308 K=1,5	OUTP3380
308 DUB(I,J+6)=DUB(I,J+6)+DUB(K,I)*CVZ(K,J)	OUTP3390
DO 310 K=1,10	OUTP3400
310 DUB(I+6,J+6)=DUB(I+6,J+6)+DUB(K,I+3)*CVZ(K,J)	OUTP3410
312 DUB(I+3,J+6)=CVZ(I+3,J)	OUTP3420
DO 314 I=1,NSTC	OUTP3430
DO 314 J=1,NPV	OUTP3440
314 DUB(I+9,J+6)=CVZ(I+10,J)	OUTP3450
316 WRITE(OUT,1036)	OUTP3460
1036 FORMAT(34H CORRELATION MATRIX (CVZ)TRANPOSE)	OUTP3470
MT=NSTX-LT	OUTP3480
DO 318 J=1,NPV	OUTP3490
318 WRITE(OUT,1034) (DUB(I,J+6),I=1,MT)	OUTP3500
GO TO 46	OUTP3510
END	OUTP3520

```

SUBROUTINE PRESET
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYP ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
NDIMT = 160
NDIMZ = 30
NDIMV = 5
NDIMU = 5
DO 12 I=1,NDIMZ
DO 4 J=1,NDIMZ
4 P(I,J)=0.
DO 6 J=1,NDIMU
6 CUZ(I,J) = 0.
DO 8 J=1,NDIMV
8 CVZ(1,J) = 0.
DO 10 J=1,10
10 PH(J,I)=0.
12 DZ(I) = 0.
DO 16 I=1,NDIMU
16 U(I)=0.
DO 18 I=1,NDIMV
18 S(I)=0.
DO 26 I=1,NDIMT
26 C(I) = 0.
C(36) = 1.
C(40) = 1.
C(44) = 1.
C(61) = 1.
C(65) = 1.
C(69) = 1.
C(76) = 1.

```

```

COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
PRES0010
PRES0020
PRES0030
PRES0040
PRES0050
PRES0060
PRES0070
PRES0080
PRES0090
PRES0100
PRES0110
PRES0120
PRES0130
PRES0140
PRES0150
PRES0160
PRES0170
PRES0180
PRES0190
PRES0200
PRES0210
PRES0220
PRES0230
PRES0240
PRES0250
PRES0260
PRES0270

```



```

C(77) = 1.
C(78) = 1.
C(91) = 1.
C(92) = 1.
C(93) = 1.
C(106) = 1.
C(107) = 1.
C(108) = 1.
C(121) = 1.
C(122) = 1.
C(123) = 1.
C(136) = 1.
C(137) = 1.
C(138) = 1.
CONRD = .0174532925
XJ2 = 1.082645E-3
XMU = 3.985992E+14
OMEGA = .7292116E-4
RPO = 6356173.
REO = 6378163.
NCOUNT = 0
ICOUNT = 1
KDATAS = -1
NST = 0
NSTX = 0
NSTC = 0
NSTA = 0
NPU = 0
NPV = 0
FIT = 1
PQR = 2
SCRACH = 3
STATE = 4
IN = 5
OUT = 6
N8(1) = 0
N8(2) = 1
N8(3) = 0
N9(1) = 0
N9(2) = 1
N9(3) = 0
N10(1) = 0
N10(2) = 1
N10(3) = 0
N11(1) = 0
N11(2) = 1
N11(3) = 0
DO 200 I=1,9
  DFIT(I) = 1.E10
  DTI(I) = 1.E10
200 NTR(I) = 0
  TIME = 1.E+10
  KG = 2
  CALL INDAT
  CALL SETUP
99 RETURN
END

```

```

PRES0280
PRES0290
PRES0300
PRES0310
PRES0320
PRES0330
PRES0340
PRES0350
PRES0360
PRES0370
PRES0380
PRES0390
PRES0400
PRES0410
PRES0420
PRES0430
PRES0440
PRES0450
PRES0460
PRES0470
PRES0480
PRES0490
PRES0500
PRES0510
PRES0520
PRES0530
PRES0540
PRES0550
PRES0560
PRES0570
PRES0580
PRES0590
PRES0600
PRES0610
PRES0620
PRES0630
PRES0640
PRES0650
PRES0660
PRES0670
PRES0680
PRES0690
PRES0700
PRES0710
PRES0720
PRES0730
PRES0740
PRES0750
PRES0760
PRES0770
PRES0780
PRES0790
PRES0800
PRES0810
PRES0820
PRES0830
PRES0840

```

```

SUBROUTINE PROP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBR5 ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,K5,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
C-----CALCULATE EQ.(55B) -----
DO 4 I=1,10
DO 4 J=1,NSTX
SUM = 0.
L = J+1
DO 2 K=1,J
2 SUM = SUM + PH(I,K)*P(K,J)
IF(L.GT.NSTX) GO TO 4
DO 3 K=L,NSTX
3 SUM = SUM + PH(I,K)*P(J,K)
4 DUB(J,I) = SUM
DO 10 I=1,10
DO 8 J=1,10
SUM = 0.
DO 6 K=1,NSTX
6 SUM = SUM + DUB(K,I)*PH(J,K)
8 P(I,J) = SUM
10 CONTINUE
IF(NSTX-10) 12,16,12
12 DO 14 I=11,NSTX
DO 14 J=1,10
14 P(J,I) = DUB(I,J)
IF(NPU) 38,38,60
60 DO 64 I=1,10
DO 64 K=11,NSTX
SUM = 0.
DO 62 J=1,NPU

```

II=J+NSTX	PROP0280
62 SUM = SUM + PH(I,II)*CUZ(K,J)	PROP0290
64 P(I,K) = P(I,K) + SUM	PROP0300
GO TO 20	PROP0310
16 IF(NPU) 38,38,20	PROP0320
C-----CALCULATE EQ.(55C) -----	PROP0330
20 DO 25 J=1,NPU	PROP0340
DO 24 I=1,10	PROP0350
SUM = 0.	PROP0360
DO 22 K=1,NSTX	PROP0370
SUM = SUM + PH(I,K)*CUZ(K,J)	PROP0380
22 CONTINUE	PROP0390
DUB(I,J) = SUM	PROP0400
24 DUB(I,15) = SUM + PH(I,J+NSTX)*D(J)	PROP0410
DO 25 I=1,10	PROP0420
25 CUZ(I,J) = DUB(I,15)	PROP0430
26 CONTINUE	PROP0440
30 DO 34 I=1,10	PROP0450
DO 34 J=1,10	PROP0460
SUM = 0.	PROP0470
DO 32 K=1,NPU	PROP0480
32 SUM = SUM + CUZ(I,K)*PH(J,K+NSTX) + PH(I,K+NSTX)*DUB(J,K)	PROP0490
34 P(I,J) = P(I,J) + SUM	PROP0500
36 CONTINUE	PROP0510
38 IF(NPV) 99,99,40	PROP0520
C-----CALCULATE EQ.(55D) -----	PROP0530
40 DO 48 J=1,NPV	PROP0540
DO 44 I=1,10	PROP0550
SUM = 0.	PROP0560
DO 42 K=1,NSTX	PROP0570
42 SUM = SUM + PH(I,K)*CVZ(K,J)	PROP0580
44 DUB(I,1) = SUM	PROP0590
DO 46 I=1,10	PROP0600
46 CVZ(I,J) = DUB(I,1)	PROP0610
48 CONTINUE	PROP0620
99 IF(NPC(4),EQ.0) GO TO 75	PROP0630
IF(NPC(1),EQ.2) GO TO 75	PROP0640
C-----CALCULATE EQ.(55A) -----	PROP0650
DO 72 I=1,10	PROP0660
SUM = 0.	PROP0670
DO 70 J=1,NSTX	PROP0680
70 SUM = SUM + PH(I,J)*DZ(J)	PROP0690
72 DUB(I,1) = SUM	PROP0700
DO 74 I=1,10	PROP0710
74 DZ(I) = DUB(I,1)	PROP0720
75 CONTINUE	PROP0730
ENTRY IDENT	PROP0740
K = NSTX+NPU	PROP0750
DO 52 I=1,10	PROP0760
DO 50 J=1,K	PROP0770
50 PH(I,J)=0.	PROP0780
52 PH(I,I)=1.	PROP0790
RETURN	PROP0800
END	PROP0810

	SUBROUTINE RKUTTA	RKUT0000
	DIMENSION PR(3)	RKUT0010
	DIMENSION F1(410),F2(410),F3(410),DELY(410)	RKUT0020
	COMMON /INTGRL/ P,T,TP,Y(410),DY(410),N,L	RKUT0030
	DATA PR /.5,.25,.5/	RKUT0040
	GO TO (1,2,2,4),L	RKUT0050
1	IF(IG.EQ.0) GO TO 30	RKUT0060
	DO 10 I = 1,N	RKUT0070
10	F3(I)=Y(I)	RKUT0080
	L = 2	RKUT0090
	RETURN	RKUT0100
2	DT = P	RKUT0110
	J = 1	RKUT0120
	T2 = TP - T	RKUT0130
	RT2=T2/P	RKUT0140
	IF(RT2-.99999)22,26,29	RKUT0150
22	IF(RT2.GT..00001) GO TO 26	RKUT0160
20	L=3	RKUT0170
	RETURN	RKUT0180
26	DT=T2	RKUT0190
29	IG=0	RKUT0200
30	GO TO(31,32,33,34),J	RKUT0210
31	T = T+PR(1)*DT	RKUT0220
	DO 310 I=1,N	RKUT0230
	F1(I)=DY(I)*DT	RKUT0240
310	Y(I)=F3(I)+PR(1)*F1(I)	RKUT0250
	J = J+1	RKUT0260
	GO TO 38	RKUT0270
33	T = T+PR(1)*DT	RKUT0280
32	T2=DT/PR(1)	RKUT0290
	DO 320 I=1,N	RKUT0300
	RT2=DY(I)*T2	RKUT0310
	F1(I)=F1(I)+RT2	RKUT0320
320	Y(I)=F3(I)+PR(J)*RT2	RKUT0330
35	J = J + 1	RKUT0340
	RETURN	RKUT0350
34	DO 340 I=1,N	RKUT0360
340	F1(I)=F1(I)+DY(I)*DT	RKUT0370
37	DO 39 I = 1,N	RKUT0380
	DELY(I)=F1(I)/6.+DELY(I)	RKUT0390
39	Y(I)=F2(I)+DELY(I)	RKUT0400
	IG = 1	RKUT0410
	RETURN	RKUT0420
4	DT=P	RKUT0430
	IG = 1	RKUT0440
	J = 1	RKUT0450
	DO 40 I = 1,N	RKUT0460
	DELY(I) = 0.00	RKUT0470
40	F2(I)=Y(I)	RKUT0480
38	L = 1	RKUT0490
	RETURN	RKUT0500
	END	RKUT0510

```

SUBROUTINE SETUP
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUO(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHOT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TG(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PGR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PGR
DIMENSION DUA(4,2)
WRITE(OUT,1000)
1000 FORMAT(1H1,27H CONTROLS ARE SPECIFIED FOR)
IF(NPC(1)-1) 10,11,12
10 WRITE(OUT,1001) TO,TFINAL
1001 FORMAT(5X,28H*FILTERING RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
GO TO 13
11 WRITE(OUT,1002) TO,TFINAL
1002 FORMAT(5X,32H*DETERMINISTIC RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
1.4)
GO TO 24
12 WRITE(OUT,1003) TO,TFINAL
1003 FORMAT(5X,33H*ERROR ANALYSIS RUN FROM TIME TO=F9.4,11H TO TFINAL=F9.4)
19.4)
GO TO 21
13 IF(NPC(4))14,14,15
14 WRITE(OUT,1004)
1004 FORMAT(5X,18H*UPDATED REFERENCE)
GO TO 16
15 WRITE(OUT,1005)
1005 FORMAT(5X,21H*NONUPDATED REFERENCE)
16 IF(NPC(8)-1) 17,18,19
17 WRITE(OUT,1006)
1006 FORMAT(5X,57H*SMOOTH DETERMINISTICALLY, NO RESIDUALS NOR LOSS FUNCTION)
GO TO 20
18 WRITE(OUT,1007)

```

```

1007 FORMAT(5X,64H*SMOOTH DETERMINISTICALLY, CALCULATE RESIDUALS AND LOSETP0280
      XSS FUNCTION) SETP0290
      GO TO 20 SETP0300
      19 IF(NPC(8)-3) 170,172,174 SETP0310
170 WRITE(OUT,1027) SETP0320
1027 FORMAT(5X,49H*SMOOTH COVARIANCE,NO RESIDUALS NOR LOSS FUNCTION) SETP0330
      GO TO 20 SETP0340
172 WRITE(OUT,1028) SETP0350
1028 FORMAT(5X,56H*SMOOTH COVARIANCE,CALCULATE RESIDUALS AND LOSS FUNCTSETP0360
      XION) SETP0370
      GO TO 20 SETP0380
174 WRITE(OUT,1029) SETP0390
1029 FORMAT(5X,13H*NO SMOOTHING) SETP0400
      20 WRITE(OUT,1009) NPC(7) SETP0410
1009 FORMAT(5X,12H*FILTER FOR I2,11H ITERATIONS) SETP0420
      21 IF(NPC(9).EQ.0) GO TO 23 SETP0430
      22 WRITE(OUT,1010) SETP0440
1010 FORMAT(5X,28H*SCALAR PROCESS FITTING DATA) SETP0450
      GO TO 24 SETP0460
      23 WRITE(OUT,1011) SETP0470
1011 FORMAT(5X,36H*VECTOR PROCESS FITTING DATA TRIPLES) SETP0480
      24 IF(NPC(2)) 25,25,26 SETP0490
      25 WRITE(OUT,1012) SETP0500
1012 FORMAT(5X,52H*INPUT AND OUTPUT IN METRIC UNITS(M,M/SEC,M/SEC2*KG))SETP0510
      GO TO 27 SETP0520
      26 WRITE(OUT,1013) SETP0530
1013 FORMAT(5X,62H*INPUT AND OUTPUT IN ENGLISH UNITS (FT,FT/SEC,FT/SEC2SETP0540
      X,LB,SLUG)) SETP0550
      27 WRITE(OUT,1014) REO,RPO,OMEGA,XMU,XJ2 SETP0560
1014 FORMAT(5X,18H*PLANET PARAMETERS/20X,11HEQUIT,RAD.=E15.8,13H POLARSETP0570
      1 RAD.=E15.8,13H ROTATION =E15.8/20X,11HMU(GRAV.) =E15.8,13H J2(SETP0580
      2GRAV.) =E15.8/5X,26H*INITIAL STATE ESTIMATE IS) SETP0590
      IF(NPC(3)-1) 28,29,30 SETP0600
      28 WRITE(OUT,1015) (ZO(I),I=1,10) SETP0610
1015 FORMAT(20X,11HU,9X,1H=E15.8,3H V,9X,1H=E15.8,3H W,9X,1H=E15.8/20XSETP0620
      1,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITUDE =E15.8/2SETP0630
      20X,2HE0,8X,1H=E15.8,4H E1,8X,1H=E15.8,4H E2,8X,1H=E15.8/20X,2HE3SETP0640
      3,8X,1H=E15.8) SETP0650
      GO TO 31 SETP0660
      29 WRITE(OUT,1016) (ZO(I),I=1,9) SETP0670
1016 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP0680
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITSETP0690
      2UDE =E15.8/20X,11HPSI(BAR) =E15.8,13H THETA(BAR)=E15.8,13H PHISETP0700
      3BAR) =E15.8) SETP0710
      GO TO 31 SETP0720
      30 WRITE(OUT,1017) (ZO(I),I=1,9) SETP0730
1017 FORMAT(20X,11HVELOCITY =E15.8,13H GAMMA =E15.8,13H LAMBDA SETP0740
      1 =E15.8/20X,11HALTITUDE =E15.8,13H GEOD.LAT. =E15.8,13H LONGITSETP0750
      2UDE =E15.8/20X,11HSIGMA =E15.8,13H BETA =E15.8,13H ALPHISETP0760
      3A =E15.8) SETP0770
      31 RERP2=(REO/RPO)**2 SETP0780
      XMUJ = 3.*XMU*XJ2*REO**2 SETP0790
      IF(NPC(1)-1)32,40,32 SETP0800
      32 WRITE(OUT,1018) NSTA SETP0810
1018 FORMAT(5X,22H*FITTING DATA IS FROM I2,8H SOURCES) SETP0820
      KSS=0 SETP0830
      DO 42 I=1,NSTA SETP0840
      IF(NS(I)-6) 33,44,45 SETP0850
      33 MT = NS(I) SETP0860
      N = 73 +15*VT SETP0670

```

```

WRITE(OUT,1019) I,MT,C(N),C(N+1),C(N+2)
1019 FORMAT(10X,I1,19H. TRACKING STATION I1,12H. GEOD.LAT.=F11.6,12H. L
XONGITUDE=F11.6,12H. ALTITUDE =F11.4,19H ABOVE REF. SURFACE)
C(N)=C(N)*CONRD
C(N+1)=C(N+1)*CONRD
C(N) = ATAN2(SIN(C(N)),RERP2*COS(C(N)))
NT=N+2
MTYP = MT
CALL STAT
DO 36 J=1,NSTC
IF(NC(J)-N) 36,35,35
35 IF(NC(J)-NT)37,37,36
36 CONTINUE
GO TO 38
37 KSS=KSS+1
NSS(KSS) = MT
38 MO(MT) = 0
DO 39 J=1,NSTC
IF(NC(J).LT.N-6) GO TO 39
IF(NC(J).LE.N-4) GO TO 40
39 CONTINUE
IF(C(N-6).NE.0.) GO TO 40
IF(C(N-5).NE.0.) GO TO 40
IF(C(N-4).NE.0.) GO TO 40
GO TO 42
44 WRITE(OUT,1020) I,C(151),C(152)
1020 FORMAT(10X,I1,27H. AIRBORNE RADAR, DELTA(P)=F11.6,11H DELTA(Y)=F1
X1.6)
GO TO 42
45 IF(NS(I)-7) 41,41,43
41 WRITE(OUT,1031) I
GO TO 42
43 WRITE(OUT,1030) I
GO TO 42
1030 FORMAT(I11,15H. POSITION DATA)
1031 FORMAT(I11,15H. VELOCITY DATA)
40 MO(MT) = 1
42 CONTINUE
46 ZO(5) = ZO(5)*CONRD
ZO(6)=ZO(6)*CONRD
NSTX = NSTC + 10
ZO(5) = ATAN2(SIN(ZO(5)),RERP2*COS(ZO(5)))
CPH=COS(ZO(5))
SPH=SIN(ZO(5))
RO =REO/SQRT(1.+(RERP2-1.)*SPH**2)
R= ZO(4)+RO
ZO(4)=R-REO
DO 48 I=1,10
48 X(I)=ZO(I)
IF(NPC(3).EQ.0) GO TO 100
50 DO 51 I=7,9
51 ZO(I)=ZO(I)*CONRD
DO 52 I=1,2
ZO(I+1) = ZO(I+1)*CONRD
ST(I)=SIN(ZO(I+1))
52 CT(I)=COS(ZO(I+1))
DO 53 I=3,5
ST(I)=SIN(ZO(I+4)/2.)
53 CT(I)=COS(ZO(I+4)/2.)
X(3)=ZO(1)*CT(1)

```

```

SETP0880
SETP0890
SETP0900
SETP0910
SETP0920
SETP0930
SETP0940
SETP0950
SETP0960
SETP0970
SETP0980
SETP0990
SETP1000
SETP1010
SETP1020
SETP1030
SETP1040
SETP1050
SETP1060
SETP1070
SETP1080
SETP1090
SETP1100
SETP1110
SETP1120
SETP1130
SETP1140
SETP1150
SETP1160
SETP1170
SETP1180
SETP1190
SETP1200
SETP1210
SETP1220
SETP1230
SETP1240
SETP1250
SETP1260
SETP1270
SETP1280
SETP1290
SETP1300
SETP1310
SETP1320
SETP1330
SETP1340
SETP1350
SETP1360
SETP1370
SETP1380
SETP1390
SETP1400
SETP1410
SETP1420
SETP1430
SETP1440
SETP1450
SETP1460
SETP1470

```

	X(1)=X(3)*CT(2)	SETP1480
	X(2)=X(3)*ST(2)+R*OMEGA*CPH	SETP1490
	X(3)=-Z0(1)*ST(1)	SETP1500
	DO 54 I=1,10	SETP1510
	DO 54 J=1,9	SETP1520
54	DUB(I,J)=0.	SETP1530
	DUB(1,1)= CT(1)*CT(2)	SETP1540
	DUB(2,1)= CT(1)*ST(2)	SETP1550
	DUB(3,1)=-ST(1)	SETP1560
	SP(1)= Z0(1)*ST(1)	SETP1570
	DUB(1,2)=-SP(1)*CT(2)	SETP1580
	DUB(2,2)=-SP(1)*ST(2)	SETP1590
	SP(1)= Z0(1)*CT(1)	SETP1600
	DUB(3,2)=-SP(1)	SETP1610
	DUB(1,3)=-SP(1)*ST(2)	SETP1620
	DUB(2,3)= SP(1)*CT(2)	SETP1630
	DUB(2,4)= OMEGA*CPH	SETP1640
	DUB(2,5)=-R*OMEGA*SPH	SETP1650
	DUB(4,4)=1.	SETP1660
	DUB(5,5)=1.	SETP1670
	DUB(6,6)=1.	SETP1680
	IF(NPC(3)-1) 100,56,60	SETP1690
56	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP1700
	DUA(2,1)= CT(3)*CT(4)*ST(5)	SETP1710
	DUA(3,1)= CT(3)*ST(4)*CT(5)	SETP1720
	DUA(4,1)= ST(3)*CT(4)*CT(5)	SETP1730
	DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP1740
	DUA(2,2)= ST(3)*ST(4)*CT(5)	SETP1750
	DUA(3,2)= ST(3)*CT(4)*ST(5)	SETP1760
	DUA(4,2)= CT(3)*ST(4)*ST(5)	SETP1770
	X(7) = DUA(1,1)+DUA(1,2)	SETP1780
	X(8) = DUA(2,1)-DUA(2,2)	SETP1790
	X(9) = DUA(3,1)+DUA(3,2)	SETP1800
	X(10)= DUA(4,1)-DUA(4,2)	SETP1810
	IF(NPC(1).EQ.1) GO TO 100	SETP1820
	DUB(7,7) = -X(10)/2.	SETP1830
	DUB(8,7) = -X(9)/2.	SETP1840
	DUB(9,7) = X(8)/2.	SETP1850
	DUB(10,7) = X(7)/2.	SETP1860
	DUB(7,8) = -(DUA(3,1) - DUA(3,2))/2.	SETP1870
	DUB(8,8) = -(DUA(4,1) + DUA(4,2))/2.	SETP1880
	DUB(9,8) = (DUA(1,1) - DUA(1,2))/2.	SETP1890
	DUB(10,8) = -(DUA(2,1) + DUA(2,2))/2.	SETP1900
	DUB(7,9) = -X(8)/2.	SETP1910
	DUB(8,9) = X(7)/2.	SETP1920
	DUB(9,9) = X(10)/2.	SETP1930
	DUB(10,9) = -X(9)/2.	SETP1940
	GO TO 70	SETP1950
60	ST(1) = SIN(.5*Z0(2))	SETP1960
	CT(1) = COS(.5*Z0(2))	SETP1970
	ST(2) = SIN(.5*Z0(3))	SETP1980
	CT(2) = COS(.5*Z0(3))	SETP1990
	DUE(1)= CT(1)*CT(2)	SETP2000
	DUE(2)=-ST(1)*ST(2)	SETP2010
	DUE(3)= ST(1)*CT(2)	SETP2020
	DUE(4)= CT(1)*ST(2)	SETP2030
	DUA(1,1)= CT(3)*CT(4)*CT(5)	SETP2040
	DUA(2,1)= ST(3)*CT(4)*CT(5)	SETP2050
	DUA(3,1)= CT(3)*CT(4)*ST(5)	SETP2060
	DUA(4,1)= ST(3)*CT(4)*ST(5)	SETP2070

DUA(1,2)= ST(3)*ST(4)*ST(5)	SETP2080
DUA(2,2)= CT(3)*ST(4)*ST(5)	SETP2090
DUA(3,2)= ST(3)*ST(4)*CT(5)	SETP2100
DUA(4,2)= CT(3)*ST(4)*CT(5)	SETP2110
DUF(1)= DUA(1,1)-DUA(1,2)	SETP2120
DUF(2)= DUA(2,1)+DUA(2,2)	SETP2130
DUF(3)= DUA(3,1)+DUA(3,2)	SETP2140
DUF(4)= DUA(4,1)-DUA(4,2)	SETP2150
X(7) = DUE(1)*DUF(1)-DUE(2)*DUF(2)-DUE(3)*DUF(3)-DUE(4)*DUF(4)	SETP2160
X(8) = DUE(1)*DUF(2)+DUE(2)*DUF(1)+DUE(3)*DUF(4)-DUE(4)*DUF(3)	SETP2170
X(9) = DUE(1)*DUF(3)-DUE(2)*DUF(4)+DUE(3)*DUF(1)+DUE(4)*DUF(2)	SETP2180
X(10)= DUE(1)*DUF(4)+DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(1)	SETP2190
IF(NPC(1).EQ.1) GO TO 100	SETP2200
DUB(7,2) = -X(9)/2. - DUE(2)*DUF(4) + DUE(4)*DUF(2)	SETP2210
DUB(8,2) = X(10)/2.- DUE(2)*DUF(3) - DUE(4)*DUF(1)	SETP2220
DUB(9,2) = X(7)/2. + DUE(2)*DUF(2) + DUE(4)*DUF(4)	SETP2230
DUB(10,2)= -X(8)/2. + DUE(2)*DUF(1) - DUE(4)*DUF(3)	SETP2240
DUB(7,3) = -X(10)/2.	SETP2250
DUB(8,3) = -X(9)/2.	SETP2260
DUB(9,3) = X(8)/2.	SETP2270
DUB(10,3)= X(7)/2.	SETP2280
DUB(7,7) = -X(8)/2. + DUE(3)*DUF(4) - DUE(4)*DUF(3)	SETP2290
DUB(8,7) = X(7)/2. + DUE(3)*DUF(3) + DUE(4)*DUF(4)	SETP2300
DUB(9,7) = -X(10)/2.- DUE(3)*DUF(2) + DUE(4)*DUF(1)	SETP2310
DUB(10,7)= X(9)/2. - DUE(3)*DUF(1) - DUE(4)*DUF(2)	SETP2320
DUF(1) = DUA(1,1)+DUA(1,2)	SETP2330
DUF(2) = DUA(2,1)-DUA(2,2)	SETP2340
DUF(3) = DUA(3,1)-DUA(3,2)	SETP2350
DUF(4) = DUA(4,1)+DUA(4,2)	SETP2360
DUB(7,8) = (-DUE(1)*DUF(4)-DUE(2)*DUF(3)-DUE(3)*DUF(2)+DUE(4)*DUF(1))/2.	SETP2370
DUB(8,8) = (DUE(1)*DUF(3)-DUE(2)*DUF(4)-DUE(3)*DUF(1)-DUE(4)*DUF(2))/2.	SETP2380
DUB(9,8) = (DUE(1)*DUF(2)+DUE(2)*DUF(1)-DUE(3)*DUF(4)+DUE(4)*DUF(3))/2.	SETP2390
DUB(10,8)= (-DUE(1)*DUF(1)+DUE(2)*DUF(2)-DUE(3)*DUF(3)-DUE(4)*DUF(4))/2.	SETP2400
DUB(7,9) = -X(9)/2.	SETP2410
DUB(8,9) = -X(10)/2.	SETP2420
DUB(9,9) = X(7)/2.	SETP2430
DUB(10,9)= X(8)/2.	SETP2440
70 DO 74 I=1,10	SETP2450
DO 74 J=1,NSTX	SETP2460
SUM = 0.	SETP2470
DO 72 K=1,9	SETP2480
72 SUM = SUM + DUB(I,K)*P(K,J)	SETP2490
74 PH(I,J) = SUM	SETP2500
DO 80 I=1,10	SETP2510
DO 78 J=1,10	SETP2520
SUM = 0.	SETP2530
DO 76 K=1,10	SETP2540
76 SUM = SUM + PH(I,K)*DUB(J,K)	SETP2550
78 P(I,J) = SUM	SETP2560
DO 80 J=1,NSTX	SETP2570
80 P(I,J) = PH(I,J)	SETP2580
IF(NPU.EQ.0) GO TO 88	SETP2590
DO 84 I=1,10	SETP2600
DO 84 J=1,NPU	SETP2610
SUM = 0.	SETP2620
DO 82 K=1,9	SETP2630
	SETP2640
	SETP2650
	SETP2660
	SETP2670

82 SUM = SUM + DUB(I,K)*CUZ(K,J)	SETP2680
84 PH(I,J) = SUM	SETP2690
DO 86 I=1,10	SETP2700
DO 86 J=1,NPU	SETP2710
86 CUZ(I,J) = PH(I,J)	SETP2720
88 IF(NPV.EQ.0) GO TO 100	SETP2730
DO 92 I=1,10	SETP2740
DO 92 J=1,NPV	SETP2750
SUM = 0.	SETP2760
DO 90 K=1,9	SETP2770
90 SUM = SUM + DUB(I,K)*CVZ(K,J)	SETP2780
92 PH(I,J) = SUM	SETP2790
DO 94 I=1,10	SETP2800
DO 94 J=1,NPV	SETP2810
94 CVZ(I,J) = PH(I,J)	SETP2820
100 WRITE(OUT,3021)	SETP2830
WRITE(OUT,1021) (I,I,X(I),P(I,I),I=1,10)	SETP2840
3021 FORMAT(//,24H STATE VECTOR COMPONENTS/43H COMP. ID.NO. EST.	SETP2850
*VALUE VARIANCE)	SETP2860
1021 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP2870
IF(NSTC) 102,104,102	SETP2880
102 WRITE(OUT,1022)	SETP2890
1022 FORMAT(42H MODEL PARAMETERS IN EXPANDED STATE VECTOR)	SETP2900
DO 103 I=1,NSTC	SETP2910
LT=NC(I)	SETP2920
MT=I+10	SETP2930
103 WRITE(OUT,1023) MT,LT,C(LT),P(MT,MT)	SETP2940
1023 FORMAT(1X,I4,4X,I4,5X,2E15.8)	SETP2950
104 IF(NPU) 106,108,106	SETP2960
106 WRITE(OUT,1024)	SETP2970
1024 FORMAT(55H RANDOM MODEL PARAMETERS NOT BEING ESTIMATED (U-VECTOR))	SETP2980
DO 107 I=1,NPU	SETP2990
LT=MC(I)	SETP3000
107 WRITE(OUT,1023) I,LT,C(LT),D(I)	SETP3010
108 IF(NPV) 110,112,110	SETP3020
110 WRITE(OUT,1025)	SETP3030
1025 FORMAT(61H RANDOM MEASUREMENT PARAMETERS NOT BEING ESTIMATED (V-VE	SETP3040
XCTOR))	SETP3050
DO 111 I=1,NPV	SETP3060
LT=MCC(I)	SETP3070
111 WRITE(OUT,1023) I,LT,C(LT),S(I)	SETP3080
112 LT=9	SETP3090
IF(NPC(3).EQ.0) LT=10	SETP3100
IF(NST-LT) 114,120,114	SETP3110
114 WRITE(OUT,1026)	SETP3120
1026 FORMAT(48H IMPROPER NUMBER OF STATE VARIABLES ARE INPUTTED)	SETP3130
CALL EXIT	SETP3140
120 IF(NPC(1)-1) 124,122,124	SETP3150
122 NALL=10	SETP3160
GO TO 128	SETP3170
124 NALL = 10*(NSTX+NPU+1)	SETP3180
K = NSTX + NPU	SETP3190
DO 126 I =1,10	SETP3200
DO 125 J=1,K	SETP3210
125 PH(I,J) = 0.	SETP3220
126 PH(I,I) = 1.	SETP3230
128 IF(NPC(1)-2) 144,130,144	SETP4450
130 IF(NSTA-1) 144,144,132	SETP4460
132 DO 142 I=2,NSTA	SETP4470
MT=NS(I-1)	SETP4480

TT=DTF(MT)	SETP4490
LT=I-1	SETP4500
DO 136 J=1,NSTA	SETP4510
K=NS(J)	SETP4520
IF(TT-DTF(K)) 135,135,136	SETP4530
135 TT=DTF(K)	SETP4540
LT=J	SETP4550
136 CONTINUE	SETP4560
137 IP=NS(I-1)	SETP4570
138 NS(I-1)=NS(LT)	SETP4580
139 NS(LT)=IP	SETP4590
142 CONTINUE	SETP4600
144 KDATA=-1	SETP3550
WRITE(SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SETP3560
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SETP3570
ET = TO	SETP3580
TZERO = TO	SETP3590
T = TO	SETP3600
TIMES=TZERO-10.	SETP3610
KDAP = 1	SETP3620
KPROP=-1	SETP3630
KDATAS=-1	SETP3640
C(151)= C(151)*CONRD	SETP3650
C(152)= C(152)*CONRD	SETP3660
RETURN	SETP3670
END	SETP3680

```

SUBROUTINE SMOOTH
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3),KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RC ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40),DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT,J ,JNBR,JNBRS,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KQB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30),NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA,NSTC,NSTX,NT,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
CALL IDENT
FLOS = 0.
TIME = TZERO - 10.
NALLSV=NALL
MOPTSV=NPC(1)
DCOMP=-DCOMP
IF(NPC(1)-1) 4,6,2
2 IF(NPC(8)-4) 12,6,12
4 IF(NPC(7).GT.ICOUNT) IF(NPC(8)-4) 16,6,16
IF(NPC(8).LE.1) GO TO 8
IF(NPC(8).LE.3) GO TO 14
6 TZERO = TO
NPC(7) = ICOUNT
GO TO 62
8 NPC(1) = 1
NALL=10
9 IF(NPC(8).EQ.0) GO TO 12
IF(NPC(8).EQ.2) GO TO 12
10 KSM = 1
GO TO 18
12 KSM = 0
GO TO 18
14 IF(NPC(8)-2) 12,12,10
16 NPC(1) = 1
NALL=10
GO TO 9
18 T2 = TO

```

WRITE(OUT,1004)	SMTH0280
20 CALL INTAG	SMTH0290
TO=T2	SMTH0300
IF(ET.LE.TIME) GO TO 150	SMTH0310
IF(NPC(1).NE.1) CALL PROP	SMTH0320
24 CALL OUTPUT	SMTH0330
L1=1	SMTH0340
28 IF(T2-TZERO) 60,60,30	SMTH0350
30 ET=ET-DET	SMTH0360
IF(KSM.LE.0) GO TO 38	SMTH0370
36 TIME = TYM(KG)	SMTH0380
37 IF(TIME.LE.ET) GO TO 38	SMTH0390
T2 = TIME	SMTH0400
GO TO 20	SMTH0410
38 T2 = ET	SMTH0420
GO TO 20	SMTH0430
60 NALL=NALLSV	SMTH0440
NPC(1)=MOPTSV	SMTH0450
DCOMP=-DCOMP	SMTH0460
IF(ICOUNT-NPC(7)) 64,62,62	SMTH0470
62 ET=TFINAL	SMTH0480
NPC(1)=1	SMTH0490
L1=0	SMTH0500
GO TO 99	SMTH0510
64 ICOUNT=ICOUNT+1	SMTH0520
DO 66 I=1,6	SMTH0530
66 NTR(I) = 0	SMTH0540
REWIND FIT	SMTH0550
REWIND PGR	SMTH0560
KDATAS=-1	SMTH0570
KDATA=-1	SMTH0580
KPROP=-1	SMTH0590
NCOUNT=0	SMTH0600
L1=1	SMTH0610
BACKSPACE SCRACH	SMTH0620
BACKSPACE SCRACH	SMTH0630
READ (SCRACH) NSTX,NPU,NPV,((P(I,J),I=1,NSTX),J=1,NSTX),	SMTH0640
1 ((CUZ(I,J),I=1,NSTX),J=1,NPU),((CVZ(I,J),I=1,NSTX),J=1,NPV)	SMTH0650
CALL IDENT	SMTH0660
99 RETURN	SMTH0670
150 MTYP=MTP(KG)	SMTH0680
IF(KG.EQ.0) GO TO 158	SMTH0690
CALL OBSERV	SMTH0700
DO 156 I=1,3	SMTH0710
IF(MR(I,MTYP)) 152,154,152	SMTH0720
152 RES(I)=OFM(1)-DAT(I,KG)	SMTH0730
IF(MTYP.GT.5) GO TO 153	SMTH0740
IF(I.EQ.1) GO TO 153	SMTH0750
IF(ABS(RES(I)).LT.3.1416) GO TO 153	SMTH0760
RES(I)=RES(I)-SIGN(6.283185307179586,RES(I))	SMTH0770
153 CONTINUE	SMTH0780
RES(I+3)= RES(I)/SP(I)	SMTH0790
FLOS= FLOS + RES(I+3)**2	SMTH0800
KD(I)=NCOUNT	SMTH0810
NCOUNT=NCOUNT-1	SMTH0820
GO TO 156	SMTH0830
154 RES(1)=0.	SMTH0840
RES(I+3)=0.	SMTH0850
KD(I) = 0	SMTH0860
156 CONTINUE	SMTH0870

IF(L1.NE.0) WRITE(OUT,1000)	SMTH0880
L1=0	SMTH0890
WRITE(OUT,1002) (KD(I),I=1,3),MTYP,TO,(RES(I),I=1,6),FLOS	SMTH0900
KG=KG-1	SMTH0910
IF(KG.GT.0) GO TO 36	SMTH0920
158 TIME=TZERO-10.	SMTH0930
GO TO 37	SMTH0940
1000 FORMAT(//5X6HPOINTS4X,4HTYPE,3X,4HTIME,6X,4HRES1,9X,4HRES2,9X,4HRES	SMTH0950
XS3,9X,8HWGT.RES1,5X,8HWGT.RES2,5X,8HWGT.RES3,5X,9HLOSS FCTN)	SMTH0960
1002 FORMAT(1X,I4,1H,I4,1H,I4,1X,I2,1X,F10.3,7(1X,E12.5))	SMTH0970
1004 FORMAT(///20(1H*),25HBEGIN BACKWARDS SMOOTHING,75(1H*))	SMTH0980
END	SMTH0990

```

SUBROUTINE STAT
COMMON /INTGRL/ DCOMP,T,T2,X(10),PH(10,40),DX(10),DPH(10,40),
* NALL,LRK
COMMON /TWICE/ A(3,3) ,CPH ,CT(5) ,SP(10) ,ST(5)
1 ,TPH ,VO(20) ,ZO(20) ,AG(3) ,AMDOT(3) ,APDOT(4)
2 ,B(8) ,CGM(3) ,DFM(3) ,DTRAN(3,3),DUD(10,1),DUE(4)
3 ,DUF(4) ,F1(3,40) ,F2(3,5) ,F3(4,40) ,GG(3) ,HI(2)
4 ,IDN ,II ,IP ,IPC ,JJ ,JN ,KA ,KD(3) ,KDUM ,KG2
5 ,K1 ,NNN ,NPTS ,PAR(6) ,PDOT(3) ,PMDOT(3) ,RES(6)
6 ,RO ,SPD(5) ,SPH ,TRAN(3,3),XX(50)
DIMENSION DUB(30,15)
EQUIVALENCE (AG(1),DUB(1,1))
COMMON /METH2/ AB(3) ,AM(3) ,AP(4) ,AX(40) ,AY(40)
1 ,AZ(40) ,C(160) ,CCAPH(5) ,CONRD ,CPHDT(5) ,CUZ(30,5)
2 ,CVZ(30,5),D(5) ,DAT(3,40) ,DATA(3) ,DATAS(3) ,DATC(3)
3 ,DET ,DFIT(9) ,DTF(9) ,DTI(9) ,DZ(30) ,ET
4 ,FLOS ,G(3,30) ,H(3,5) ,I ,ICOUNT ,J ,JNBR ,JNBRS ,JST
5 ,K ,KAR ,KC(3) ,KDAP ,KDATA ,KDATAS ,KG,KI,KK
6 ,KN ,KOB ,KPROP,KS,KSM,KSS,L ,LC(3) ,LCS(3) ,LS ,LT
7 ,L1 ,M ,MC(5) ,MCC(5) ,MO(5) ,MR(3,9) ,MT
8 ,MTP(40) ,MTYP ,MTYPS ,N ,NC(30) ,NCOUNT ,NPC(15)
9 ,NPU ,NPV ,NS(9) ,NSS(5) ,NST ,NSTA ,NSTC ,NSTX ,NT ,NTR(9)
A ,N8(3) ,N9(3) ,N10(3) ,N11(3) ,OMEGA ,P(30,30)
B ,PA(3) ,PM(3) ,R ,REO ,RERP2
C ,RPO ,ROT(5) ,S(5) ,SCAPH(5) ,SI(3) ,SIG(3,40)
D ,SIGM(3) ,SIGMS(3) ,SPHDT(5) ,SUM ,SUM2 ,SYG(3,9) ,TFINAL
E ,TFIT(9) ,TIME ,TIMES ,TO ,TP(40) ,TQ(40)
F ,TR(40) ,TT(40) ,TXCG(20) ,TYCG(20) ,TYM(40) ,TZCG(20)
G ,TZERO ,XJ2 ,XMU ,XMUJ ,XP(3) ,XXCG(20)
H ,XYCG(20) ,XZCG(20)
INTEGER OUT,FIT,STATE,SCRACH,PQR
COMMON /TAPENO/ IN,OUT,FIT,STATE,SCRACH,PQR
EQUIVALENCE (SP(3),PHIDT),(SP(4),CAPHI)
IF(MTYP.GT.5) RETURN
N = 60 + 15*MTYP
SP(1) = COS(C(N+13))
SP(2) = SIN(C(N+13))
C-----CALCULATE EQ.(237) -----
PHIDT = ATAN2(RERP2*SP(2),SP(1))
CAPHI= PHIDT - C(N+13)
SPHDT(MTYP)=SIN(PHIDT)
CPHDT(MTYP)=COS(PHIDT)
CCAPH(MTYP)= COS(CAPHI)
SCAPH(MTYP)= SIN(CAPHI)
ROT(MTYP) = REO/SQRT(1.+(RERP2-1.)*SP(2)**2)
99 RETURN
END

```

FUNCTION TAB(TARG,N,T,Y)	TAB 0000
DIMENSION N(1),T(1),Y(1)	TABT0010
IF(N(1))111,14,111	TABT0020
111 CONTINUE	TABT0030
I = N(2)	TABT0040
6 IF(TARG - T(I))3,2,1	TABT0050
1 IF(N(3))9,5,9	TABT0060
5 I = I + 1	TABT0070
IF(I-N(1)) 6,4,4	TABT0080
4 I = I - 1	TABT0090
8 TAB = (Y(I+1)*(TARG - T(I)) - Y(I)*(TARG - T(I+1)))/(T(I+1)-T(I))	TABT0100
7 N(2) = I	TABT0110
99 RETURN	TABT0120
11 I = I - 1	TABT0130
2 TAB = Y(I)	TABT0140
GO TO 7	TABT0150
9 IF(TARG - T(I-1)) 4,11,12	TABT0160
3 IF(N(3))5,10,5	TABT0170
10 IF(TARG - T(I-1))12,11,4	TABT0180
12 I = I - 1	TABT0190
IF(I-1)18,8,6	TABT0200
18 I=1	TABT0210
GO TO 8	TABT0220
14 TAB = 0.	TABT0230
RETURN	TABT0240
END	TABT0250

Martin Marietta Corporation
 Denver, Colorado, June 6, 1969

APPENDIX

DATA CONDITIONING

During postflight analyses studies the measurement data must be conditioned before being used in STEP. The airborne measurements received from the telemetry signal must be decoded, digitized, calibrated, time corrected, edited, smoothed, and formatted for use on the PQR tape. The data are not smoothed if they are to be used on the FIT tape. The radar tracking data must be edited, and formatted for use on the FIT tape. Methods that were used on the PRIME program postflight analyses are presented for accomplishing these data conditioning tasks. These methods are certainly not unique, but nevertheless do suggest one way of performing the data conditioning.

Consider a single channel of telemetry data that has been decoded, calibrated, and digitized. For each data point, their corresponds a time. This time must be consistent with the range time that is recorded with the tracking data. If the telemetry time is obtained from an airborne clock, then time corrections on the telemetry data may be necessary. These time corrections can be obtained by comparing range time and telemetry time at points where discrete events occur. This comparison will yield corrections that can be made to the telemetry time bringing it into agreement with range time. The measurement data may appear as shown in figure A1.

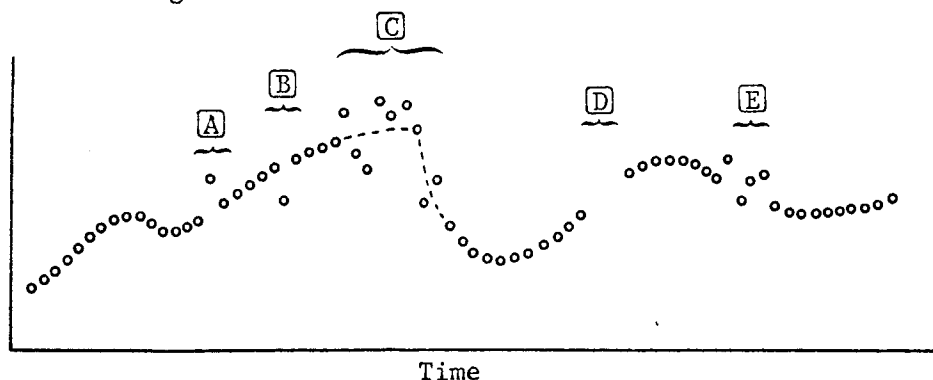


Figure A1.- Measurement Time History

Several types of anomalies are presented in figure A1. At A and B single wild points can be seen; at C is a series of approximately nine erroneous data points; at D is missing data, and at E another series of erroneous data points. The first problem encountered in the data conditioning task is that

APPENDIX

of determining where such anomalies occur. One must then decide if and how the data should be replaced. Finally, the data are smoothed if they are to be used on the PQR tape.

A. Determination of Anomalies

Erratic data can be manually identified by plotting the data. This, however, is very time consuming. Another way is to form a difference table for the data as tabulated below

<u>t</u>	<u>X</u>	<u>ΔX</u>	<u>$\Delta^2 X$</u>	<u>$\Delta^3 X$</u>
0	0.563			
		0.302		
0.1	0.865		0.008	
		0.310		-0.002
0.2	1.175		0.006	
		0.316		0.001
0.3	1.491		0.007	
		0.323		0.001
0.4	1.814		0.008	
		0.331		-0.001
0.5	2.145		0.007	
		0.338		-0.001
0.6	2.483		0.006	
		0.344		-0.006
0.7	2.827		0	
		0.344		0.005
0.8	3.171		0.005	
		0.349		
0.9	3.520			
.				
.				
.				

where
$$\Delta^n X_i = \Delta^{n-1} X_{i+1} - \Delta^{n-1} X_i$$

For well-behaved data the higher differences remain small. Should a wild point occur it can immediately be identified by a rapid change in the higher differences. For example, if at $t = 0.5$ let $X = 4.145$ instead of 2.145. The errors in the differences fan to the right as follows:

APPENDIX

t	X	ΔX	$\Delta^2 X$	$\Delta^3 X$
0	0.563			
0.1	0.865	0.302		
0.2	1.175	0.310	-0.008	-0.002
0.3	1.491	0.316	0.006	0.001
0.4	1.814	0.323	0.007	2.000
0.5	4.145	2.331	2.008	-6.001
0.6	2.483	-1.662	-3.993	5.999
0.7	2.827	.344	2.006	-2.006
0.8	3.171	.344	0	.005
0.9	3.520	.349	.005	

Such errors can be detected by testing the second or higher differences. When an erratic change occurs, a wild point or abrupt change in the data is detected. Where abrupt changes are known to occur (e.g., engine ignition or shutdown) the difference test should be neglected.

The difference test is implemented in the data conditioning task as follows. The n data channels are stored in chronological order on magnetic tape where each record contains N data points formatted as follows

N	T(1)	X(1,1)	X(1,2)	X(1,3)	. . .	X(1,m)
	T(2)	X(2,1)	X(2,2)	X(2,3)	. . .	X(2,m)
	.					
	.					
	.					
	T(N)	X(N,1)	X(N,2)	X(N,3)	. . .	X(N,m)

where m is the number of data channels (or separate measurements), and N is the number of time points per record. The data are then processed through a computer program that tests the second difference. When a difference exceeds a given value

APPENDIX

the erroneous point is flagged on a tab printout as well as on a magnetic tape on which the data are recorded using the following format:

```

N  T(1)   I(1,1), I(1,2) . . . I(1,m)   X(1,1) X(1,2) . . . X(1,m)
    T(2)   I(2,1), I(2,2) . . . I(2,m)   X(2,1) X(2,2) . . . X(2,m)
    .
    .
    T(N)   I(N,1)  I(N,2) . . . I(N,m)   X(N,1) X(N,2) . . . X(N,m)
  
```

The m fixed point flags for each line of data $I(.,1)$ $I(.,2)$. . . $I(.,m)$ are normally zero. If a wild point is detected in channel k its flag $I(.,k)$ is set to one. Inspection of these flags on the tab printout allows immediate identification of the time and data channel for which an erratic point has been detected.

If unequally spaced time intervals occur in the data, divided differences can be used instead of the ordinary differences shown above. Should data gaps occur as in D of figure A1, the data should be replaced if they are to be used in the PQR tape. For data to be used in the FIT tape, the gap need not be replaced. Therefore, as the data are being tested for wild points, the time is simultaneously tested for gaps. When a gap is detected, the line of data is written on the tab printout and output tape. Because the missing data are unknown, zeros are written for the X s and the flags $I(i,j)$ set to one. The time is obtained by linear interpolation using points adjacent to the gap.

The output tape, called output tape 1, and tab printout, which are ultimately produced by this first stage of processing contains the times, flags and data. Where the data are correct, the flag is zero. Where data have been detected to be erroneous or missing, the flag is 1.

B. Data Replacement

Data to be used on the FIT tape requires no further processing. Final formatting will use only those points having zero flags on output tape 1 above. For data to be used on the PQR tape, replacement of wild points and gaps is performed next. The output tape 1, resulting from the processing in Subsection A

APPENDIX

above, is read into a program, which replaces all data with flags equal to one (wild points and gaps). The point replacement is accomplished by fitting a cubic polynomial to four "good" point bounding the gap or wild point. The points are then replaced by interpolating the cubic polynomial for the erroneous or missing data. The fitting points for the interpolating polynomial are spread as shown in figure A2 so that noise in the fitting data will not be exaggerated.

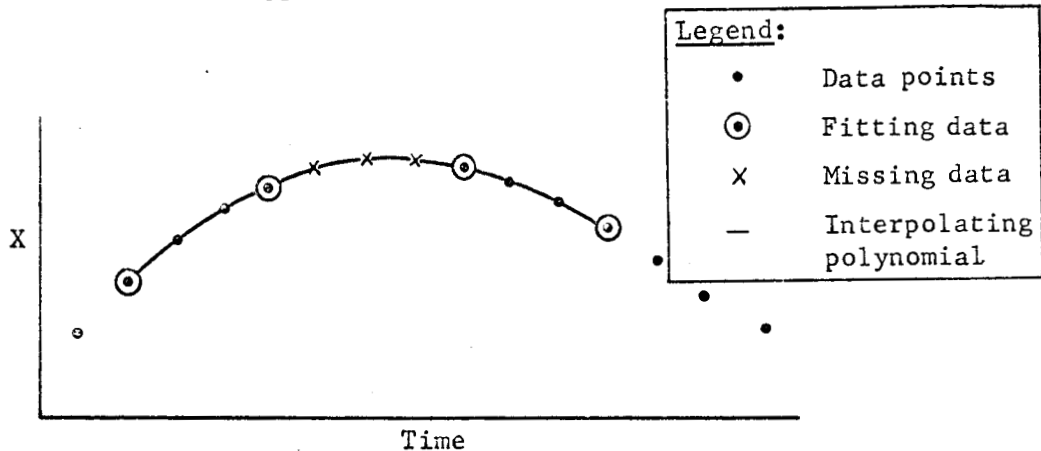


Figure A2.- Replacement by Interpolation

The points to which the polynomial are fit are circled in figure A2. If k points are to be interpolated in the gap, then the first and $k + 1$ st points on each side of the gap are used to fit the cubic polynomial. As the gaps and wild points are replaced by interpolation their flags are set to 2.

Occasionally, cubic polynomials cannot be used to replace wild points or gaps. In set C of figure A1, it can be seen that a cubic polynomial would undoubtedly replace the data improperly. However, an individual knowing what physically occurred during this time might be better able to fair a reasonable curve through the region. Therefore, a second way of replacing data is by card input. The user specifies the time, channel, and value for the data, and the program inserts it on output tape 2 flagged with a 3 to denote that it was provided by the user.

C. Smoothing

The data on output tape 2 resulting from the data replacement task above, is next inputted into a program that smoothes it. If

APPENDIX

time derivatives of the data are required (as is the case with strapped-down accelerometers and gyros), smoothing and differentiating occurs. Smoothing and differentiating formulas used on the PRIME program are classified as linear finite memory smoothing, and smoothing and differentiating formulas (see ref. 3). The smoothing formula assumes the form

$$C_n = \sum_{k=0}^{n-1} a_k r_{n-k} \quad (A1)$$

where C_n is the value of a smoothed parabola fit to n data points r_1, r_2, \dots, r_n and evaluated at the end point n . The a_k are the coefficients of the linear filter and are calculated as follows;

$$a_k = \mu_1 + \mu_2 k + \mu_3 k^2 \quad (A2)$$

with

$$\mu_1 = \frac{18(2n-1)\alpha + 30\alpha^2 + 3(3n^2 - 3n + 2)}{n(n+1)(n+2)} \quad (A3)$$

$$\mu_2 = -\frac{12(2n-1)(8n-11)\alpha}{n(n-1)(n+1)(n^2-4)} - \frac{180\alpha^2}{n(n+1)(n^2-4)} \quad (A4)$$

$$\begin{aligned} \mu_3 = & \frac{180\alpha}{n(n+1)(n^2-4)} + \frac{180\alpha^2}{n(n^2-1)(n^2-4)} \\ & + \frac{30}{n(n+1)(n+2)} \end{aligned} \quad (A5)$$

where α is the amount of lag or lead (i.e. $C_n = R_{n+\alpha}$). For an end point filter $\alpha = 0$, for a midpoint filter $\alpha = -\frac{n-1}{2}$ with n odd.

For smoothing and differentiating, C_n in equation (A1) is the first derivative of a smoothed parabola fit to the n data points r_1, r_2, \dots, r_n and evaluated at point n with lag or lead α . The coefficients are calculated from equation (A2) with

APPENDIX

$$\mu_1 = \frac{6(6n - 3 + 10\alpha)}{nT(n + 1)(n + 2)} \quad (A6)$$

$$\mu_2 = \frac{12[(8n - 11)(2n - 1) + 30(n - 1)\alpha]}{nT(n^2 - 1)(n^2 - 4)} \quad (A7)$$

$$\mu_3 = \frac{180(n - 1 + 2\alpha)}{nT(n^2 - 1)(n^2 - 4)} \quad (A8)$$

where T is the fixed time interval between adjacent data points.

Equation (A1) is an end point filter since to find C_n the n data points before and including r_n are used. By a simple transformation the end point filter can be converted to any other type filter by merely shifting the points being used to the right of C_n by means of α .

An obvious difficulty arises when attempting to apply the filter near the beginning, or end of a table or across a discrete such as thrust ignition or termination. At the beginning a table the filter is commenced as an end point filter and "grown" to a midpoint (or whatever is desired) filter as the filter is walked through the data. At the end of a table, a midpoint filter is grown into an end point filter. At discontinuities, the filter is changed from midpoint to endpoint at the discontinuity. Then it is restarted as an end point filter on the other side of the discontinuity and grown back to a midpoint filter. On the PRIME program, the filter span (number of points N) was decreased as the data nonlinearity increased. When the vehicle was out of atmosphere and the data very smooth an eleven point filter was used. This was reduced to a five-point filter during in-atmosphere maneuvers.

REFERENCES

1. Wagner, W. E.: Reentry Filtering, Prediction, and Smoothing. J. Spacecraft Rockets, vol. 3, no. 9, Sept. 1966, pp. 1321-1327.
2. Clark, S. P., ed.: Handbook of Physical Constants. Geological Society of America, Inc., 1966.
3. Monroe, A. J.: Digital Processes for Sampled Data Systems. John Wiley and Sons, New York, 1962.